

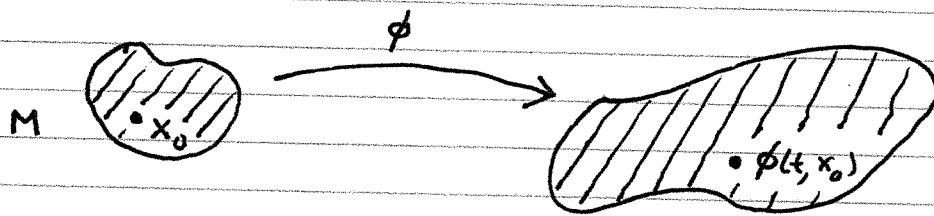
## Positive Invariance and Trapping Regions

Recall the flow function  $\phi(t, x_0)$  for  $\dot{x} = f(x)$  satisfies

$$(1) \quad \frac{\partial \phi}{\partial t} = f(\phi)$$

$$(2) \quad \phi(0, x_0) = x_0$$

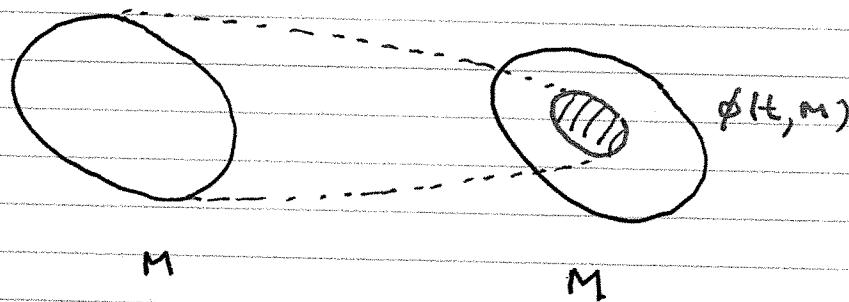
One can examine the image of sets  $M$  under the flow  $\phi$



Definition A set  $M$  is positively invariant if

$$\phi(t, M) \subset M \quad \forall t \geq 0$$

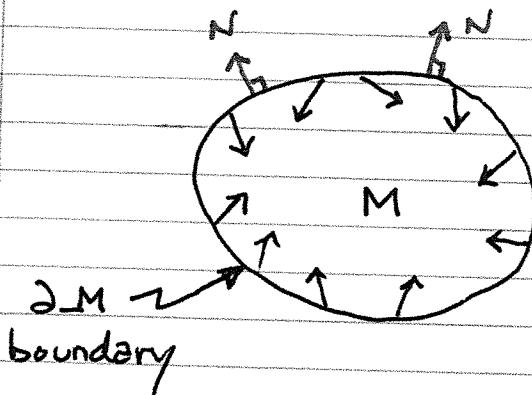
If additionally it is closed and bounded then  $M$  is called a trapping region



One way to check if a set  $M$  is a trapping region is to show

$$f \cdot N < 0 \quad \forall x \in \partial M$$

where  $N$  is the outward normal on the boundary  $\partial M$  of the region  $M$ .



Illustrates a case where  $f$  is always pointing into the interior of  $M$  and

$$f \cdot N < 0 \quad \forall x \in \partial M$$

### EXAMPLE

$$\begin{aligned} \dot{x} &= -xy - x \\ \dot{y} &= -y \end{aligned}$$

$\partial M$  is the unit circle and  $M$  its interior.

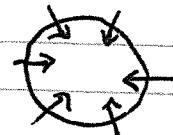
$\partial M$  is parametrized by  $(x, y) = (\cos \theta, \sin \theta)$  and  $N = (\cos \theta, \sin \theta)$  as well.

$$F(\theta) = -(xy + x, y) \cdot N \quad \downarrow \text{algebra}$$

$$F(\theta) = -(1 + \sin \theta \cos^2 \theta) < 0$$

Hence  $M$  is a trapping region.

Note  $M$  contains one fixed pt



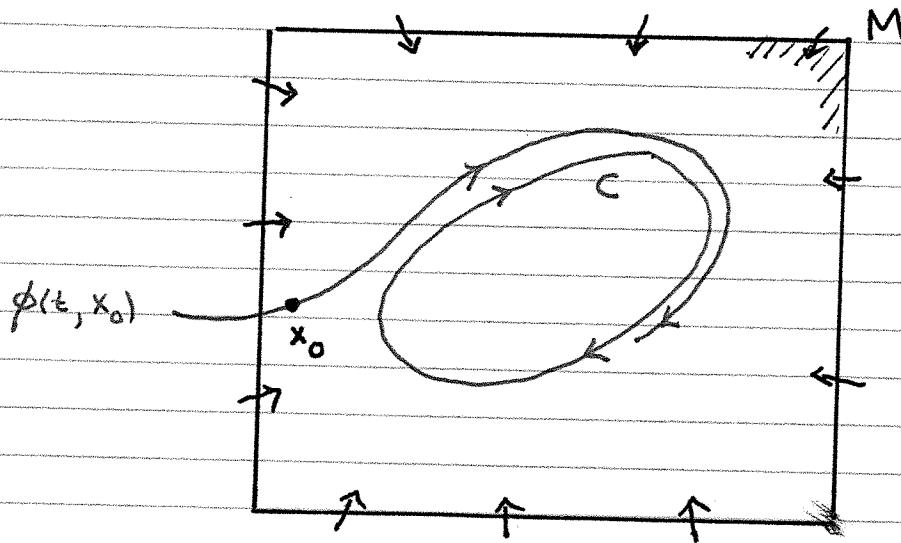
## Poincaré-Bendixson Theorem

Suppose  $M$  is a trapping region for  $\dot{x} = f(x)$  which contains no fixed points. Then there exists some periodic orbit  $C$  contained entirely in  $M$ .

PF : Difficult. See Perko (1991: pg 227) for details.  
May be many  $C$  in  $M$ .

### Remarks

- (1) There are more general versions (later) where  $M$  may contain a finite number of fixed points. The conclusion in such generalizations are more complex.
- (2) Not only does  $C$  exist, but  $\phi(t, x_0)$  "approaches"  $C$  as  $t \rightarrow \infty$ . "Approach" needs a more careful definition



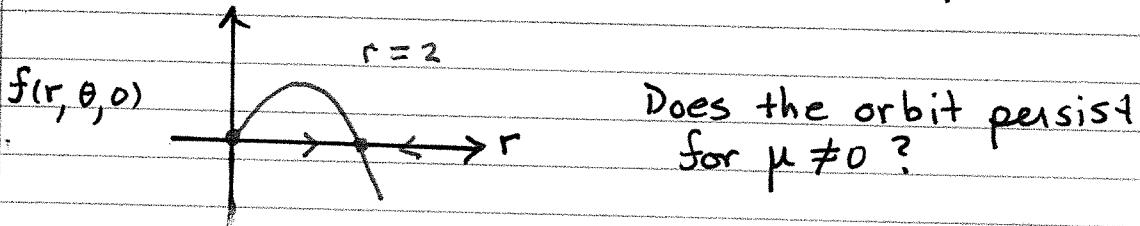
$C$  = periodic orbit

EXAMPLEAnnular trapping region

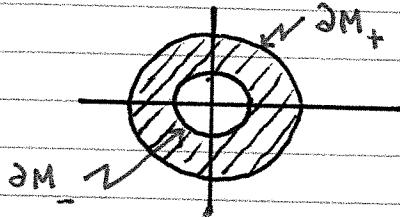
$$(1) \quad \dot{r} = r(4-r^2) + \mu r \sin \theta = f(r, \theta, \mu)$$

$$(2) \quad \dot{\theta} = 1$$

When  $\mu=0$  this system has a stable periodic orbit.



Annular trapping region  $M$ . origin sole fx pt.



Want (for trapping)

$$\begin{aligned} \dot{r} > 0 & \text{ on } \partial M_- \\ \dot{r} < 0 & \text{ on } \partial M_+ \end{aligned}$$

On  $\partial M_-$  we need a radius  $r$  small enough so  $f > 0$

$$r(4-r^2) > -\mu r \sin \theta$$

Sufficient to choose  $r$  so that  $r(4-r^2) > +\mu r \geq -\mu r \sin \theta$

$$\underbrace{r(4-\mu-r^2)}_{> 0} > 0$$

True if  $r > \sqrt{4-\mu}$  on inner circle  $\partial M_-$ .

Similarly  $r < \sqrt{4+\mu}$  on outer circle  $\partial M_+$  so  $f < 0$   
Thus if these radii are satisfied  $M$  is indeed  
a trapping region. By Poincaré-Bendixson  
there is at least one periodic orbit  $C$   
inside  $M$ .

EXAMPLEPolar generalizations

$$\begin{aligned}\dot{r} &= f(r) + \mu G(r, \theta) \\ \dot{\theta} &= 1\end{aligned}$$

where  $G$  is uniformly bounded

$$|G(r, \theta)| < K \quad \forall (r, \theta)$$

and the graph of  $f(r)$  qualitatively is



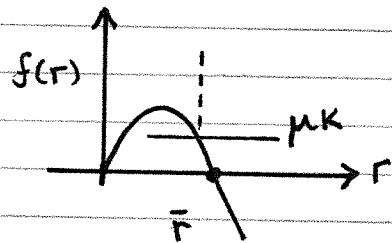
Same annular  $M$ . On inner boundary  $\partial M_-$  need

$$f(r) > -\mu G(r, \theta)$$

Sufficient that we pick  $r$  such that

$$f(r) > \mu K$$

which is true for suff. small  $\mu$   
Similar for  $\partial M_+$  so  $M$  is a  
trapping region.

EXAMPLE

$$\begin{aligned}\dot{r} &= r(1-r) + \frac{\mu r^2 \sin^2 \theta}{1+r^2} \\ \dot{\theta} &= 1\end{aligned}$$



Bounded so we can find an annular trapping region and system has period orbit.

## Omega limit sets

Below  $\phi(t, x_0)$  is the flow function for

$$\dot{x} = f(x) \quad x(0) = x_0$$

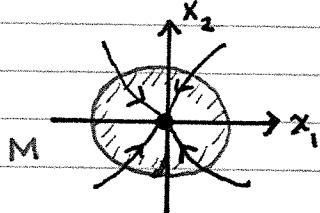
Defn:  $p$  is an w-limit point of  $x_0$  if there is a sequence of times  $\{t_i\}$  with  $t_i \rightarrow \infty$  such that

$$\phi(t_i, x_0) \rightarrow p \quad \text{as } i \rightarrow \infty$$

The w-limit set  $\omega(x_0)$  of  $x_0$  is

$$\omega(x_0) \equiv \{p : p \text{ an w-limit point}\}$$

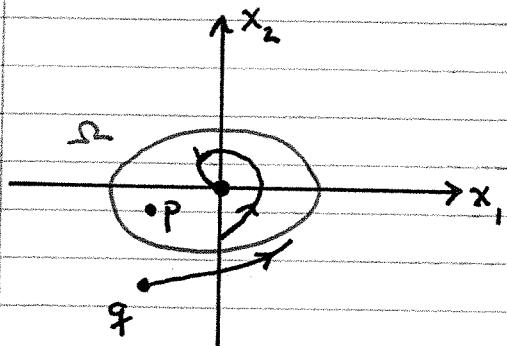
### EXAMPLE Stable node



$M$  is positively invariant

$$\omega(x_0) = \{(0,0)\} \quad \forall x_0 \in M$$

### EXAMPLE Half stable periodic orbit



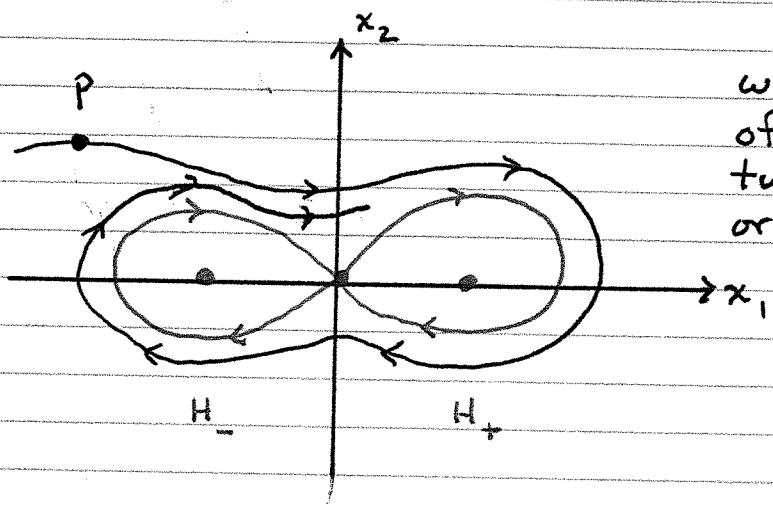
Limit cycle  $\Omega$ , stable origin

$$\omega(p) = \vec{0}$$

$$\omega(q) = \Omega$$

### EXAMPLE

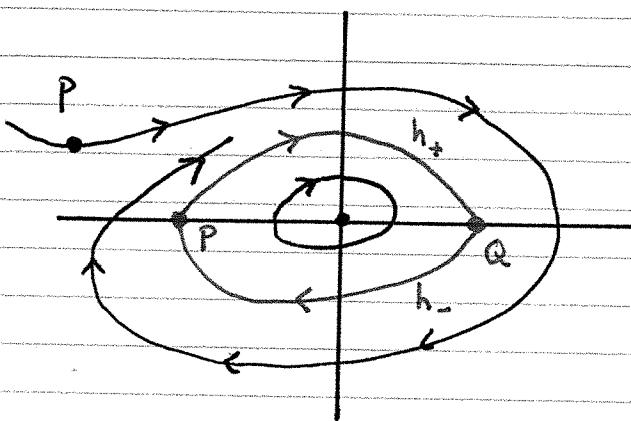
### Homoclinic orbit(s)



$\omega(p)$  is the union  
of the origin and  
two homoclinic  
orbits  $H_{\pm}$

### EXAMPLE

### Heteroclinic cycle



$\omega(p)$  is the union  
of the two  
heteroclinic orbits  
 $h_{\pm}$  and fixed pts  
 $P$  and  $Q$

## Poincare - Bendixson (General)

Suppose  $M$  is a trapping region for

$$\dot{x} = f(x) \quad x(0) = x_0$$

which contains a finite number of isolated fixed points  $\bar{x}_i, i=1, 2, \dots, n$ . Then for each  $x_0 \in M$  one of the following is true:

- (a)  $\omega(x_0)$  is a fixed point
- (b)  $\omega(x_0)$  is a periodic orbit in  $M$
- (c)  $\omega(x_0)$  consists of a finite number of fixed points, homoclinic orbits and/or heteroclinic orbits.

Remark: The theorem implies that planar systems can't have "chaos". At most

- (i) fixed points
- (ii) periodic orbits
- (iii) homoclinic cycles
- (iv) heteroclinic cycles