

Necessary Conditions for local Min (Max)

If \bar{y} is a local min of J then

$$(i) \quad \Delta J = J(\bar{y} + \varepsilon h) - J(\bar{y}) \geq 0$$

for all admissible variations $\delta y = \varepsilon h(x)$

In this setting $y = \bar{y} + \varepsilon h$ and \bar{y} are near each other if ε is small since

$$\|y - \bar{y}\| = \|\varepsilon h\| = \varepsilon \|h\| \rightarrow 0 \quad \text{as } \varepsilon \rightarrow 0.$$

Since

$$\Delta J = \delta J(\bar{y}, h) \varepsilon + o(\varepsilon)$$

a necessary condition for $\Delta J \geq 0$ is that δJ vanish (noting though ε is small it can be positive or negative).

This argument is true for every $h(x)$ for which $\varepsilon h(x)$ is an admissible variation

Theorem \bar{y} is a local min of $J: \mathcal{A} \rightarrow \mathbb{R}$
Only if

$$\delta J(\bar{y}, h) = 0$$

for all admissible variations $\delta y = \varepsilon h$.

The theorem is true for local max \bar{y} as well.

Theorem Let $g(x) \in C[a, b]$ and suppose

$$(1) \quad \int_a^b g(x)v(x)dx = 0 \quad \forall v \in A^*$$

where A^* is any one of the following spaces

$$A^* = C[a, b]$$

$$A^* = C^n[a, b]$$

$$A^* = \{y : y \in C^n[a, b], y(a) = y(b) = 0\}$$

Then $g(x) \equiv 0$.

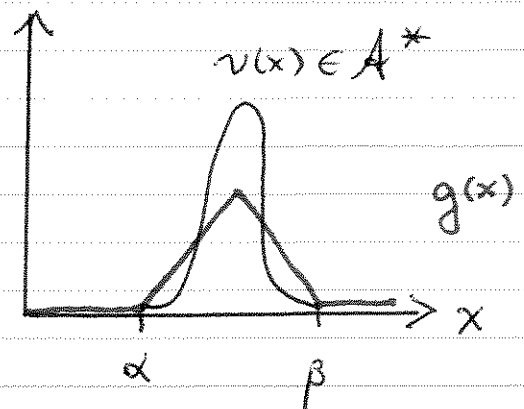
Proof Outline (By contradiction)

Suppose (1) is true but $g(x)$ is not identically zero. Since $g(x)$ is continuous there must be some interval $[\alpha, \beta] \subset [a, b]$ on which it is non zero. Without loss of generality $g(x) > 0$ on $I = [\alpha, \beta]$.

Pick any $v \in A^*$ positive on I but zero elsewhere. Then

$$\int_a^b g(x)v(x)dx = \int_\alpha^\beta g(x)v(x)dx > 0$$

contradicts (1)



Euler Lagrange Equations

Let $J: A \rightarrow \mathbb{R}$ where

$$J(y) \equiv \int_a^b L(x, y(x), y'(x)) dx$$

$$A = \{y : y \in C^2[a, b], y(a) = y_1, y(b) = y_2\}$$

and $L(x, y, y')$ is continuously differentiable in (x, y, y') .

Then every extrema $\bar{y} \in A$ of $J(y)$ satisfy the Euler Lagrange equation

$$(1) \quad L_y(x, \bar{y}, \bar{y}') = \frac{d}{dx} L_{y'}(x, \bar{y}, \bar{y}')$$

Here 'extrema' are all potential minimizers or maximizers of $J(y)$ over A .

The Euler-Lagrange equation (1) taken collectively with the boundary conditions form a nonlinear boundary value problem for extrema

Proof Let $\bar{y} \in A$ be an extrema of J and

$$F(\epsilon) \equiv J(\bar{y} + \epsilon h) = \int_a^b L(x, \bar{y} + \epsilon h, \bar{y}' + \epsilon h') dx$$

We seek to compute $F'(0) = \delta J(\bar{y}, h)$

$$F'(\varepsilon) = \int_a^b \frac{\partial}{\partial \varepsilon} L(x, \bar{y} + \varepsilon h, \bar{y}' + \varepsilon h') dx$$

$$F'(\varepsilon) = \int_a^b L_y(x, y, y') \frac{\partial}{\partial \varepsilon} (\bar{y} + \varepsilon h) + L_{y'}(x, y, y') \frac{\partial}{\partial \varepsilon} (\bar{y}' + \varepsilon h') dx$$

where $y \equiv \bar{y} + \varepsilon h$. Here L_y is the partial of L in y whereas $L_{y'}$ is the partial of L w.r.t. y' .

Evaluating at $\varepsilon = 0$

$$F'(0) = \int_a^b L_y(x, \bar{y}, \bar{y}') h + L_{y'}(x, \bar{y}, \bar{y}') h' dx$$

Integrate the second term by parts

$$F'(0) = \underbrace{L_{y'}(x, \bar{y}, \bar{y}') h \Big|_a^b}_{\text{vanishes since } h(a)=h(b)=0} + \int_a^b (L_y - \frac{d}{dx} L_{y'}) h dx$$

for $\varepsilon h(x)$ to be admissible variation

Conclude

$$F'(0) = \delta J(\bar{y}, h) = \int_a^b \underbrace{\left[L_y(x, \bar{y}, \bar{y}') - \frac{d}{dx} L_{y'}(x, \bar{y}, \bar{y}') \right]}_{g(x)} h(x) dx$$

For $\delta J(\bar{y}, h) = 0$ for all admissible $h \in C^2[a, b]$ the term $g(x) \in C[a, b]$ must vanish. This is the Euler Lagrange Equation!

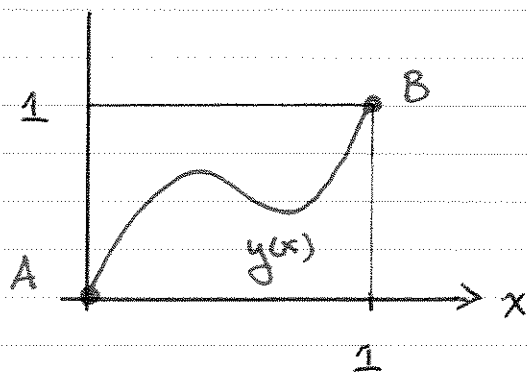
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EXAMPLE Arc length Functional

$$J(y) = \int_0^1 \sqrt{1 + y'(x)^2} dx$$

$$A = \{y : y \in C^2[0,1], y(0) = 0, y(1) = 1\}$$

Seek an extrema $\bar{y} \in A$ that minimizes J



Which \bar{y} minimizes the distance from A to B

Here the Lagrangian $L(x, y, y') = (1 + y'^2)^{1/2}$

Euler-Lagrange equations

$$L_y(x, \bar{y}, \bar{y}') = \frac{d}{dx} L_{y'}(x, \bar{y}, \bar{y}')$$

$$(1) \quad 0 = \frac{d}{dx} (\bar{y}' (1 + \bar{y}'^2)^{-1/2})$$

From which we conclude there is some $c \in \mathbb{R}$ s.t.

$$(2) \quad \bar{y}' (1 + \bar{y}'^2)^{-1/2} = c$$

One could solve eqn (2) for \bar{y}' but one need only note that \bar{y}' is a root of the equation

$$G(\bar{y}') = c$$

where $G(z) = z(1+z^2)^{-1/2}$. In other words,

$$(3) \quad \bar{y}' = A$$

for some constant A . Thus

$$\bar{y}(x) = Ax + B$$

is the general soln of the E-L eqn.

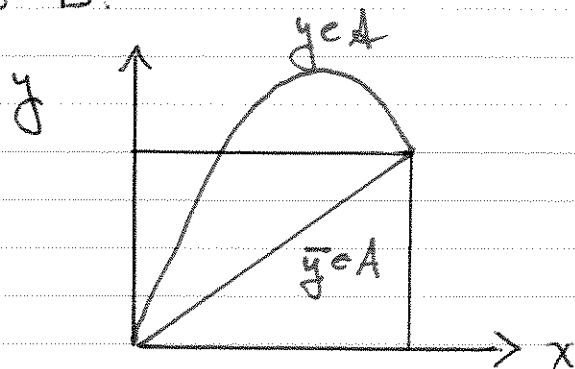
For $\bar{y} \in \mathcal{A}$ it must also satisfy B.C.

$$\left. \begin{array}{l} \bar{y}(0) = B = 0 \\ \bar{y}(1) = A + B = 1 \end{array} \right\} A=1, B=0$$

Hence the sole extrema is

$$\bar{y}(x) = x$$

and the minimizer is the straight line from A to B .



$$J(y) \geq J(\bar{y})$$

First Integrals of Euler Lagrange Eqns

Let

$$J(y) = \int_a^b L(x, y(x), y'(x)) dx$$

For sufficiently smooth Lagrangians $L(x, y, z)$ a necessary condition that $\bar{y} \in A$ extremizes J is that it satisfy the Euler Lagrange equation

$$(1) \quad L_y(x, \bar{y}, \bar{y}') = \frac{d}{dx} L_{y'}(x, \bar{y}, \bar{y}')$$

In general (1) is a second order non-linear differential equation and can be very difficult to solve.

However, certain special cases for solving the Euler Lagrange Equation exist

CASE ONE $L = L(x, y)$ doesn't depend on y'

Then the EL-eqn simplifies to

$$(2) \quad L(x, \bar{y}) = 0$$

which is algebraic for extrema $\bar{y}(x)$

EXAMPLE $L(x, y) = e^y - x^2 y, A = C[1, 2]$

$$L_y(x, \bar{y}) = e^{\bar{y}} - x^2 = 0$$

$$\bar{y}(x) = 2 \ln x$$

CASE TWO $L = L(x, y')$ doesn't depend on y

Then the EL-eqns simplify to

$$0 = \frac{d}{dx} L_{y'}(x, \bar{y}')$$

which implies

$$(3) \quad L_{y'}(x, \bar{y}') = c$$

for some constant c . This is a first order differential equation for $\bar{y}(x)$

EXAMPLE

$$L(x, y') = \frac{1}{3x^2}(y')^3 - x^2 y'$$

Thus $L_{y'}(x, \bar{y}')$ is a first integral and \bar{y} solves

$$L_{y'}(x, \bar{y}') = \frac{1}{x^2}(\bar{y}')^2 - x^2 = c_1$$

for some $c_1 \in \mathbb{R}$. Solve for \bar{y}'

$$\bar{y}'(x) = \pm x \sqrt{c_1 + x^2}$$

Integrate to find general soln

$$\bar{y}(x) = \pm \frac{1}{3}(c_1 + x^2)^{3/2} + c_2$$

where c_2 is some other constant. If $\bar{y} \in A$

$$A = \{y : y \in C^2[1, 2], \bar{y}(1) = 2, \bar{y}(2) = 1\}$$

Then c_1, c_2 must solve 2 Bound. Cond.

$$\bar{y}(1) = \pm \frac{1}{3}(c_1 + 1)^{3/2} + c_2 = 2, \quad \bar{y}(2) = \pm \frac{1}{3}(c_1 + 2)^{3/2} + c_2 = 1$$

CASE THREE $L = L(x, y, y')$ doesn't depend on x

At first the EL-eqns appear intractable

$$(4) \quad L_y(y, y') = \frac{d}{dx} L_{y'}(y, y')$$

However, one can find a first integral for (4)

Theorem If y is a solution of

$$L_y(y, y') = \frac{d}{dx} L_{y'}(y, y')$$

Then

$$(5) \quad L(y, y') - y' L_{y'}(y, y') = c$$

for some constant c .

Thus, instead of solving the second order diff. eqn (4) one solves the first order eqn (5)

Pf/

$$\begin{aligned} \frac{d}{dx} (L - y' L_{y'}) &= \frac{dL}{dx} - y' \frac{d}{dx} L_{y'} - y'' L_{y'} \\ &= \underbrace{L_y y' + L_{y''} y''}_{=0} - y' \frac{d}{dx} L_{y'} - y' L_{y''} \\ &= y' \left(\underbrace{L_y - \frac{d}{dx} L_{y'}}_{=0 \text{ since } y \text{ solves EL-eqn}} \right) \\ &= 0 \end{aligned}$$

Thus $L - y' L_{y'}$ must be a constant \square

EXAMPLE Find extrema for

$$J(y) = \int_0^{\pi/2} (y^2 - y'^2) dx$$

$$A = \{y: y \in C^2[0, \pi/2], y(0) = 0, y(\pi/2) = 1\}$$

Since the Lagrangian doesn't depend on x there is some constant c such that

$$(1) \quad L - y' L_{y'} = c$$

For $L = y^2 - y'^2$ we have for extrema $\bar{y} \in A$

$$(\bar{y}^2 - \bar{y}'^2) - \bar{y}'(-2\bar{y}') = c$$

$$\bar{y}'^2 + \bar{y}^2 = c_1^2 > 0$$

which is separable

$$\frac{d\bar{y}}{dx} = \pm \sqrt{c_1^2 - \bar{y}^2}$$

$$\frac{d\bar{y}}{\sqrt{c_1^2 - \bar{y}^2}} = \pm dx$$

Integrate and invert the $\frac{1}{c_1} \arcsin(\frac{\bar{y}}{c_1})$ term:

$$\bar{y}(x) = A \sin(B + x)$$

for constants A, B that depend on c_1, c_2

Since $\bar{y} \in A$ it satisfies the Bound. Cond.

$$\bar{y}(0) = A \sin B = 0$$

$$\bar{y}\left(\frac{\pi}{2}\right) = A \sin\left(B + \frac{\pi}{2}\right) = 1$$

Can't have $A = 0$ else $\bar{y}(x) \equiv 0 \notin A$. Thus $B = 0$ and $A = 1$

$$\bar{y}(x) = \sin x$$

is the sole extrema.

Remarks Though the first integral

$$L - y' L_{y'} = c$$

leads to a solution, solving the E-Lag Eqns directly lead to the soln more quickly:

Since $L_y = 2y$ and $L_{y'} = -2y'$ the E-L eqns are:

$$L_y = \frac{d}{dx} L_{y'}$$

$$2y = \frac{d}{dx} (-2y') = -2y''$$

Hence

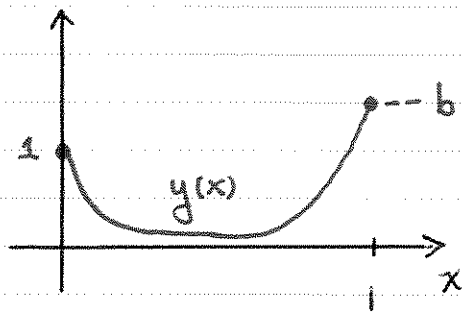
$$\bar{y}'' + \bar{y} = 0$$

$$\bar{y}(0) = 0$$

$$\bar{y}(1) = \frac{\pi}{2}$$

whose soln is clearly $\bar{y} = \sin x$.

EXAMPLE Surface area of revolution



Revolve the graph $y(x)$ about x -axis to form a surface

Given $y(0) = 1$, $y(1) = b$ which $y(x)$ minimizes surface area?

Surprisingly, the answer is not a cone!

$$J(y) = 2\pi \int_0^1 y \sqrt{1 + y'^2} dx$$

is surface area of revolution from calculus.

The admissible set is

$$A = \{y : y \in C^2[0, 1], y(0) = 1, y(1) = b\}$$

Since the Lagrangian

$$L = L(y, y') = y \sqrt{1 + y'^2}$$

does not depend on x , a first integral of the Euler Lagrange eqns is

$$L - y' L_{y'} = c$$

or,

$$y \sqrt{1 + y'^2} - \frac{y y'^2}{\sqrt{1 + y'^2}} = c$$

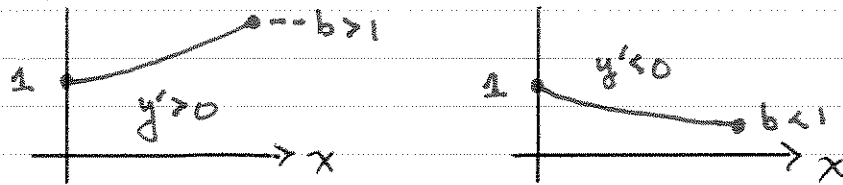
This can be algebraically be simplified to

$$\frac{y}{\sqrt{1+y'^2}} = c$$

Solving for y' we find

$$\frac{dy}{dx} = \pm \sqrt{\left(\frac{y}{c}\right)^2 - 1}$$

If $b > 1$ (without loss of generality) we may assume $y'(x) > 0$ hence "+" sign.



Then

$$\frac{dy}{dx} = + \sqrt{\left(\frac{y}{c}\right)^2 - 1}$$

which is separable. The general soln is

$$y(x) = c \cosh\left(\frac{x}{c} + \mu\right)$$

where $c, \mu \in \mathbb{R}$ are constants.

The boundary condition $y(0) = 1$ implies

$$c = (\cosh \mu)^{-1}$$

so that

$$(1) \quad y(x) = \frac{\cosh(x \cosh \mu + \mu)}{\cosh \mu}$$

Though the constant μ cannot be found explicitly, it can be found implicitly:

$$y(1) = \frac{\cosh(\cosh \mu + \mu)}{\cosh \mu} = b$$

Thus μ is the root of

$$(2) \quad \cosh(\cosh \bar{\mu} + \bar{\mu}) = b \cosh \bar{\mu}$$

One can find, for a given b , the root of (2) numerically and use it in

$$\bar{y}(x) = \frac{\cosh(x \cosh \bar{\mu} + \bar{\mu})}{\cosh \bar{\mu}}$$

as the extrema (minimizer) for the problem.