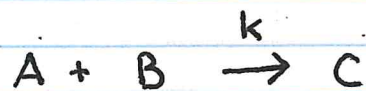


Law of Mass Action - simple

Rate of change of concentration is proportional to the product of reactants



results in system

$$A' = -kAB$$

$$B' = -kAB$$

$$C' = +kAB$$

where k is the reaction rate.

Remarks

(1) Concentration usually in molarity M

$$[A] = 1M \Leftrightarrow \text{liter contains } N_A = 6.02 \times 10^{23} \text{ molecules}$$

Mass action law only works for molarity. Once differential eqns have been found they can be converted to gm/liter use the gram molecular weights.

(2) AB proportional to total number of reactions (collisions) at any given instant

Arrhenius Theory

$$k = \alpha e^{-E_a/RT}$$

Reaction rate is proportional to the exponential term where

E_a = activation energy
for reaction

$$[E_a] = \text{J/mole}$$

T = temperature

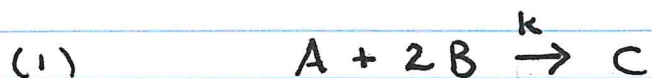
$$[T] = \text{Kelvin}$$

R = Gas constant = 8.314 J/mole/K

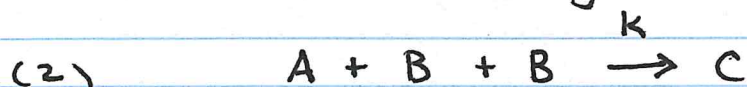
In some cases $\alpha = \alpha_0 T^n$ for $n \in (-1, 1)$.

Note that $T \uparrow$ implies rate $k \uparrow$

EXAMPLE Stoichiometric coefficients



Number of possible collisions is $[A][B]^2$
so (1) should be thought of as



having "three" reactants. L.O.M.A. then \Rightarrow

$$\frac{dC}{dt} = +kAB^2$$

Here "2" in eqn (1) is a stoichiometric coeff.

Law of Mass Action - general



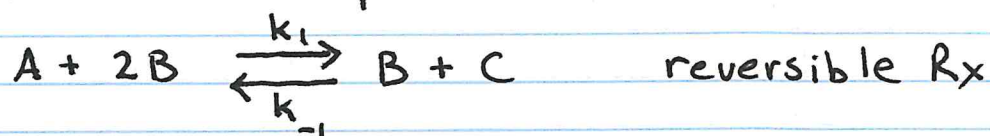
$$(2) \quad kAB^m = -\frac{dA}{dt} = \frac{1}{p} \frac{dC}{dt} = \frac{1}{(n-m)} \frac{dB}{dt}$$

The stoichiometric coefficients reflect the fact for every molecule of A

p molecules of C produced

(m-n) net loss of molecules of B

EXAMPLE Reaction equations for



Is a set of three chem. Rx eqns

$$A' = -k_1 AB^2 + k_{-1} BC - k_2 AC$$

$$B' = -k_1 AB^2 - k_{-1} BC + k_2 AC$$

$$C' = k_1 AB^2 - k_{-1} BC - k_2 AC$$

EXAMPLE Auto catalytic / Stoichiometry



Reaction equations for A, B, C, D

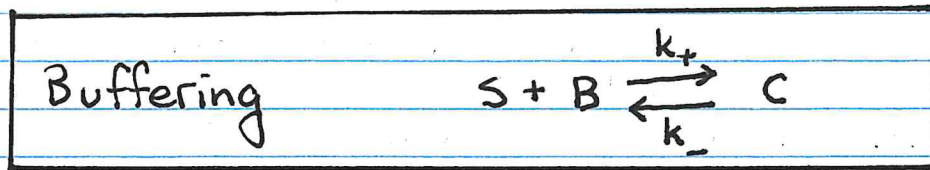
$$A' = -k_1 AB^3 + k_{-1} BCD - k_2 AD + k_3 BC^2$$

$$B' = -2k_1 AB^3 + 2k_{-1} BCD + k_2 AD - k_3 BC^2$$

$$C' = k_1 AB^3 - k_{-1} BCD - 2k_3 BC^2$$

$$D' = k_1 AB^3 - k_{-1} BCD - k_2 AD$$

Reaction equations autocatalytic since A is ultimately involved in its own creation.



$S = \text{Substrate}$ (Ca^{2+})
 $B = \text{Buffer}$ (Protein)
 $C = \text{complex}$ (Protein- Ca^{2+} complex)

Law of Mass Action

$$\begin{aligned}
 (1) \quad S' &= -k_+SB + k_-C & S(0) &= S_0 \\
 (2) \quad B' &= -k_+SB + k_-C & B(0) &= B_0 \\
 (3) \quad C' &= k_+SB - k_-C & C(0) &= C_0
 \end{aligned}$$

Conservation of receptors

$$(B+C)' = 0$$

$$(4) \quad B + C = N = B_0 + C_0 \quad \# \text{ receptor sites}$$

Use (4) to simplify (1)-(3)

$$\begin{aligned}
 S' &= f(B, S) \\
 B' &= f(B, S)
 \end{aligned}$$

where

$$f(B, S) = -k_+SB + k_-(N-B)$$

The sign of f determines trajectory direction.

Sign of $f(S, B)$

$$f(S, B) < 0$$

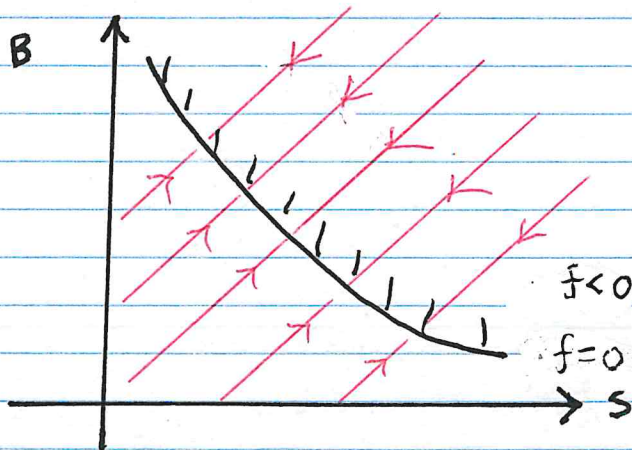
$$-k_+ SB + k_-(N-B) < 0$$

$$-(k_+ S + k_-)B + k_- N < 0$$

solving for B

$$f < 0 \Leftrightarrow B < g(S) = \frac{K_E N}{K_E + S}$$

where the equilibrium constant: $K_E = \frac{k_-}{k_+}$



physical region
(shaded)
for $c(t) = 0$

Notes

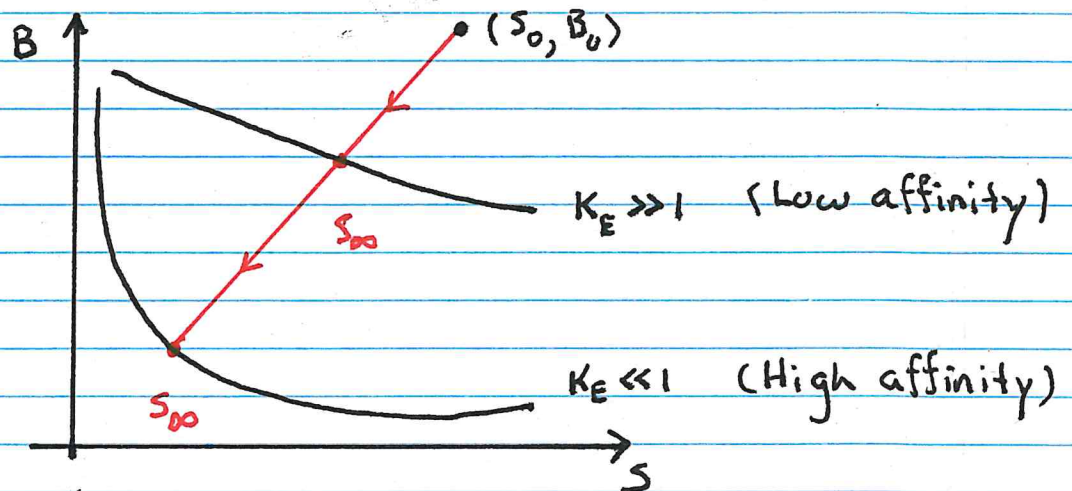
- $f=0$ is a line of fixed points
- $f < 0$ is physical region since $\frac{dS}{dt} < 0$ there.
- $f=0$ is a "stable invariant manifold"

Low and High affinity binding

Trajectories in the SB-plane have slope one and approach the curve

$$B = g(S) = \frac{K_E N}{K_E + S} \quad K_E = \frac{k_-}{k_+}$$

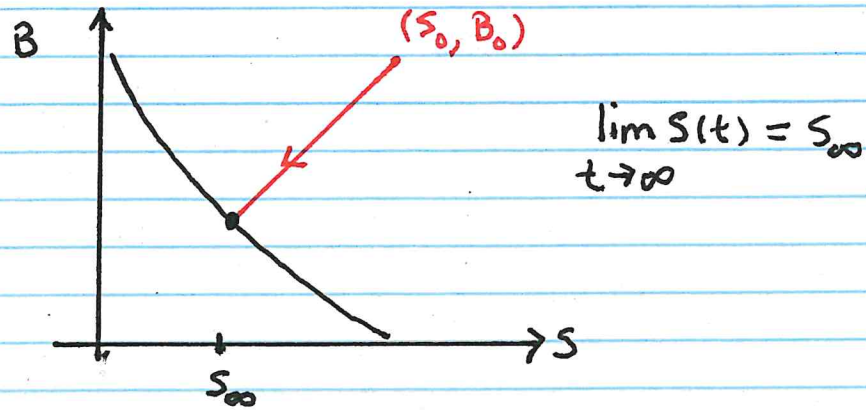
Consider the two cases $K_E \gg 1$ and $K_E \ll 1$



In the high affinity case the asymptotic value S_∞ of S is smaller meaning more substrate molecules are bound.

$K_E \gg 1$	Low Affinity	larger S_∞
$K_E \ll 1$	High Affinity	smaller S_∞

Asymptotic behavior



S_∞ can be found as the intersection of the two curves

$$B = S + \Delta$$

$$\Delta = B_0 - S_0$$

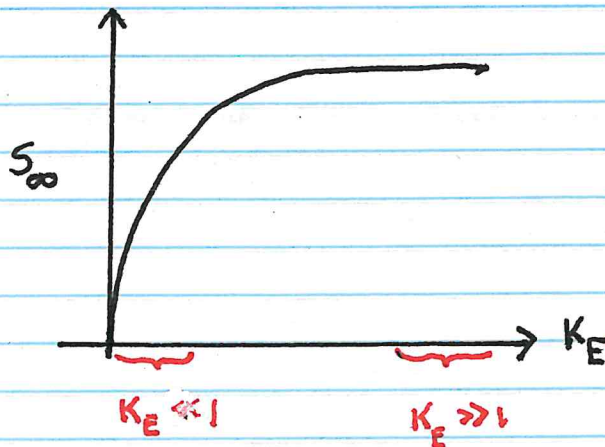
$$B = g(S)$$

Results in a quadratic eqn for S

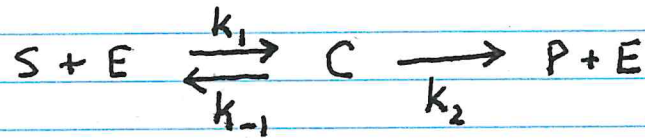
(1)

$$S + \Delta = \frac{K_E N}{K_E + S}$$

Solving and plotting S_∞ versus K_E one gets



Michaelis-Menten Kinetics

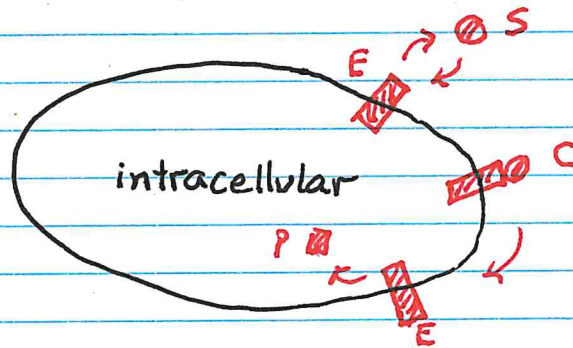


where

S = substrate (small)
E = enzyme (large)
C = complex
P = product

Can model cell nutrient uptake via membrane proteins E. Typically

$$E_0 \ll S_0$$



Law of Mass Action

$$(1) \quad \dot{S} = k_{-1}C - k_1SE \quad S(0) = S_0$$

$$(2) \quad \dot{E} = (k_{-1} + k_2)C - k_1SE \quad E(0) = E_0$$

$$(3) \quad \dot{C} = -\dot{E} \quad C(0) = 0$$

$$(4) \quad \dot{P} = k_2C \quad P(0) = 0$$

Conservation of receptors: $E + C = E_0$

Nondimensionalization

$$s = S/S^* \quad e = E/E^* \quad c = C/C^* \quad p = P/p^* \quad \tau = t/t^*$$

For the following choices

$$S^* = S_0 \quad E^* = C^* = E_0 \quad p^* = \frac{k_2}{k_1} \quad t^* = \frac{1}{k_1 E_0}$$

one can derive the dimensionless eqns for the dimensionless variables (s, e, c, p, τ)

$$\left\{ \begin{array}{ll} (1) & s' = \eta_1 c - se \quad s(0) = 1 \\ (2) & \epsilon e' = \eta_2 c - se \quad e(0) = 1 \\ (3) & \epsilon c' = -\eta_2 c + se \quad c(0) = 0 \\ (4) & p' = c \quad p(0) = 0 \end{array} \right.$$

where

$$\epsilon = \frac{E_0}{S_0} \ll 1$$

and

$$\eta_1 = \frac{k_{-1}}{k_1 S_0} \quad \eta_2 = \frac{k_{-1} + k_2}{k_1 S_0}$$

Notice that for positive k_1, k_{-1} and k_2

$$\eta_2 > \eta_1$$

physicality
condition

Quasi Steady State (QSS)

Is a science term where one lets $\epsilon \rightarrow 0$ as an approximation to (1)-(4). This yields from the $\epsilon\epsilon'$ eqn

$$(5) \quad k_2 c - s e = 0$$

Conservation of receptors (dimensionless) is:

$$(6) \quad e + c = 1$$

One may solve the system (5)-(6) for e in terms of s or c in terms of s

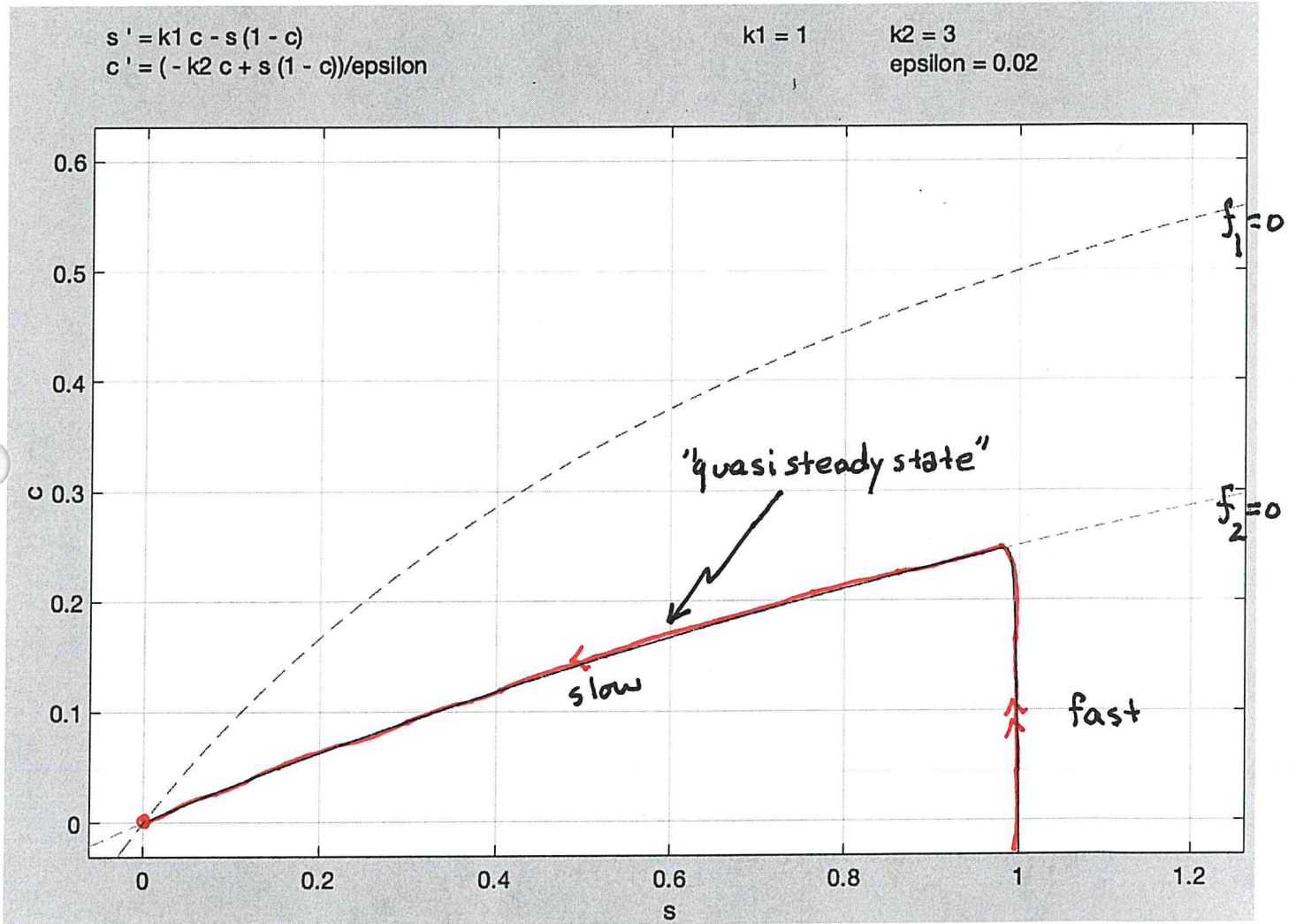
$$e = \frac{k_2}{k_2 + s} \quad c = \frac{s}{k_2 + s}$$

Next page shows a typical numerical solution of (1)-(4)

$$k_1 = 1 \quad k_2 = 3$$

Typical Numerical solution

$$k_2 > k_1 \quad \epsilon \ll 1$$



s and c nullclines shown

FAST-SLOW TIME APPROXIMATIONS

Using conservation of receptors

$$e + c = 1$$

in (1)-(3) we get a planar system

$$(5) \quad \begin{cases} \frac{ds}{dt} = f_1(s, c) = \kappa_1 c - s(1-c) \\ \varepsilon \frac{dc}{dt} = f_2(s, c) = -\kappa_2 c + s(1-c) \end{cases}$$

along with initial conditions:

$$s(0) = 1 \quad c(0) = 0$$

These equations are exact.

Nullclines/Equilibrium

Are easy to define

$$f_1 = 0 \quad \Leftrightarrow \quad c = H_1(s) = \frac{s}{\kappa_1 + s}$$

$$f_2 = 0 \quad \Leftrightarrow \quad c = H_2(s) = \frac{s}{\kappa_2 + s}$$

From these it is easy to show $(0, 0)$ is the sole equilibrium.

To understand the solutions of system (5) we introduce fast and slow times

τ slow time

$t = \frac{\tau}{\epsilon}$ fast time

Since $\epsilon \ll 1$, only a small change in the slow time τ is needed to make the fast time change by order 1 or $O(1)$. For instance, $\epsilon = 10^{-3}$ and $\tau = 2 \times 10^{-3}$ yields $t = 2$.

Lastly, system (5) can be expressed with either time using the chain rule.

$$\frac{ds}{d\tau} = \frac{ds}{dt} \frac{dt}{d\tau} = \frac{1}{\epsilon} \frac{ds}{dt}$$

$\frac{ds}{d\tau} = f_1(s, c)$ $\epsilon \frac{dc}{d\tau} = f_2(s, c)$	$\frac{ds}{dt} = \epsilon f_1(s, c)$ $\frac{dc}{dt} = f_2(s, c)$
SLOW SUBSYSTEM $\tau = \text{slow time}$	FAST SUBSYSTEM $t = \text{fast time}$

Leading order Fast Subsystem (FS)

Le

$$S(t) = S_0(t) + \epsilon S_1(t) + \dots$$

smaller higher order terms

$$C(t) = C_0(t) + \epsilon C_1(t) + \dots$$

in the (FS) yields leading order behavior

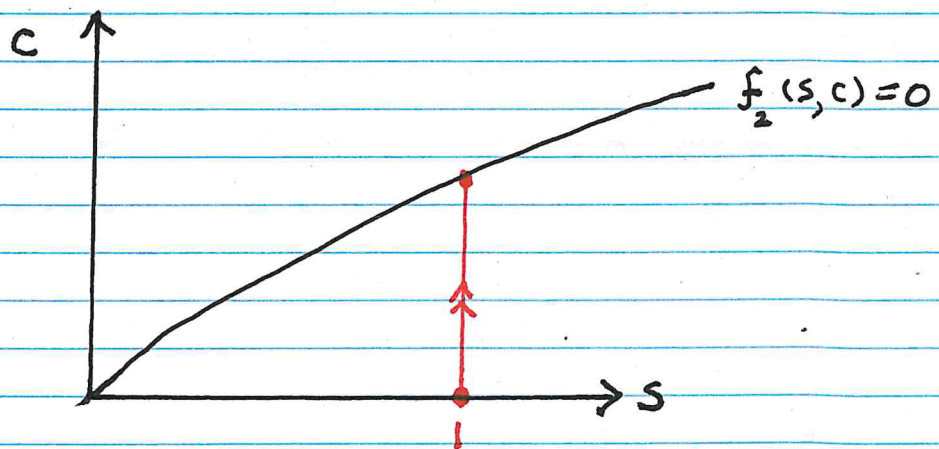
$$\left\| \begin{array}{ll} \frac{dS_0}{dt} = 0 & S_0(0) = 1 \\ \frac{dC_0}{dt} = f_2(S_0, C_0) & C_0(0) = 0 \end{array} \right\|$$

Solving with initial conditions

$$S_0(t) = 1$$

$$C_0(t) = \frac{1}{\mu} (1 - \exp(-\mu t)) \quad \mu \equiv \eta_2 + 1$$

Note $C_0(t) \rightarrow \frac{1}{\eta_2 + 1}$ or that $f_2(1, C_0) \rightarrow 0$



Leading order Slow Subsystem (SS)

Let

$$S(\tau) = S_0(\tau) + \epsilon S_1(\tau) + \dots$$

$$C(\tau) = C_0(\tau) + \epsilon C_1(\tau) + \dots$$

in the (SS) yields leading order behavior

$$(6) \quad \left\| \begin{array}{l} \frac{dS_0}{d\tau} = f_1(S_0, C_0) \\ 0 = f_2(S_0, C_0) \end{array} \right\| \quad \begin{array}{l} \text{Differential} \\ \text{Algebraic} \\ \text{Equations} \end{array}$$

$$\text{Recall that } f_2 = 0 \Leftrightarrow C_0 = H_2(S_0) = \frac{S_0}{K_2 + S_0}$$

$$(7) \quad \frac{dS_0}{d\tau} = F(S_0) = f_1(S_0, H_2(S_0))$$

Explicitly (7) is

$$\frac{dS_0}{d\tau} = (K_1 - K_2) \cdot H_2(S_0) < 0$$

This is separable and its implicit soln is

$$\boxed{S_0 + K_2 \ln(S_0) - 1 = -(K_2 - K_1)t}$$

Equilibria Stability (FS)

$$\frac{ds}{dt} = \varepsilon f_1(s, c)$$

$$\frac{dc}{dt} = f_2(s, c)$$

Sole equilibria is $P = (0, 0)$. Nullclines are

$$f_1 = 0 \quad c = H_1(s) = \frac{s}{K_1 + s}$$

$$f_2 = 0 \quad c = H_2(s) = \frac{s}{K_2 + s}$$

Jacobian at $P = (0, 0)$

$$Df^{\rightarrow}(0, 0) = \begin{bmatrix} -\varepsilon & \varepsilon K_1 \\ 1 & -K_2 \end{bmatrix}$$

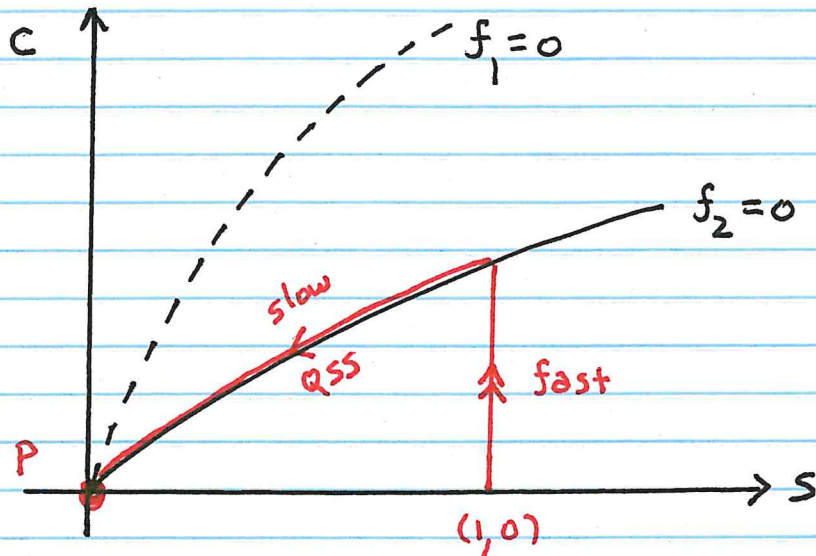
From this we see

$$\det Df^{\rightarrow} = \varepsilon(K_2 - K_1) > 0$$

$$\text{Tr } Df^{\rightarrow} = -(K_2 + \varepsilon) < 0$$

hence P is stable.

Summary of Dynamics



- (1) Rapidly achieves QSS
- (2) Measurable dynamic more likely to only be motion on slow subsystem manifold $f_2 = 0$ or

$$c = \frac{s}{\kappa_2 + s}$$

- (3) Continues until substrate depleted
- (4) Since $e + c = 1$, $e \rightarrow 1$ as $t \rightarrow \infty$.
- (5) Production rate given by slow subsystem

$$\frac{dp}{dt} = c = \frac{s}{\kappa_2 + s}$$

Production Rate

The dimensionless production rate v is

$$v \equiv \frac{dp}{dt} = \frac{s}{s + k_2}$$

This can be converted back to dimensional form

$$(1) \quad V = \frac{dP}{dt} = \frac{\bar{V}S'}{K_m + S'}$$

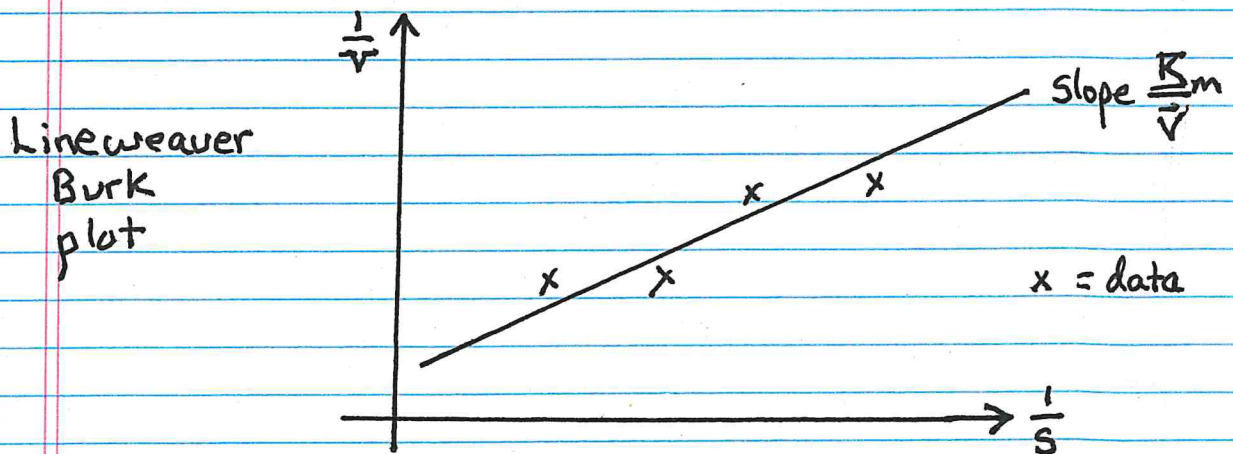
where

$$\bar{V} = k_2 E_0 \quad K_m = \frac{k_{-1} + k_2}{k_1}$$

Eqn (1) can be re-written

$$\boxed{\frac{1}{V} = \frac{1}{\bar{V}} + \frac{K_m}{\bar{V}} \frac{1}{S}}$$

Measure production rate and S . Use linear regression to find \bar{V} and K_m



Quick Derivation (Michaelis-Menten)

Suppose you know a priori that E and C are fast variables then production rates can be computed directly from the dimensional equations

$$S' = k_1 C - k_1 S E$$

$$E' = (k_1 + k_2) C - k_1 S E$$

$$C' = -(k_1 + k_2) C + k_1 S E$$

$$P' = k_2 C$$

} Both zero
when in
QSS

Noting that the number of receptors is conserved

$$\begin{array}{l} (k_1 + k_2) C - k_1 S E = 0 \\ E + C = E_0 \end{array}$$

QSS

receptors.

These are two eqns for (E, C). Solving these we get C and E as functions of S: 0

$$C = \frac{S E_0}{K_m + S}$$

so that

$$\frac{dP}{dt} = k_2 C = \frac{\bar{v} S}{S + K_m}$$

as before.