

Final Exam

If $\mathbf{A} = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ is invertible then $\mathbf{A}^{-1} = \frac{1}{\det \mathbf{A}} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$.

Theorem 2.40.

Suppose that \mathbf{A} is a 2×2 matrix with one eigenvalue λ of multiplicity 2, and suppose that the eigenspace of λ has dimension 1. Let \mathbf{v}_1 be a nonzero eigenvector, and choose \mathbf{v}_2 such that $(\mathbf{A} - \lambda \mathbf{I})\mathbf{v}_2 = \mathbf{v}_1$. Then

$$\begin{aligned} \mathbf{x}_1(t) &= e^{\lambda t} \mathbf{v}_1 \text{ and} \\ \mathbf{x}_2(t) &= e^{\lambda t} [\mathbf{v}_2 + t \mathbf{v}_1] \end{aligned}$$

form a fundamental set of solutions to the system $\mathbf{x}' = \mathbf{A}\mathbf{x}$.

Jacobian.

For a planar autonomous system given by

$$\begin{aligned} x' &= f(x, y), \\ y' &= g(x, y), \end{aligned}$$

the Jacobian of $\begin{bmatrix} f \\ g \end{bmatrix}$ at $\begin{bmatrix} x_0 \\ y_0 \end{bmatrix}$ is

$$J = J(x_0, y_0) = \begin{bmatrix} \frac{\partial f}{\partial x}(x_0, y_0) & \frac{\partial f}{\partial y}(x_0, y_0) \\ \frac{\partial g}{\partial x}(x_0, y_0) & \frac{\partial g}{\partial y}(x_0, y_0) \end{bmatrix}.$$

Poincaré Diagram: Classification of Phase Portraits in the $(\det A, \text{Tr } A)$ -plane

