

Initial Layer Problems

In initial value problems initial (rather than boundary) conditions are stipulated.

For instance

$$(1) \quad \epsilon y'' = f(y, y', \epsilon)$$

$$(2) \quad y(0) = A$$

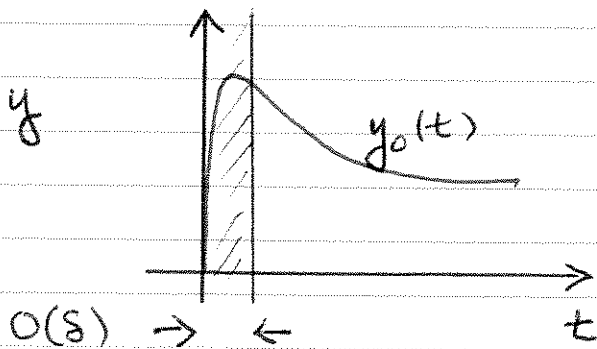
$$(3) \quad y'(0) = B$$

is a class of such second order IVP. Here the $\epsilon y''$ can be large if the derivative y' is large — making the problem singular.

Here an outer expansion $y(x, \epsilon) = y_0(x) + o(1)$ yields the leading order problem

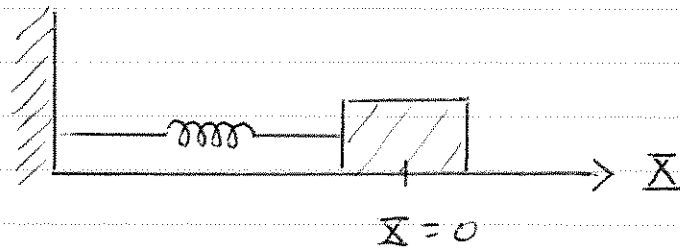
$$(4) \quad 0 = f(y_0, y_0', 0)$$

Since this is a first order diff eqn, its solution can't (in general) satisfy both the initial conditions (1)-(2).



Thus we expect initial (inner) layers.

Damped Spring Problem



Mass m at position x at time T
acted on by two forces

$$F_{\text{spring}} = -kx \quad (\text{Hooke's Law})$$

$$F_{\text{friction}} = -a \frac{dx}{dt}$$

In dimensional form Newton's Laws \Rightarrow

$$(1) \quad m \frac{d^2x}{dT^2} + a \frac{dx}{dT} + kx = 0$$

Will assume initially mass is at rest at its equilibrium position $x=0$ and an impulse (momentum) of magnitude I is applied

$$(2) \quad x(0) = 0$$

$$(3) \quad m \dot{x}(0) = I$$

Nondimensionalize model

There are several nondimensionalizations (nonunique). We present one here

$$y = \frac{x}{x^*} \quad t = \frac{\tau}{\tau^*}$$

Differential Eqn becomes

$$\frac{m}{k(\tau^*)^2} \frac{d^2 y}{dt^2} + \frac{a}{k\tau^*} \frac{dy}{dt} + y = 0$$

↑
choose τ^* to make
this equal one

For $\tau^* = a/k$ we get

$$(4) \quad \varepsilon y'' + y' + y = 0$$

where the dimensionless parameter ε is

$$(5) \quad \varepsilon \equiv \frac{mk}{a^2}$$

Now we nondimensionalize initial conditions.

Independent of the choice of x^*

$$(6) \quad y(0) = 0$$

The as yet to be defined constant x^* does enter in the other initial condition.

we have

$$\left(\frac{m \bar{X}^*}{\Gamma^*} \right) y'(0) = I$$

or for $\Gamma^* = a/k$, $\varepsilon = mk/a^2$

$$y'(0) = \frac{I a}{m k \bar{X}^*}$$

$$(7) \quad \boxed{y'(0) = \frac{1}{\varepsilon} \left(\frac{I \bar{X}^*}{a} \right)}$$

We will choose \bar{X}^* so that

$$(8) \quad \varepsilon y'(0) = \alpha \quad \alpha = \frac{I \bar{X}^*}{a}$$

where α is some dimensionless parameter. Its significance we will address later.

Model Problem

$$(9) \quad \varepsilon y'' + y' + y = 0$$

$$(10) \quad y(0) = 0$$

$$(11) \quad \varepsilon y'(0) = \alpha$$

Has a known exact solution.

The exact solution is

$$y(x, \varepsilon) = c(\varepsilon) \left(e^{\lambda_+(\varepsilon)t} - e^{\lambda_-(\varepsilon)t} \right)$$

where

$$\lambda_{\pm}(\varepsilon) = \frac{1}{2\varepsilon} (-1 \pm \sqrt{1-4\varepsilon})$$

$$c(\varepsilon) = \frac{\alpha}{\sqrt{1-4\varepsilon}}$$

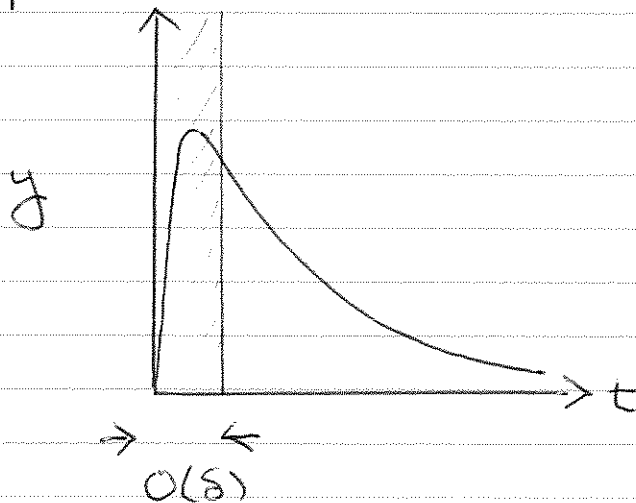
None of this nondimensionalization or exact solution depends on knowing the magnitudes of ε, α

Overdamped Spring Assumption

$$\varepsilon = \frac{mk}{a^2} \ll 1 \quad \alpha = O(1)$$

where $\varepsilon \ll 1$ since friction coefficient a is large.

In this instance the exact solution has a layer



Matched asymptotic approximation

$$(1) \quad \varepsilon y'' + y' + y = 0, \quad t > 0$$

$$(2) \quad y(0) = 0 \quad \varepsilon y'(0) = \alpha$$

where $0 < \varepsilon \ll 1$ and $\alpha = O(1)$

Outer solution $y(t, \varepsilon) = y_0(t) + o(1)$

$$y_0' + y_0 = 0$$

satisfies no initial conditions since it is an approximation valid only away from the layer at $t = 0$.

$$y_0(t) = A e^{-t}$$

will find constant A from matching condition.

Inner solution

$$y(t, \varepsilon) = \overline{Y}(\tau, \varepsilon) \quad \tau = \frac{t}{\delta(\varepsilon)}, \quad \delta \ll 1$$

yields

$$\frac{\varepsilon}{\delta^2} \overline{Y}'' + \frac{1}{\delta} \overline{Y}' + \overline{Y} = 0$$

$$\textcircled{1} \sim \textcircled{2} \gg \textcircled{3}$$

Hence choose

$$\delta(\varepsilon) = \varepsilon$$

yields (exactly)

$$(3) \quad \underline{Y}'' + \underline{Y}' + \varepsilon \underline{Y} = 0$$

More importantly the initial condition $\varepsilon y'(0) = \alpha$ becomes

$$(4) \quad \varepsilon y'(0) = \underline{Y}'(0) = \alpha$$

Thus $\underline{Y}(\varepsilon, \varepsilon) = \underline{Y}_0(\tau) + o(1)$ yields the leading order inner problem

$$(5) \quad \underline{Y}_0'' + \underline{Y}_0' = 0$$

$$(6) \quad \underline{Y}_0(0) = 0 \quad \underline{Y}_0'(0) = \alpha$$

only if $\alpha = O(1)$. The inner soln $\underline{Y}_0(\tau)$ is

$$\underline{Y}_0(\tau) = \alpha(1 - e^{-\tau}) \quad \tau = \frac{t}{\varepsilon}$$

Matching

Note $\tau \rightarrow +\infty$ away from layer

$$M = \lim_{\tau \rightarrow +\infty} \underline{Y}_0(\tau) = \lim_{t \rightarrow 0^+} y_0(t)$$

$$M = \alpha = A$$

Hence the outer soln is now complete

$$y_0(t) = \alpha e^{-t}$$

Uniform Approximation

$$y_u(t, \varepsilon) = y_0(t) + \underline{Y}_0\left(\frac{t}{\varepsilon}\right) - M$$

$$y_u(t, \varepsilon) = \alpha \left(e^{-t} - e^{-t/\varepsilon} \right)$$

is a very simple result.

Issues Recall dimensionless parameters

$$\varepsilon = \frac{mk}{a^2}$$

$$\alpha = \frac{I \bar{x}^*}{a}$$

These dimensionless parameters can be independently small or large. For instance, if a is very large we expect $\varepsilon \ll 1$ but then why not $\alpha \ll 1$? Even if a is large the dimensional quantity I may large be as well making $\alpha \approx 1$ for some $x^* \approx 1$.

So even if $\varepsilon \ll 1$ we have cases of α small, α "order one" and α large.

Turns out α merely determines the magnitude of the layer. Why?

Set
$$z(t) = \frac{1}{\alpha} y(t)$$

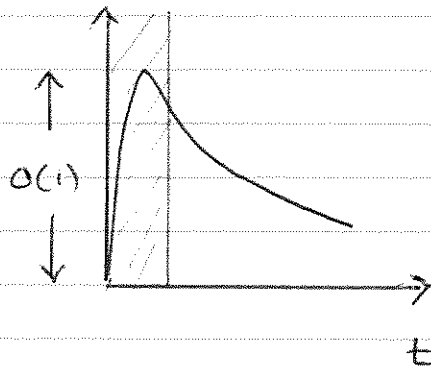
then

$$(1) \quad \epsilon z'' + z' + z = 0$$

$$(2) \quad z(0) = 0$$

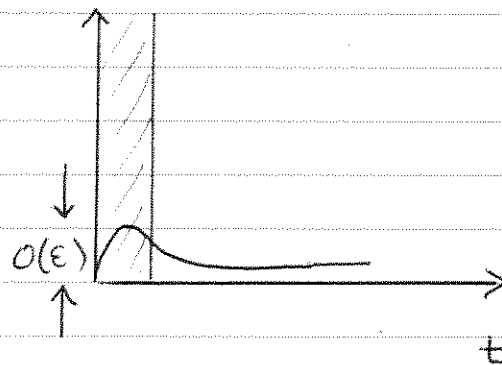
$$(3) \quad \epsilon z'(0) = 1$$

which has the same uniformly valid soln as if $\epsilon = 1$



$$\epsilon = O(1)$$

large impulse
 I



$$\epsilon = O(\epsilon)$$

small impulse
 I

$y(t)$

Second Issue

The way one nondimensionalizes can affect how you solve a problem. Suppose as before we chose

$$\pi^* = a/k$$

Then the dimensionless differential equation is still

$$\varepsilon y'' + y' + y = 0$$

with the same ε . And, $y(0) = 0$ still.

One could have written $\bar{x}'(0) = I/m$ as

$$\left(\frac{m \bar{x}^*}{I} \right) y'(0) = I$$

$$y'(0) = \frac{I a}{m k \bar{x}^*}$$

then chosen $\bar{x}^* = (I a)/(m k)$ so that $y'(0) = 1$.
For this different scaling

$$(1) \quad \varepsilon y'' + y' + y = 0$$

$$(2) \quad y(0) = 0 \quad y'(0) = 1$$

The inner problem for this new problem is different

$$y(t, \varepsilon) = \bar{Y}(\bar{t}, \varepsilon) \quad \bar{t} = \frac{t}{\delta(\varepsilon)}$$

as before yields (for $\delta = \varepsilon$)

$$(3) \quad \bar{Y}'' + \bar{Y}' + \varepsilon \bar{Y} = 0$$

$$(4) \quad \bar{Y}(0) = 0 \quad \frac{1}{\varepsilon} \bar{Y}'(0) = 1$$

If we now expand $\bar{Y}(\tau, \varepsilon)$:

$$\bar{Y}(\tau, \varepsilon) = \bar{Y}_0(\tau) + \varepsilon \bar{Y}_1(\tau) + O(\varepsilon^2)$$

we find

$$O(1) \quad \bar{Y}_0'' + \bar{Y}_0' = 0, \quad \bar{Y}_0(0) = \bar{Y}_0'(0) = 0$$

$$O(\varepsilon) \quad \bar{Y}_1'' + \bar{Y}_1' = -\bar{Y}_0, \quad \bar{Y}_1(0) = 0, \bar{Y}_1'(0) = 1$$

where, in particular, the initial conditions we derived from

$$\begin{aligned} \frac{1}{\varepsilon} \bar{Y}'(0, \varepsilon) &= \frac{1}{\varepsilon} (\bar{Y}_0'(0) + \varepsilon \bar{Y}_1'(0) + O(\varepsilon^2)) \\ &= \frac{1}{\varepsilon} \bar{Y}_0'(0) + \bar{Y}_1'(0) + O(\varepsilon) \\ &= 1 \end{aligned}$$

So that $\bar{Y}_0'(0) = 0, \bar{Y}_1'(0) = 1$ etc.

Solution of $O(1)$ problem is $\bar{Y}_0(\tau) \equiv 0$
thus

$$\bar{Y}_1'' + \bar{Y}_1' = 0 \quad \bar{Y}_1(0) = 0 \quad \bar{Y}_1'(0) = 1$$

and $\bar{Y}_1(\tau) = 1 - e^{-\tau}$. Then $\bar{Y} = \varepsilon \bar{Y}_1(\tau) + o(\varepsilon)$
must be matched to a scaled outer
soln $y(t, \varepsilon) = \varepsilon y_0(t) + o(1)$.

Point is, everything is nastier if one makes a bad choice for nondimensionalization.