

0	1	2	3	4	5	6	7	8	9	
10	10	10	10	10	10	10	10	5	10	95

Math 333 First Exam (19 Oct 2010)

Name:

median score 62
(65%)
avg score 59
(62%)

If you use a theorem indicate what it is. Show all work (unless instructed otherwise).

Good Luck!

2pts each

0. Circle True or False without explanation:

- (**T**) or F) Every linearly independent set in V can be extended to a basis of V .
- (**T**) or F) \mathbf{R}^9 and $M_{3 \times 3}$ are isomorphic.
- (**T**) or (**F**) If $T \circ S$ is one-to-one then so is T .
- (**T**) or (**F**) If U, W are subspaces then so is their union $U \cup W$.
- (**T**) or F) Any linear $T : \mathcal{P}_2 \rightarrow \mathcal{P}_2$ that is one-to-one is onto.

1. Find a basis and the dimension for the subspace (in $M_{3 \times 3}$) given by

$$W := \left\{ \begin{bmatrix} a & 0 & c \\ c & a & b \\ 0 & b & a \end{bmatrix} : a, b, c \in \mathbf{R} \right\}. \text{ Do not prove anything.}$$

$$a \begin{bmatrix} 1 & 0 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} + b \begin{bmatrix} 0 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

basis (clearly span and are lin. indep)

so $\dim = 3$.

10 pts 2. Carefully verify that the set of all even functions on \mathbf{R} ,

$$W := \{f \in \mathcal{F} : f(x) = f(-x) \text{ for all } x \in \mathbf{R}\},$$

is a subspace of \mathcal{F} .

Suppose $f, g \in W$ and c is a scalar in \mathbf{R} .

Then

$$\begin{aligned} (f+g)(-x) &= \underbrace{f(-x)}_{\text{def of } f} + \underbrace{g(-x)}_{\text{def of } g} = \underbrace{f(x)}_{\text{hyp. of } f} + \underbrace{g(x)}_{\text{hyp. of } g} = \underbrace{(f+g)(x)}_{\text{def of } f+g} \\ (cf)(-x) &= c \cdot f(-x) = c \cdot f(x) = (cf)(x) \end{aligned}$$

Thus $f+g \in W$ and $cf \in W$ making W a subspace.

10 pts

3. Suppose that $T : V \rightarrow W$ is linear and $\{T(v_1), \dots, T(v_n)\}$ is a linearly independent set. Prove that $\{v_1, \dots, v_n\}$ is linearly independent but the opposite implication may fail.

6 pts

Suppose $a_1 v_1 + \dots + a_n v_n = 0$ for some a_1, \dots, a_n .

Then $T(\text{---}) = T(0)$ i.e.

$$a_1 T(v_1) + \dots + a_n T(v_n) = 0 \quad (\text{by linearity of } T \text{ and } T(0) = 0)$$

By our hypothesis on $T(v_i)$, $a_1 = a_2 = \dots = a_n = 0$.

Thus $\{v_1, \dots, v_n\}$ are lin. indep.

4 pts

The opposite implication fails \Rightarrow shown by an example

$$T : \mathbf{R}^2 \rightarrow \mathbf{R}^2 \text{ being the zero map, i.e., } T(v) = 0 \text{ for all } v \in \mathbf{R}^2.$$

Just take $v_1 = e_1, v_2 = e_2$.

4. Let $T : \mathcal{P}_2 \rightarrow \mathcal{P}_2$ be given by $T(p) := p''$ (the second derivative).

5 pts

a) Describe $\ker(T)$ and compute $\text{nullity}(T)$.

$$\ker(T) = \{p \in \mathcal{P}_2 : p'' = 0\} = \{ax^2 + bx + c : 2a = 0\} = \{bx + c : b, c \in \mathbb{R}\}$$

which are all "linear functions" as encountered in calculus class; or, simply, \mathcal{P}_1 .

$$\text{nullity}(T) = 2 \quad \text{since } \{1, x\} \text{ is a basis of } \ker(T).$$

5 pts

b) Describe $\text{range}(T)$ and compute $\text{rank}(T)$.

$$\text{range}(T) = \{p'' : p \in \mathcal{P}_2\} = \{2a : a \in \mathbb{R}\} = \text{all constant functions}$$

or, simply, \mathcal{P}_0 .

$$\text{rank}(T) = 1 \quad \text{since } \{1\} \text{ is a basis of } \text{range}(T).$$

c) Write out the matrix of T in the standard basis $\{1, x, x^2\}$.

$$\begin{aligned} \text{Since } T(1) &= 0 \\ T(x) &= 0 \\ T(x^2) &= 2 = 2 \cdot 1 \end{aligned} \quad \text{we have } [T] = \begin{bmatrix} 0 & 0 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

10 pts

5. You learned that if $\dim V = \dim W$ (and finite) then V and W are isomorphic. Recall the construction of the isomorphism $T : V \rightarrow W$ (without proving its properties).

Let $\mathcal{B} = \{v_1, \dots, v_n\}$ be a basis of V and $\{w_1, \dots, w_n\}$ be a basis of W .

Then, on any $v \in V$, we define

$$T(v) = \left[T\left(\sum_{i=1}^n x_i v_i\right) = \sum_{i=1}^n x_i T(v_i) \right] = \sum_{i=1}^n x_i w_i$$

Can cut out this piece.

where x_i are the coordinates of v i.e. $\begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = [v]_{\mathcal{B}}$.

6. Suppose that $\{v_1, v_2, v_3\}$ is a basis (of some V).

4 pts

a) Show that $\mathcal{B} = \{v_1 - v_2, v_2 - v_3, v_3 - v_1\}$ is not a basis.

The vectors are lin. dep. since:

$$\begin{aligned} 1 \cdot (v_1 - v_2) + 1 \cdot (v_2 - v_3) + 1 \cdot (v_3 - v_1) &= \\ = v_1 - v_2 + v_2 - v_3 + v_3 - v_1 &= 0. \end{aligned}$$

6 pts

b) Show that $\mathcal{B} = \{v_1 + v_2, v_2 + v_3, v_3 + v_1\}$ is a basis.

Lin. independence: $a_1(v_1 + v_2) + a_2(v_2 + v_3) + a_3(v_3 + v_1) = 0$
 $(a_1 + a_3)v_1 + (a_1 + a_2)v_2 + (a_2 + a_3)v_3 = 0$

so $\begin{cases} a_1 + a_3 = 0 \\ a_1 + a_2 = 0 \\ a_2 + a_3 = 0 \end{cases}$ i.e. $\begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} = 0$ so $a_1 = a_2 = a_3 = 0$.

Spanning: Any v can be written as $b_1v_1 + b_2v_2 + b_3v_3$.

The question is if we can write it as $a_1(v_1 + v_2) + a_2(v_2 + v_3) + a_3(v_3 + v_1)$.

That is if we can solve $A \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$. But this we can $\mathbf{a} = A^{-1}\mathbf{b}$.

\leftarrow matrix A if $\det = 1+1-0=2$
 3×3 so A^{-1} exists.

10 pts

7. Suppose that the set $\mathcal{A} = \{v_1, \dots, v_n\}$ spans all of V but fails to do so if one removes any of its vectors. Prove that \mathcal{A} is independent.

Suppose \mathcal{A} is dependent i.e. $a_1v_1 + \dots + a_nv_n = 0$ and some $a_i \neq 0$.

Then $v_i = -\frac{1}{a_i}(a_1v_1 + \dots + a_nv_n)$ so $v_i \in \text{span}(v_1, \dots, v_n)$
 \leftarrow it's missing \leftarrow it's missing

Thus $\text{span}(v_1, \dots, v_n) = V$
 \leftarrow it's removed

5 pts 8. Show that $\{e^x, e^{-x}\}$ is linearly independent (in \mathcal{F}).

Say $ae^x + be^{-x} = 0$.

Then @ $x=0$: $a+b=0$

@ $x=1$: $a \cdot e + b \cdot e^{-1} = 0$

so $\begin{bmatrix} 1 & 1 \\ e & e^{-1} \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = 0$

has $\det = e^{-1} - e \neq 0$ so $a=b=0$.

9. A certain binary code sends a message $x = (x_1, x_2)^T$ to $b := Gx$ where the code generating matrix G is

$$G = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \\ 1 & 0 \end{bmatrix} \quad \text{so} \quad \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix} = Gx = \begin{bmatrix} x_1 \\ x_2 \\ x_1 + x_2 \\ x_1 \end{bmatrix}$$

6 pts

a) Find the conditions ("check") for (b_1, b_2, b_3, b_4) to be an uncorrupted message (i.e. $b = Gx$ for some x).

b uncorrupted iff $b \in C(G)$ iff $b \perp N(G^T)$

$N(G^T)$ is 2-dim (since G has two pivots $\frac{2}{2} = 4-2$) and we easily "guess"

$N(G^T) = \text{span} \{ [1, 1, 1, 0], [1, 0, 0, 1] \}$

$$\begin{bmatrix} 1 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix} = 0 \quad \text{i.e.}$$

$b_1 + b_2 + b_3 = 0$ ← ordinary parity check

$b_1 + b_4 = 0$ ← $b_1 = b_4$

NOTE:

$[A|I]$ per theorem we proved so could short circuit

4 pts.

b) How many bits in (b_1, b_2, b_3, b_4) can be corrupted and the original message (x_1, x_2) is still recoverable? (Give an answer and some indication of the reason.)

Just one since one can recover x_1, x_2 from any three (in fact any two of the first three) and so corrupting the middle bits can be unrecoverable e.g.

$$\begin{bmatrix} 1 \\ 1 \end{bmatrix} \mapsto \begin{bmatrix} 1 \\ x \\ x \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix} \mapsto \begin{bmatrix} 1 \\ x \\ x \\ 1 \end{bmatrix}$$

0	1	2	3	4	5	6	7	8	
8	10	10	10	10	10	10	10	10	88 _{max}

Math 333 Second Exam (30 Nov 2010)

Name:

Show all work (unless instructed otherwise). Good Luck!

0. Circle **True** or **False** without explanation: Below vectors are in a finite dimensional vector space V , $\langle \cdot | \cdot \rangle$ denotes an inner product, and $\| \cdot \|$ its associated norm.

(**T** or **F**) $\langle u | v \rangle = \|u\| \|v\|$ only if one of u and v is a scalar multiple of another.

(**T** or **F**) Every norm on V comes from an inner product.

(**T** or **F**) $\bar{x} := A^+ b$ is a **least squares solution** to $Ax = b$.

(**T** or **F**) For any square matrix A , the SVD gives a diagonalization of A .

10 pts

1. Suppose that u, v, w are vectors in an inner product space and

$$\langle u | v \rangle = -3, \quad \langle u | w \rangle = -6, \quad \langle v | w \rangle = 6$$

$$\|u\| = 3, \quad \|v\| = \sqrt{5}, \quad \|w\| = \sqrt{8}.$$

5 pts

a) Evaluate $\|u + w\| = \dots \sqrt{\langle u + w | u + w \rangle}$

$$= (\langle u | u \rangle + 2\langle u | w \rangle + \langle w | w \rangle)^{1/2}$$

$$= (3 + 2 \cdot (-6) + 8)^{1/2} = \sqrt{5}$$

5 pts

b) Determine by computation if $u + v$ is perpendicular to w .

$$\langle u + v | w \rangle = \langle u | w \rangle + \langle v | w \rangle$$

$$= -6 + 6 = 0$$

so **yes**

- 10 pts 4. Let $\|A\|$ be a matrix norm of a square matrix A compatible with a vector norm $\|x\|$. Show that if λ is an eigenvalue of A then

$$\|A\| \geq |\lambda|.$$

Let $v \neq 0$ be the corresponding eigenvector so that

$$Av = \lambda v.$$

$$\text{Then } \|A\| \cdot \|v\| \geq \|Av\| = \|\lambda v\| = |\lambda| \cdot \|v\|$$

Div. by $\|v\|$, yields $\|A\| \geq |\lambda|$.
↑ by compatibility ↑ prop. of $\|\cdot\|$

- 10 pts 5. Prove (while justifying each step) that the Frobenius norm

$$\|A\|_F := \sqrt{\sum_{i,j=1}^n |a_{ij}|^2}$$

is compatible with the Euclidean norm, i.e., $\|Ax\| \leq \|A\|_F \|x\|$ for all x in \mathbf{R}^n .

$$\|Ax\|^2 = \sum_i \left| \sum_j a_{ij} x_j \right|^2$$

$$\leq \sum_i \left(\sqrt{\sum_j a_{ij}^2} \sqrt{\sum_j x_j^2} \right)^2$$

by using
Cauchy-Schwarz

$$= \sum_i \left(\sum_j a_{ij}^2 \sum_j x_j^2 \right)$$

$$= \left(\sum_i \sum_j a_{ij}^2 \right) \sum_i x_i^2$$

$$= \sum_{i,j} a_{ij}^2 \sum_i x_i^2 = \|A\|_F^2 \cdot \|x\|^2$$

6 pts

8. Consider the matrix $A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$. *lengths only!*

a) Compute the semi-axis of the ellipse that is the image of the unit circle under the linear transformation T_A of the plane \mathbf{R}^2 induced by A .

$$A^T A = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} \text{ has char. poly}$$

$$\lambda^2 - \text{trace } \lambda + \det = 0$$

$$\lambda^2 - 3\lambda + 1 = 0 \text{ with roots}$$

$$\lambda_{1,2} = \frac{3 \pm \sqrt{9-4}}{2}$$

$$\text{Singular values: } \sigma_1 = \sqrt{\lambda_1} = \sqrt{\frac{3+\sqrt{5}}{2}}$$

$$\sigma_2 = \sqrt{\lambda_2} = \sqrt{\frac{3-\sqrt{5}}{2}}$$

are the semi-axis lengths

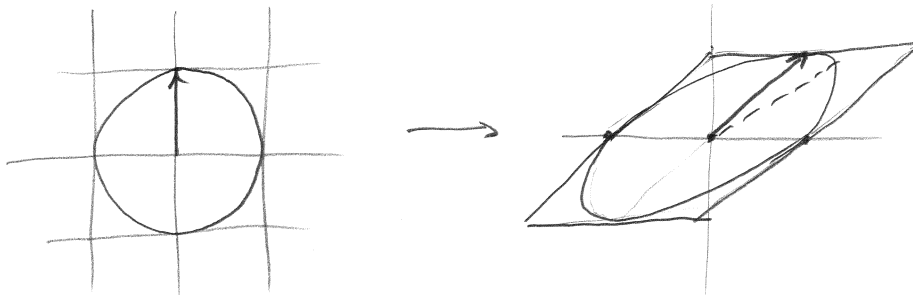
3 pts

b) What is the value of the operator norm $\|A\| := \max_{\|x\|=1} \|Ax\|$? (Here $\|x\|$ is the ordinary Euclidean norm.)

$$\|A\| = \sigma_1 = \sqrt{\frac{3+\sqrt{5}}{2}}$$

1 pt

c)* Sketch the image of the square $\{(x, y) : -1 \leq x \leq 1, -1 \leq y \leq 1\}$ under T_A and guess-sketch the ellipse (from a)). *mark the semi-axes*



12:35

0	1	2	3	4	5	6	7	8	9	10	120 (max)
10	10	10	10	10	10	15	10	15	10	10	

Math 333 Final Exam (15 Dec 2010)

Name:

Show all work (unless instructed otherwise). Good Luck!

10 pts

0. Circle True or False without explanation. Below V is a finite dimensional vector space.

(T or F) V is isomorphic to \mathbf{R}^n provided $n = \dim(V)$.

(T or F) Any two bases of V have the same number of elements.

(T or F) If $T : V \rightarrow V$ is linear and onto then it is one-to-one.

(T or F) For orthogonally diagonalizable A , the singular values are eigenvalues.

(T or F) For $A \geq 0$, $A^3 > 0$ implies that A is irreducible.

10 pts

1. V is an inner product space and $\|x\| := \sqrt{\langle x|x \rangle}$ is the associated norm.

a) Demonstrate the Parallelogram Law:

$$\|u+v\|^2 + \|u-v\|^2 = 2\|u\|^2 + 2\|v\|^2 \quad \text{for all } u, v \text{ in } V.$$

$$\text{LHS} = \langle u+v | u+v \rangle^2 + \langle u-v | u-v \rangle^2$$

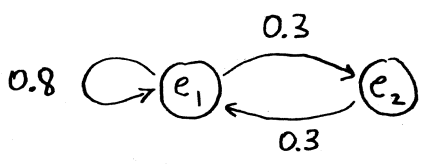
$$= \|u\|^2 + 2\langle u|v \rangle + \|v\|^2 + \|u\|^2 - 2\langle u|v \rangle + \|v\|^2$$

$$= 2\|u\|^2 + 2\|v\|^2$$

adjusted EI score = $\max \left\{ EI, 0.2EI + 0.8M \right\}$
↖ *max*

10 pts

2. The following graph describes the flow of wealth in a partnership of two agents e_1 and e_2 .



$$A = \begin{bmatrix} 0.8 & 0.3 \\ 0.3 & 0 \end{bmatrix} \quad \begin{array}{l} \text{trace} = 0.8 \\ \text{det} = -0.09 \end{array}$$

a) What is the asymptotic ratio of the wealth of e_1 to the wealth of e_2 ?

$$\lambda^2 - 0.8\lambda - 0.09 = 0 \quad \text{so} \quad \lambda = \frac{0.8 \pm \sqrt{0.64 + 0.36}}{2} = \frac{0.8 \pm 1}{2}$$

so $\lambda_1 = 0.9$; $\lambda_2 = -0.1$

$$A - \lambda_1 I = \begin{bmatrix} -0.1 & 0.3 \\ 0.3 & 0.9 \end{bmatrix} \quad \text{so} \quad -0.1x_1 + 0.3x_2 = 0$$

gives eigenvector $v_1 = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$ hence the ratio = $\frac{3}{1}$

b) Compute the growth rate λ_1 . Is this partnership going to prosper or fizzle out?

$\lambda_1 = 0.9$

Since $\lambda_1^n = 0.9^n \rightarrow 0$ as $n \rightarrow \infty$ the partnership fizzes out

10 pts

3. Let $\|A\|$ be a matrix norm of a square matrix A compatible with a vector norm $\|x\|$. Suppose there is x with $\|x\| = 1$ such that

$$\|Ax\| = 2 \quad \text{and} \quad \|A^2x\| = 9.$$

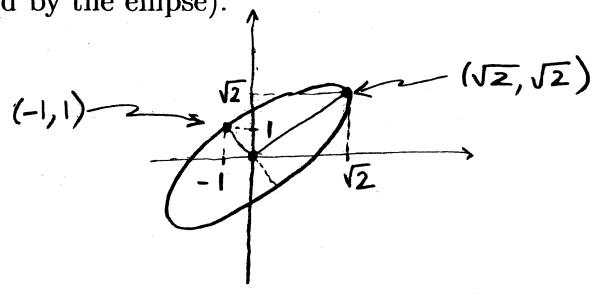
a) Prove that $\|A\| \geq 2$. $\|A\| = \|A\| \cdot \|x\| \stackrel{\text{compatibility}}{\geq} \|Ax\| = 2$

b)* Prove that $\|A\| \geq 3$. $\|A\|^2 \stackrel{\text{matrix norm}}{\geq} \|A \cdot A\| = \|A^2\| \|x\| \geq \|A^2x\| = 9$

so $\|A\| \geq 3$

10 pts

4. For a 2×3 matrix A , the image of the unit sphere under T_A is the depicted solid ellipse (i.e., the oval area bounded by the ellipse).



3 pts

b) What is the rank(A)?

2

3 pts

a) What are the singular values of A ?

lengths of semi axes: $\sqrt{\sqrt{2}^2 + \sqrt{2}^2} = \sqrt{4} = 2$
 and $\sqrt{(-1)^2 + 1^2} = \sqrt{2}$

4 pts

c) What is the U in the SVD $A = U\Sigma V^T$?

$u_1 = \text{normalized } (\sqrt{2}, \sqrt{2})^T = (\sqrt{2}/2, \sqrt{2}/2)^T$
 $u_2 = \text{normalized } (-1, 1)^T = (-1/\sqrt{2}, 1/\sqrt{2})^T$

10 pts

5. Suppose that B is a fixed 2×2 matrix.

5 pts

a) Check that the set $W_B := \{A \in M_{2 \times 2} : AB = BA\}$ is a subspace (of $M_{2 \times 2}$).

Suppose $A, \tilde{A} \in W_B$ i.e. $AB \stackrel{(1)}{=} BA$ and $\tilde{A}B \stackrel{(2)}{=} B\tilde{A}$
 Then $(A + \tilde{A})B = AB + \tilde{A}B \stackrel{(1)(2)}{=} BA + B\tilde{A} = B(A + \tilde{A})$ so $A + \tilde{A} \in W_B$
 Suppose $A \in W_B$ and α scalar.
 Then $(\alpha A)B = \alpha(AB) \stackrel{(1)}{=} \alpha(BA) = B(\alpha A)$ so $\alpha A \in W_B$

5 pts

b) Find a basis of W_B for the specific B given by $B = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$.

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \in W_B \text{ iff } \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$\begin{bmatrix} a+b & a+b \\ c+d & c+d \end{bmatrix} = \begin{bmatrix} a+c & b+d \\ a+c & b+d \end{bmatrix}$$

i.e. $\begin{cases} a+b = a+c \text{ so } b=c \\ a+b = b+d \text{ so } a=d \\ c+d = a+c \text{ so } d=a \\ c+d = b+d \text{ so } c=b \end{cases}$

Got $a=d$ $c=b$ i.e.

$A = a \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + c \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$. Hence $\left\{ \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \right\}$ forms a basis

15 pts

6. Let A be $n \times m$ with independent columns and QR-decomposition $A = QR$. (Here Q is $n \times m$ and R is $m \times m$.)

4 pts

a) Give an idea why $C(A) = C(Q)$.

From $A = QR$ columns of A are lin. comb. of col of Q ,
so that $C(A) \subseteq C(Q)$

Likewise, from $Q = AR^{-1}$, $C(Q) \subseteq C(A)$.

The two inclusions give $C(A) = C(Q)$

5 pts

b) Write the formula for the projection of $b \in \mathbb{R}^n$ onto $C(A)$ in terms of Q and b .

$$\text{Proj}_{C(Q)} b = q_1^T b q_1 + \dots + q_m^T b q_m = QQ^T b$$

6 pts

c) Express the least squares solution to $Ax = b$ by using Q , R , and b . Justify.

$$A^T A x = A^T b \text{ becomes } R^T \underbrace{Q^T Q}_I R x = R^T Q^T b$$

$$R^T R x = R^T Q^T b \quad / R^{-1}(R^T)^{-1}$$

$$x = R^{-1}(R^T)^{-1} R^T Q^T b = R^{-1} Q^T b$$

10 pts

7. Assuming $\{v_1, v_2, v_3\}$ is linearly independent, show that $\{v_1, v_1 + v_2, v_1 + v_2 + v_3\}$ is linearly independent as well.

$$\text{Suppose } a_1 v_1 + a_2 (v_1 + v_2) + a_3 (v_1 + v_2 + v_3) = 0$$

$$\text{Then } (a_1 + a_2 + a_3)v_1 + (a_2 + a_3)v_2 + a_3 v_3 = 0$$

$$\text{By lin indep of } \{v_1, v_2, v_3\} : a_3 = 0$$

$$a_2 + a_3 = 0 \text{ so } a_2 = 0$$

$$a_1 + a_2 + a_3 = 0 \text{ so } a_1 = 0$$

15 pts

8. Consider $T : \mathcal{P}_2 \rightarrow \mathcal{P}_2$ given by $T(p(x)) = xp'(x)$.

4 pts

a) What polynomials $p(x)$ make up the kernel(T)?

$$\begin{aligned}
 xp'(x) &= 0 \text{ for all } x \\
 p'(x) &= 0 \text{ --- " ---} \\
 p(x) &= \text{const polynomial.}
 \end{aligned}$$

5 pts

b) Find the matrix $[T]$ of T with respect to the standard basis $\{1, x, x^2\}$.

$$\begin{aligned}
 T(1) &= x \cdot 0 = 0 \\
 T(x) &= x \cdot 1 = x \\
 T(x^2) &= x \cdot 2x = 2x^2
 \end{aligned}$$

so $[T] =$

	1	x	x ²
1	0	0	0
x	0	1	0
x ²	0	0	2

2 pts

c) What is the rank(T)? (Use a.)

$$\text{rank}(T) = \text{rank}([T]) = 2$$

4 pts

d) Show that $S = I + T$ is invertible. (Here I is the identity so S is explicitly given by $S(p(x)) = p(x) + xp'(x)$; although, you may just use $[S]$ in your solution.)

$$[S] = [I + T] = [I] + [T] = \begin{bmatrix} 1 & & \\ & 2 & \\ & & 3 \end{bmatrix}$$

which is invertible and thus so is S .

10 pts

9. Construct an orthogonal basis of \mathcal{P}_2 with the inner product $\langle p|q \rangle := \int_0^1 p(x)q(x)dx$.

We shall orthogonalize $\{1, x, x^2\}$. Take $v_1 = 1$.

$$\langle 1|x \rangle = \int_0^1 x dx = \frac{1}{2}x^2 \Big|_0^1 = \frac{1}{2};$$

Thus $\text{proj}_{\text{lin}(1)} x = \frac{\langle x|1 \rangle}{\langle 1|1 \rangle} \cdot 1 = \frac{1/2}{1} \cdot 1 = \frac{1}{2}$ and $v_2 = x - \frac{1}{2}$ is \perp to v_1 .

$$\langle 1|x^2 \rangle = \int_0^1 x^2 dx = \frac{1}{3}x^3 \Big|_0^1 = \frac{1}{3}, \quad \langle x - \frac{1}{2}|x^2 \rangle = \int_0^1 x^3 - \frac{1}{2}x^2 dx \\ = \frac{1}{4}x^4 - \frac{1}{6}x^3 \Big|_0^1 = \frac{1}{4} - \frac{1}{6} = \frac{1}{12}$$

Thus $\text{proj}_{\text{lin}(v_1, v_2)} x^2 = \frac{\langle x^2|1 \rangle}{\langle 1|1 \rangle} \cdot 1 + \frac{\langle x^2|x - \frac{1}{2} \rangle}{\langle x - \frac{1}{2}|x - \frac{1}{2} \rangle} (x - \frac{1}{2}) = \frac{1}{3} + \frac{1/12}{1/2} (x - \frac{1}{2})$

$$\text{Need } \langle x + \frac{1}{2}, x - \frac{1}{2} \rangle = \int_0^1 x^2 - x + \frac{1}{4} dx = \frac{1}{3} - \frac{1}{2} + \frac{1}{4} = \frac{1}{4} - \frac{1}{6} = \frac{1}{12}$$

Hence $v_3 = x^2 - x + \frac{1}{6}$

Got $\{1, x - \frac{1}{2}, x^2 - x + \frac{1}{6}\}$

10 pts

10. In Crystallographic Restriction Theorem, a rotation matrix $R_\theta = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$ preserved some lattice Γ in \mathbb{R}^2 , $R_\theta \Gamma = \Gamma$. Explain why $\text{trace}(R_\theta) = 2 \cos \theta$ had to be an integer.

Upon choosing a basis $\{u, v\}$ with $u, v \in \Gamma$ we notice that $R_\theta(u) = au + bv$, $R_\theta(v) = cu + dv$ for some $a, b, c, d \in \mathbb{Z}$

(This is because $R_\theta(u) \in \Gamma$ and $\Gamma = \{au + bv : a, b \in \mathbb{Z}\}$; likewise for $R_\theta(v)$.)

Thus $[R_\theta] = \begin{bmatrix} a & c \\ b & d \end{bmatrix}$ so $\text{trace } R_\theta = \text{trace } [R_\theta] = a + d \in \mathbb{Z}$

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