

Necessary Conditions for Extrema - introduction

A necessary condition for a smooth function $f(x)$ to have a local minimum at x_0 is

$$(1) \quad f'(x_0) = 0$$

where

$$(2) \quad f'(x_0) = \lim_{\Delta x \rightarrow 0} \frac{f(x_0 + \Delta x) - f(x_0)}{\Delta x}$$

We seek an analogous necessary condition for functionals $J: A \rightarrow \mathbb{R}$.

To even be able to define the notions of

(i) local min

(ii) derivatives

for a functional one must first have some sort of definition of distance between functions.

We can't just use (2) since we need to know what $\Delta x \rightarrow 0$ means when Δx is a function, and not a real number as it is in (2).

Linear Spaces V

Are sets with addition $+$ and scalar multiplication definitions satisfying the following axioms

$$*(1) \quad u, v \in V \Rightarrow u + v \in V$$

$$(2) \quad u + v = v + u$$

$$(3) \quad u + (v + w) = (u + v) + w$$

$$(4) \quad \exists 0 \in V \text{ such that } u + 0 = u \quad \forall u \in V$$

$$(5) \quad \forall u \in V \exists (-u) \text{ s.t. } u + (-u) = 0$$

$$(6) \quad \alpha u \in V \quad \text{for all } \alpha \in \mathbb{R}$$

$$(7) \quad \alpha(\beta u) = (\alpha\beta)u \quad \alpha, \beta \in \mathbb{R}$$

$$(8) \quad (\alpha + \beta)u = \alpha u + \beta u$$

$$(9) \quad \alpha(u + v) = \alpha u + \alpha v$$

$$(10) \quad 1u = u \quad \forall u \in V$$

Examples of Linear Spaces

$$V = \mathbb{R} \quad (\text{set of real numbers})$$

$$V = \mathbb{R}^{n \times n} \quad (\text{set of } n \text{ by } n \text{ matrices})$$

$$V = C[0, 1] \quad (\text{set of cont fns on } [0, 1])$$

Example of a space that is not linear

$$V = A = \{y : y \in C[0, 1], y(0) = 0, y(1) = 3\}$$

If $u(x) \in A$ and $v(x) \in A$ then $u + v \notin V$ since $u(1) + v(1) = 6 \neq 3$. This set is not closed under addition

Normed Linear Spaces

Many function spaces are normed linear spaces which have a notion of distance associated with them

Defn A linear space V is a normed linear space if it has a norm $\| \cdot \|$ satisfying

$$(1) \quad \|y\| = 0 \iff y = 0$$

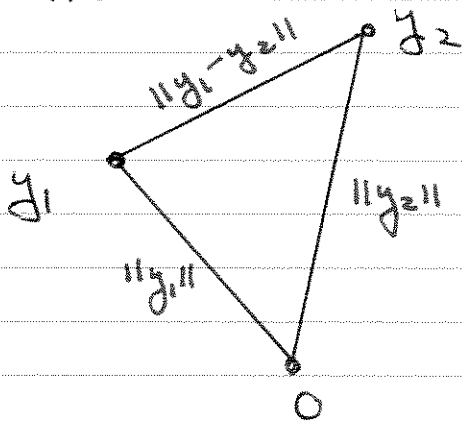
$$(2) \quad \|\alpha y\| = |\alpha| \|y\| \quad \alpha \in \mathbb{R}, y \in V$$

$$(3) \quad \|y_1 + y_2\| \leq \|y_1\| + \|y_2\| \quad \forall y_1, y_2 \in V$$

The last condition is called the triangle inequality and is used to define the distance between elements:

$$(4) \quad d(y_1, y_2) = \|y_1 - y_2\|$$

Using this defn of distance mimics that of \mathbb{R}^3



EXAMPLES OF NORMED LINEAR FUNCTION SPACES

Let $V = C[0, 1]$. Then each of the following are norms for V

$$\|y\|_{\infty} = \max_{x \in [0, 1]} |y(x)| \quad \text{Strong norm}$$

$$\|y\|_1 = \int_0^1 |y(x)| dx \quad L^1 \text{ norm}$$

$$\|y\|_2 = \left(\int_0^1 |y(x)|^2 dx \right)^{1/2} \quad L^2 \text{ norm}$$

Note in particular that $\|y\| = 0$ in all the above implies $y(x) \equiv 0$, the zero function, since $y(x)$ must be continuous.

As an example of computing distances.

$$y_1(x) = x \quad y_2(x) = -x$$

then $y_1(x) - y_2(x) = 2x$ and

$$\|y_1 - y_2\|_{\infty} = \max_{x \in [0, 1]} |2x| = 2$$

$$\|y_1 - y_2\|_1 = \int_0^1 2x dx = 1$$

$$\|y_1 - y_2\|_2 = \left(\int_0^1 (2x)^2 dx \right)^{1/2} = \frac{2}{\sqrt{3}}$$

Continuous Functionals

Defn A real valued function $f(x)$ is continuous at x_0 if for every $\varepsilon > 0$ there exists a $\delta > 0$ such that

$$|x - x_0| < \delta \Rightarrow |f(x) - f(x_0)| < \varepsilon$$

The definition for functionals on normed linear spaces is similar

Defn Let $A \subset V$ where V is a normed linear space. Let $J: A \rightarrow \mathbb{R}$. The functional J is continuous at $y_0 \in A$ if for every $\varepsilon > 0$ there exists a $\delta > 0$ such that

$$\|y - y_0\| < \delta \Rightarrow |J(y) - J(y_0)| < \varepsilon$$

EXAMPLE $A = C[0, 1]$, $J(y) = \int_0^1 y(x) dx$

Is continuous functional using the strong norm

$$\begin{aligned} |J(y) - J(y_0)| &= \left| \int_0^1 y(x) - y_0(x) dx \right| \\ &\leq \int_0^1 |y(x) - y_0(x)| dx \\ &\leq \|y - y_0\|_{\infty} = \max_{x \in [0, 1]} |y(x) - y_0(x)| \end{aligned}$$

Hence if $\delta = \varepsilon$ we'll have $\|y - y_0\|_{\infty} < \varepsilon \Rightarrow$

$$|J(y) - J(y_0)| < \varepsilon$$

Local and Global Minima for $J(y)$

Let $J: \mathcal{A} \rightarrow \mathbb{R}$ for some admissible set \mathcal{A} .

Defn \bar{y} is a global minima for J on \mathcal{A} iff

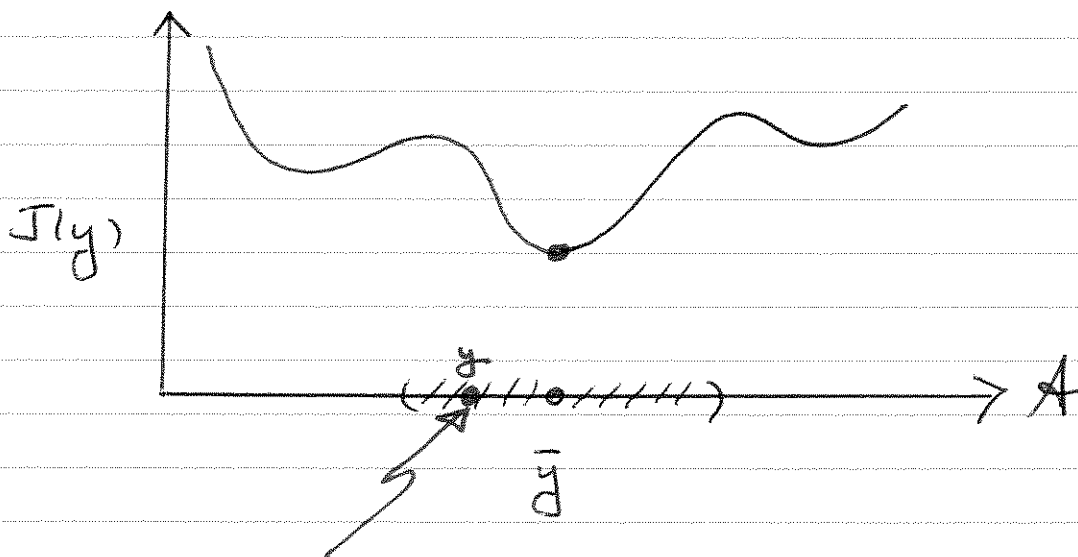
$$J(\bar{y}) \leq J(y) \quad \forall y \in \mathcal{A}.$$

This definition does not require any notion of distance between y and \bar{y} .

Defn Let $\mathcal{A} \subset V$ where V is a normed linear space and $J: \mathcal{A} \rightarrow \mathbb{R}$.
 \bar{y} is a local minima for J if there exists a $\delta > 0$ such that

$$\|y - \bar{y}\| < \delta \Rightarrow J(\bar{y}) \leq J(y)$$

Here $J(y)$ is larger for y "near" \bar{y}



Some y near \bar{y} , i.e. $\|y - \bar{y}\| < \delta$

EXAMPLE Explicit Local Min Example

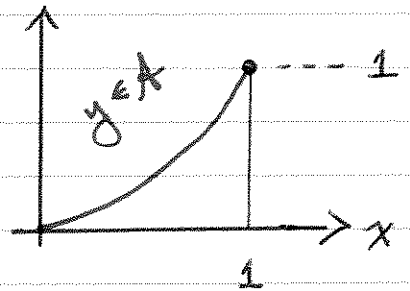
$$J(y) \equiv 30 \int_0^1 (1 + y^2 + y'^2) dx$$

where the admissible set will be quadratics thru $(0,0)$ and $(1,1)$

$$A = \{y : y(x) = ax(x-1) + x\}$$

Note that for any $a \in \mathbb{R}$

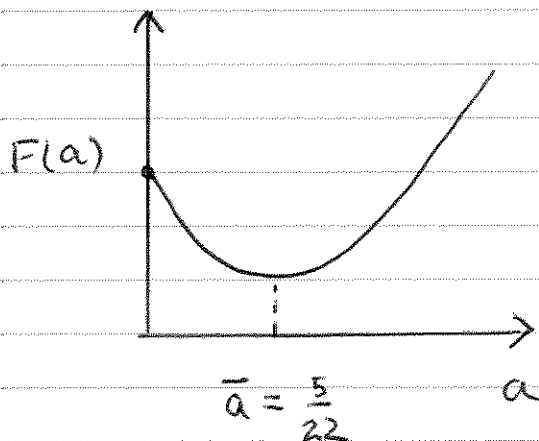
$$y(0) = 0 \quad y(1) = 1$$



This is a one parameter family of admissible functions. A is a very restrictive and small set of functions. Nevertheless we can illustrate the local min idea.

$$J(y) = 11a^2 - 5a + 70 = F(a), \quad y \in A$$

which we can plot noting $F'(a) = 22a - 5$



At least over the $y \in A$, the smallest $J(y)$ can be is

$$J(\bar{y}) = \frac{3055}{44}$$

$$\text{for } a = \bar{a} = \frac{5}{22}$$

Admissible Variations

Suppose $\bar{y} \in A$ is a candidate for a local min or max of $J(y)$.

One might test this by asking if

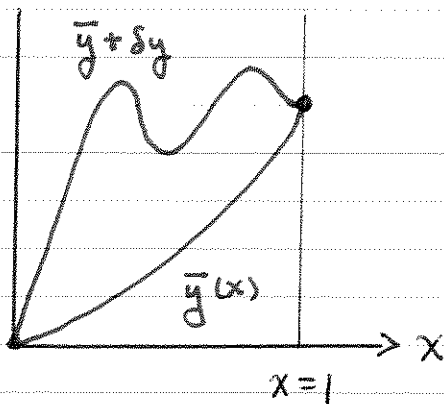
$$J(\bar{y}) \leq J(\bar{y} + \delta y)$$

where $\delta y \in V$ is some admissible variation.
 δy is admissible variation only if

$$\bar{y} + \delta y \in A$$

Not all variations are admissible.

EX $A = \{y : y \in C[0,1], y(0) = 0, y(1) = 1\}$



Here the admissible variation is a function $\delta y(x)$

Given $\bar{y}(1) = 1$, any admissible variation must have $\delta y(1) = 0$ so that $\bar{y}(1) + \delta y(1) = 1$, and that $\bar{y} + \delta y \in A$.

In fact the set A^* of all admissible variations is

$$A^* = \{\delta y : \delta y \in C[0,1], \delta y(0) = 0, \delta y(1) = 0\}$$

A and A^* are not the same sets!

First Variation (Gateaux Derivative)

Let $A \subset V$ where V is a normed linear space. Also let $J: A \rightarrow \mathbb{R}$.

Further let

$$\bar{y}(x) \in A$$

and that for some fixed $h(x) \in V$

$$\bar{y}(x) + \varepsilon h(x) \in A \quad (\text{Admissible})$$

for ε small.

Define

$$F(\varepsilon) = J(\bar{y} + \varepsilon h)$$

If $F(\varepsilon)$ is sufficiently smooth in ε

$$\Delta J \equiv F(\varepsilon) - F(0) = F'(0)\varepsilon + o(\varepsilon)$$

since it has a Taylor Series in ε .

We use this to define the "derivative" or first variation of J at \bar{y} .

Definition Let $J: A \rightarrow \mathbb{R}$, $\bar{y} \in A$ and suppose $\bar{y} + \varepsilon h \in A$ for all $\varepsilon \in \mathbb{R}$ sufficiently small.

The first variation $\delta J(\bar{y}, h)$ of J at \bar{y} in the direction h is

$$\delta J(\bar{y}, h) = F'(0) = \left. \frac{d}{d\varepsilon} J(\bar{y} + \varepsilon h) \right|_{\varepsilon=0}$$

(if it exists).

EXAMPLE Define $J(y) = y(0)^2$ $A = C[0, 1]$

$$J(y + \varepsilon h) = (y(0) + \varepsilon h(0))^2$$

$$F(\varepsilon) = J(y + \varepsilon h) = y(0)^2 + 2\varepsilon y(0)h(0) + \varepsilon^2 h(0)^2$$

Thus

$$F'(\varepsilon) = 2y(0)h(0) + 2\varepsilon h(0)$$

Evaluating at $\varepsilon = 0$ we arrive at

$$\delta J(y, h) = 2y(0)h(0)$$

Is much like the directional derivative of $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$. The "direction" is the function h .

EXAMPLE $J(y) = \int_0^1 (1 + y'(x)^2) dx$ on

$$\mathcal{A} = \{y : y \in C^1[0,1], y(0) = 0, y(1) = 1\}$$

Some admissible variations are

$$\delta y(x) = \varepsilon h(x) = \varepsilon x(1-x)$$

so that for any $\bar{y} \in \mathcal{A}$, $\bar{y} + \delta y \in \mathcal{A}$ as well.

For clarity, suppose

$$\bar{y}(x) = x$$

$$\delta y(x) = \varepsilon h(x)$$

Then

$$F(\varepsilon) = J(\bar{y} + \varepsilon h) = \int_0^1 [1 + (\bar{y}'(x) + \varepsilon h'(x))^2] dx$$

After some calculations

$$F(\varepsilon) = J(\bar{y} + \varepsilon h) = 2 + \frac{1}{3} \varepsilon^2$$

so that

$$\delta J(\bar{y}, h) = \left. \frac{d}{d\varepsilon} \left(2 + \frac{1}{3} \varepsilon^2 \right) \right|_{\varepsilon=0} = 0$$

Necessary Conditions for local Min (Max)

If \bar{y} is a local min of J then

$$(i) \quad \Delta J = J(\bar{y} + \epsilon h) - J(\bar{y}) \geq 0$$

for all admissible variations $\delta y = \epsilon h(x)$

In this setting $y = \bar{y} + \epsilon h$ and \bar{y} are near each other if ϵ is small since

$$\|y - \bar{y}\| = \|\epsilon h\| = \epsilon \|h\| \rightarrow 0 \quad \text{as } \epsilon \rightarrow 0.$$

Since

$$\Delta J = \delta J(\bar{y}, h) \epsilon + o(\epsilon)$$

a necessary condition for $\Delta J \geq 0$ is that δJ vanish (noting though ϵ is small it can be positive or negative).

This argument is true for every $h(x)$ for which $\epsilon h(x)$ is an admissible variation

Theorem \bar{y} is a local min of $J: \mathcal{A} \rightarrow \mathbb{R}$
only if

$$\delta J(\bar{y}, h) = 0$$

for all admissible variations $\delta y = \epsilon h$.

The theorem is true for local max \bar{y} as well.

Theorem Let $g(x) \in C[a, b]$ and suppose

$$(1) \quad \int_a^b g(x)v(x)dx = 0 \quad \forall v \in A^*$$

where A^* is any one of the following spaces

$$A^* = C[a, b]$$

$$A^* = C^n[a, b]$$

$$A^* = \{y : y \in C^n[a, b], y(a) = y(b) = 0\}$$

Then $g(x) \equiv 0$.

Proof Outline (By contradiction)

Suppose (1) is true by $g(x)$ is not identically zero. Since $g(x)$ is continuous there must be some interval $[\alpha, \beta] \subset [a, b]$ on which it is non zero. Without loss of generality $g(x) > 0$ on $I = [\alpha, \beta]$.

Pick any $v \in A^*$ positive on I but zero elsewhere. Then

$$\int_a^b g(x)v(x)dx = \int_\alpha^\beta g(x)v(x)dx > 0$$

contradicts (1)

