

Math 451 Midterm Exam

Due Friday, March 28, 2008

Please provide enough details of your work so that I can follow your reasoning. Without details, I cannot assign partial credit.

1. (20 points) Page 204 of Logan text, Problem 6.
2. (10 points) Assume that $k(x, t), d(x, t)$ are given functions that are sufficiently smooth. Show that the operator

$$\mathcal{L}u = u_t - (k(x, t)u_x)_x + d(x, t)u$$

is a linear operator.

3. (10 points) Determine whether the following PDE is linear or nonlinear.

$$u_{tx} + u^2 = \sin x,$$

4. (a) (10 points) Determine regions of the xt -plane where the following equation is **hyperbolic, parabolic** or **elliptic**.

$$tu_{tt} + u_{xx} = 0,$$

- (b) (10 points) Determine regions of the xt -plane where the following equation is **hyperbolic, parabolic** or **elliptic**.

$$u_{tt} + (1 + x^2)u_x - u_t = e^{tx},$$

5. (10 points) Page 175 of Logan text, Problem 2b.
6. (10 points) Page 184 of Logan text, Problem 1d.
7. (20 points) Page 346 of Logan text, Problem 5. Hint: This problem is stating that any function u that is only a function of the radius-variable explicitly must satisfy that equation. That is, any function of only r (so that the θ variable doesn't appear explicitly in the function expression for u) is a solution of the PDE.

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Midterm Exam - #1

Page 204, Problem #6

① Minimize

$$J(y) = \int_a^b p(x)[y'(x)]^2 + q(x)[y(x)]^2 dx$$

s.t.

$$W(y) = \int_a^b r(x)[y(x)]^2 dx = 1$$

where p, q, r are given functions and $y(a) = y(b) = 0$.

Soln: Define $H = \{(h_1, h_2) : h_i \in C[a, b] \text{ and } h_i(a) = h_i(b) = 0, i=1, 2\}$
 Let $\epsilon_1, \epsilon_2 \in \mathbb{R}$, and define

$$J(\epsilon_1, \epsilon_2) = J(y + \epsilon_1 h_1 + \epsilon_2 h_2)$$

$$W(\epsilon_1, \epsilon_2) = W(y + \epsilon_1 h_1 + \epsilon_2 h_2)$$

Let y be a local minimum for J st. $W(y) = 1$
 Then $(0, 0)$ is a local min for $J: \mathbb{R}^2 \rightarrow \mathbb{R}$.
 Therefore, by LMR, we must have

$$\frac{\partial J}{\partial \epsilon_1}(0, 0) + \lambda \frac{\partial W}{\partial \epsilon_1}(0, 0) = 0 \quad (1)$$

$$\frac{\partial J}{\partial \epsilon_2}(0, 0) + \lambda \frac{\partial W}{\partial \epsilon_2}(0, 0) = 0 \quad (2)$$

$$W(0, 0) = 1 \quad (3)$$

$$\begin{aligned} \frac{\partial J(0,0)}{\partial \epsilon_1} &= \left. \frac{\partial J(\epsilon_1, \epsilon_2)}{\partial \epsilon_1} \right|_{(0,0)} = \delta J(y, h_1) \\ &= \int_a^b \frac{d}{d\epsilon_1} \left[p(x) [y + \epsilon_1 h_1(x)]^2 + q(x) [y + \epsilon_1 h_1(x)]^2 \right] dx \Big|_{\epsilon_1=0} \\ &= \int_a^b 2p(x) [y'(x)] h_1'(x) + 2q(x) [y(x)] h_1(x) dx \end{aligned}$$

Similarly,

$$\frac{\partial J(0,0)}{\partial \epsilon_2} = \delta J(y, h_2) = 2 \int_a^b p(x) y'(x) h_2'(x) + q(x) y(x) h_2(x) dx$$

Finally,

$$\frac{\partial W(0,0)}{\partial \epsilon_1} = \delta W(y, h_1) = 2 \int_a^b r(x) y(x) h_1(x) dx$$

and

$$\frac{\partial W(0,0)}{\partial \epsilon_2} = \delta W(y, h_2) = 2 \int_a^b r(x) y(x) h_2(x) dx.$$

Then applying (1) $\hat{\epsilon}_1$, (2), we have

$$(1a) \quad \int_a^b p(x) y' h_1' + q(x) y h_1 + \lambda r(x) y h_1 dx = 0 \quad \forall (h_1, 0) \in H$$

$$(2a) \quad \int_a^b p(x) y' h_2' + q(x) y h_2 + \lambda r(x) y h_2 dx = 0 \quad \forall (0, h_2) \in H.$$

Apply I.B.P to (1a) $\hat{\epsilon}_1$, use B.C.s satisfied by $h_1(x)$
yields

3

$$\int_a^b [(p(x)y')' + (q(x) + \lambda r(x))y] h_1(x) dx = 0 \quad \forall h_1 \in C^1[a,b]$$

$h_1(a) = h_1(b) = 0$

By F.L.C.V. this yields the SLP.

$$-(p(x)y')' + q(x)y + \lambda r(x)y = 0$$

or

$$-(p(x)y')' + q(x)y = -\lambda r(x)y$$

$y(a) = y(b) = 0.$

Note: (2a) yields the same eqn, and the local minimizer must also satisfy

$$\int_a^b r(x)[y(x)]^2 dx = 1$$

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Midterm Exam - #2

(2) $Lu = u_t - (k(x,t)u_x)_x + d(x,t)u$
is a Linear Operator

Let u, w be functions, and let c be any constant.

$$\begin{aligned}
 (i) \quad L(u+w) &= (u+w)_t - (k(x,t)(u+w)_x)_x + d(x,t)(u+w) \\
 &= u_t + w_t - [k(x,t)[u_x + w_x]]_x + d(x,t)u + d(x,t)w \\
 &= u_t + w_t - [k(x,t)u_x + k(x,t)w_x]_x + d(x,t)u + d(x,t)w \\
 &= u_t + w_t - (k(x,t)u_x)_x - (k(x,t)w_x)_x + d(x,t)u + d(x,t)w \\
 &= [u_t - (k(x,t)u_x)_x + d(x,t)u] + [w_t - (k(x,t)w_x)_x + d(x,t)w] \\
 &= L(u) + L(w)
 \end{aligned}$$

$$\begin{aligned}
 (ii) \quad L(cu) &= (cu)_t - (k(x,t)(cu)_x)_x + d(x,t)(cu) \\
 &= cu_t - (c \cdot k(x,t)u_x)_x + cd(x,t)u \\
 &= cu_t - c \cdot (k(x,t)u_x)_x + cd(x,t)u \\
 &= c [u_t - (k(x,t)u_x)_x + d(x,t)u] = cL(u)
 \end{aligned}$$

So, L is a Linear Operator.

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Midterm Exam - #3

- (3) Determine whether the PDE is Linear or Nonlinear.

$$u_{tx} + u^2 = \sin(x)$$

Let $L(u) = u_{tx} + u^2$, and NOTE that L is a Nonlinear Operator. That is, if c is a constant and u is a function, then

$$L(cu) = (cu)_{tx} + (cu)^2$$

$$= cu_{tx} + c^2 u^2$$

$$= c[u_{tx} + cu^2] \neq cL(u) \text{ for all } c \neq 1.$$

Since L is a Nonlinear Operator, then the PDE is Nonlinear.

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Midterm Exam - #4

- (4) Determine regions in the x - t -plane where the following eqns are Hyperbolic, Parabolic or Elliptic.

(a) $t u_{tt} + u_{xx} = 0$

$$a(x,t) = t, \quad b(x,t) = 0, \quad c(x,t) = 1$$

$$b^2 - 4ac = 0 - 4(t) = -4t$$

Egn is: Hyperbolic for $t < 0$ and for all x
 Parabolic for $t = 0$ " "
 Elliptic for $t > 0$ " "

(b) $u_{tt} + (1+x^2)u_x - u_t = e^{tx}$

$$a(x,t) = 1, \quad b(x,t) = 0, \quad c(x,t) = 0$$

$$b^2 - 4ac = 0 \quad \text{for all } x, t$$

Egn is Parabolic for all x, t .

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Midterm Exam - #5

⑤ Find extremals of the functional

$$J(y) = \int_a^b y^2 + (y')^2 + 2ye^x dx$$

- We can use the ELDE here

$$L_y = 2y + 2e^x, \quad L_{y'} = 2y'$$

$$2y + 2e^x - \frac{d}{dx}[2y'] = 0$$

$$y + e^x - y'' = 0$$

$$-y'' + y = -e^x$$

$$y'' - y = e^x$$

(ELDE)

Char. Eqn: $r^2 - 1 = 0$

$$r = \pm 1$$

$$y_h(x) = c_1 e^{-x} + c_2 e^x$$

MUDC's: $Y(x) = A x e^x$

$$Y'(x) = A e^x + A x e^x = A e^x (x+1)$$

$$Y''(x) = A e^x + A e^x + A x e^x = A e^x (x+2)$$

$$Y'' - Y = e^x$$

$$A e^x (x+2) - A x e^x = e^x$$

$$A x e^x + 2A e^x - A x e^x = e^x$$

$$2A = 1$$

$$A = \frac{1}{2}$$

Extremals of J have the form
 $y(x) = c_1 e^{-x} + c_2 e^x + \frac{1}{2} x e^x$

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 Midterm Exam - #6
 Page 184, Number 1d.

- (6) Find extremal for
 $J(y) = \int_0^1 yy' + (y'')^2 dx$
 with $y \in C^4[0,1]$, $y(0)=0$, $y'(0)=1$, $y(1)=2$, $y'(1)=4$

We can use ELDE. Note that $L = L(x, y, y', y'')$

$$L_y = y', \quad L_{y'} = y, \quad L_{y''} = 2y''$$

$$y' - \frac{d}{dx}[y] + \frac{d^2}{dx^2}[2y''] = 0 \quad (\text{See (3.28) in text})$$

$$y' - y' + 2y'''' = 0$$

(ELDE)

$$\begin{aligned} y'''' &= 0 \\ y'''' &= C_3 \\ y''' &= C_3 x + C_2 \\ y'' &= \frac{1}{2} C_3 x^2 + C_2 x + C_1 \\ y' &= \frac{1}{6} C_3 x^3 + \frac{1}{2} C_2 x^2 + C_1 x + C_0 \\ y(x) &= \frac{1}{24} C_3 x^4 + \frac{1}{6} C_2 x^3 + \frac{1}{2} C_1 x^2 + C_0 x + C_0 \end{aligned}$$

Rename Constants: $y(x) = Ax^3 + Bx^2 + Cx + D$
 $y'(x) = 3Ax^2 + 2Bx + C$

$$y(0)=0 \Rightarrow D=0$$

$$y'(0)=1 \Rightarrow C=1$$

So, $y(x) = Ax^3 + Bx^2 + x$

Now, we use the other two Bdry Cond's \Rightarrow

$$y(1) = 2 \Rightarrow A + B + 1 = 2$$

$$y'(1) = 4 \Rightarrow 3A + 2B + 1 = 4$$

EQNS are:

$$\begin{array}{l} A + B = 1 \\ 3A + 2B = 3 \end{array} \Rightarrow \begin{array}{l} 3A + 3B = 3 \\ \underline{3A + 2B = 3} \end{array}$$

Subtracting yields $B = 0$

and this gives $A = 1$

Hence, $y(x) = x^3 + x$ is the extremal.

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Midterm Exam - #7

Page 346, Problem 5

(7) Show that the general soln of

$$yu_x - xu_y = 0$$

has the general solution $u(x,y) = \Psi(x^2 + y^2)$,
where $\Psi: \mathbb{R} \rightarrow \mathbb{R}$ is any smoother fctn.

Do so by introducing polar coordinates
 $x = r \cos \theta$ and $y = r \sin \theta$.

$$u = u(x,y) = u(x(r,\theta), y(r,\theta)) = u(r \cos \theta, r \sin \theta)$$

$$\textcircled{1} \quad u_r = u_x \cos \theta + u_y \sin \theta \quad (\text{By Chain Rule})$$

$$\textcircled{2} \quad u_\theta = u_x (-r \sin \theta) + u_y (r \cos \theta) \quad (\text{By Chain Rule})$$

\Rightarrow

$$u_x = \frac{u_r - u_y \sin \theta}{\cos \theta}$$

$\frac{1}{r}$ Subst. into $\textcircled{2}$ gives

$$u_\theta = -r \sin \theta \left[\frac{u_r - u_y \sin \theta}{\cos \theta} \right] + u_y r \cos \theta$$

\Rightarrow

$$u_y = \frac{1}{r} \cos \theta u_\theta + \sin \theta u_r$$

and

$$u_x = \cos \theta u_r - \frac{1}{r} \sin \theta u_\theta$$

Plugging these into the pde, we have

(2)

$$yu_x - xu_y = 0$$

$$r \sin \theta \left[\cos \theta u_r - \frac{1}{r} \sin \theta u_\theta \right] - r \cos \theta \left[\frac{1}{r} \cos \theta u_\theta + \sin \theta u_r \right] = 0$$

$$r \sin \theta \cos \theta u_r - \sin^2 \theta u_\theta - \cos^2 \theta u_\theta - r \sin \theta \cos \theta u_r = 0$$

$$-u_\theta = 0$$

$$u_\theta = 0 \quad \text{for all } r, \theta$$

Hence, u must be a function of the independent variable r only. In particular, any function that is cont.'sly diff'ble and that is only a function of r will satisfy this pde.

Hence, if Ψ is any cont.'sly diff'ble function $\Psi: \mathbb{R}^1 \rightarrow \mathbb{R}^1$, then we can define

$$u(x, y) = \Psi(x^2 + y^2),$$

and u will be a soln to the pde.

Alternatives to the previous discussion:

Observe that

$$u_\theta = -r \sin \theta u_x + r \cos \theta u_y$$

$$= -y u_x + x u_y$$

So, the pde reduces

$$yu_x - xu_y = 0 \quad \forall x, y \Rightarrow -u_\theta = 0 \quad \forall (r, \theta)$$

And $u_\theta = 0 \quad \forall (r, \theta)$ implies that u is only a function of r ; that is, $u = \Psi(x^2 + y^2)$ where Ψ an arbitrary function is a soln. to the pde.

③

Yet another alternative is to begin with

$$u = \Psi(x^2 + y^2) \quad (\text{with } \Psi \text{ sufficiently diff'ble})$$

and compute

$$u_x = \Psi'(x^2 + y^2) \cdot 2x \quad \text{and} \quad u_y = \Psi'(x^2 + y^2) \cdot 2y$$

Plugging these into the eqn yield

$$\begin{aligned} y u_x - x u_y &= y(\Psi' \cdot 2x) - x(\Psi' \cdot 2y) \\ &= 2xy \Psi' - 2xy \Psi' \\ &= 0 \end{aligned}$$

$\forall x, y$ where
 Ψ is sufficiently smooth

Other techniques used include writing

$$r = (x^2 + y^2)^{1/2} \quad \text{and} \quad \theta = \tan^{-1}(y/x)$$

and computing

$$\begin{aligned} u_x &= u_r \cdot \frac{dr}{dx} + u_\theta \cdot \frac{d\theta}{dx} = u_r \cdot \frac{1}{2}(x^2 + y^2)^{-1/2} (2x) + u_\theta \cdot \frac{1}{1+(y/x)^2} \cdot \frac{-y}{x^2} \\ &= u_r \cdot \frac{x}{r} + u_\theta \cdot \frac{-y}{x^2 + y^2} \end{aligned}$$

$$u_x = u_r \cdot \frac{x}{r} - u_\theta \cdot \frac{y}{r^2} = u_r \cdot \frac{r \cos \theta}{r} - u_\theta \cdot \frac{r \sin \theta}{r^2} = u_r \cos \theta - \frac{u_\theta \sin \theta}{r}$$

$$\boxed{u_x = u_r \cos \theta - u_\theta \frac{\sin \theta}{r}}$$



Similarly,

(4)

$$u_y = u_r \cdot \frac{dr}{dy} + u_\theta \cdot \frac{d\theta}{dy}$$

$$= u_r \cdot \frac{1}{2}(x^2+y^2)^{-1/2} (2y) + u_\theta \cdot \left(\frac{1}{1+(y/x)^2} \cdot \frac{1}{x} \right)$$

$$= u_r \cdot \frac{y}{r} + u_\theta \cdot \left(\frac{1}{x + (y^2/x)} \right)$$

$$= u_r \cdot \frac{r \sin \theta}{r} + u_\theta \left(\frac{x}{x^2 + y^2} \right)$$

$$= u_r \cdot \sin \theta + u_\theta \frac{r \cos \theta}{r^2}$$

$$\boxed{u_y = u_r \cdot \sin \theta + u_\theta \frac{\cos \theta}{r}}$$

Substituting these into $yu_x - xu_y = 0$ leads to

$$-u_\theta = 0 \quad \forall (r, \theta)$$

$$u_\theta = 0 \quad \forall (r, \theta)$$

ie. any function that is only a function of the radius variable and is sufficiently smooth is a soln of the pde..