

Asymptotic approximations of oscillations

There are several kinds of problems

Second order eqns

$$y'' + F(y, y', t, \varepsilon) = 0 \quad y(0) = a \quad y'(0) = b$$

Systems

$$y' = F(y, t, \varepsilon) \quad y(0) = a \quad y \in \mathbb{R}^n$$

Systems in Standard Form

$$y' = \omega + \varepsilon F(y, t, \varepsilon) \quad y(0) = a \quad y \in \mathbb{R}^n$$

Perturbed Hamiltonian Systems $H = H(p, q, t, \varepsilon)$

$$\dot{p}_i = -\frac{\partial H}{\partial q_i} + \varepsilon G_i(q, p, t)$$

$$\dot{q}_i = \frac{\partial H}{\partial p_i} + \varepsilon H_i(q, p, t)$$

for $i = 1, \dots, n$.

If for $F|_{\varepsilon=0}$ the system is linear the system is often said to be weakly nonlinear.

If the system is Hamiltonian for $G_i = H_i = 0$ it is said to be nearly Hamiltonian.

Regular expansions such as

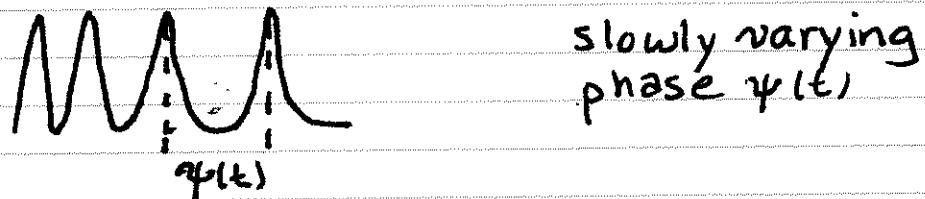
$$y(t, \varepsilon) = y_0(t) + \varepsilon y_1(t) + O(\varepsilon^2)$$

yield approximations valid for $t \in [0, T]$, $T = O(1)$.

Such solutions do not account for cumulative effects for long times such as

$$t = O\left(\frac{1}{\varepsilon^n}\right) \quad n \geq 1$$

Two cumulative effects are



Broadly there are two goals

- Find approximations $\tilde{Y}_0(t, \tilde{t})$, $\tilde{t} = \varepsilon t$ slowtime that capture cumulative effects s.t

$$y(t, \varepsilon) - \tilde{Y}_0(t, \tilde{t}) = O(\varepsilon) \quad t = O(\varepsilon^{-1})$$

- Identify (stable) periodic attractors such as limit cycles and dynamics on tori.

EXAMPLE Failure in regular expansions

$$y'' + \varepsilon y' + y = 0$$

$$y(0) = 0 \quad y'(0) = 1$$

Exact solution

$$y(t, \varepsilon) = \frac{1}{\sqrt{1 - \varepsilon^2/4}} e^{-\varepsilon t/2} \sin(t\sqrt{1 - \varepsilon^2/4})$$

Regular expansion

$$y(t, \varepsilon) = y_0(t) + \varepsilon y_1(t) + O(\varepsilon^2)$$

yields

$$O(1) \quad y_0'' + y_0 = 0 \quad y_0(0) = 0 \quad y_0'(0) = 1$$

$$O(\varepsilon) \quad y_1'' + y_1 = -y_0' \quad y_1(0) = 0 \quad y_1'(0) = 0$$

Solving

$$y(t, \varepsilon) = \sin t - \frac{1}{2} \varepsilon t \sin t + O(\varepsilon^2)$$

Though $y - y_0 - \varepsilon y_1 = O(\varepsilon^2)$ uniformly on $[0, T]$
the approximation is poor for several reasons.

Secularity

An old term from astronomy. Small changes in orbits over long times were referred to as secularities.

$$y(t, \epsilon) = \sin t - \underbrace{\frac{1}{2} \epsilon t \sin t}_{\text{secular and changes order}} + O(\epsilon^2)$$

if $t = O(\frac{1}{\epsilon})$

Qualitative behavior

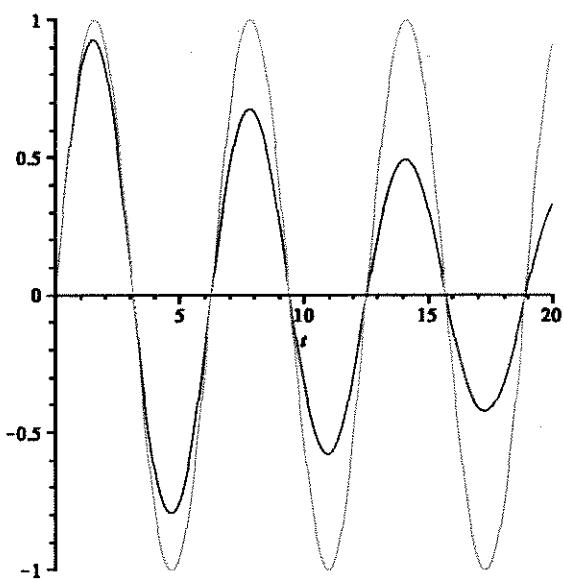
The exact solution decays whereas the two term regular expansion grows as t gets large, i.e. $t \sin t$.

Dissipation

Original problem is dissipative whereas the leading regular problem is conservative.

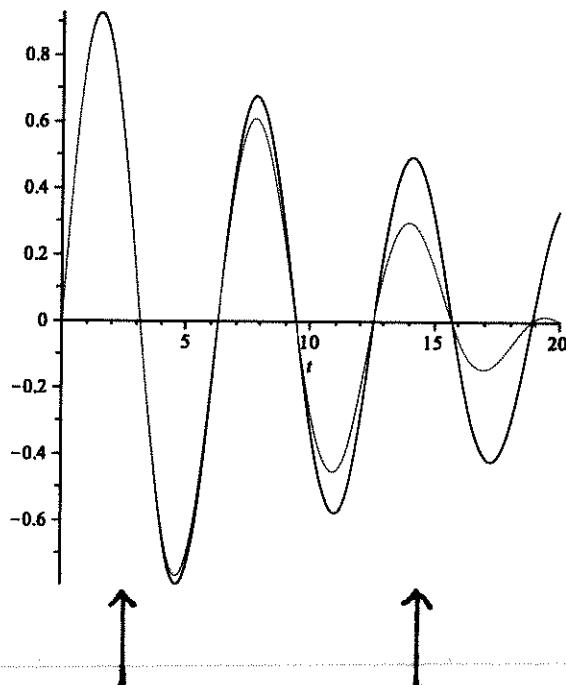
Amplitude Phase

Approximation $y_0 + \epsilon y_1$, does a bad job capturing slowly varying phase.



$y(t)$ vs $y(t, \epsilon)$

$$\epsilon = 0.1$$



$y_0 + \epsilon y_1$ vs y_H, ϵ

better
here

still not
good here.

Dissipation (detail)

$$(1) \quad y'' + \varepsilon y' + y = 0 \quad y(0) = 0 \quad y'(0) = 1$$

Hamiltonian for unperturbed problem

$$H(y, y') = \frac{1}{2}(y')^2 + \frac{1}{2}y^2$$

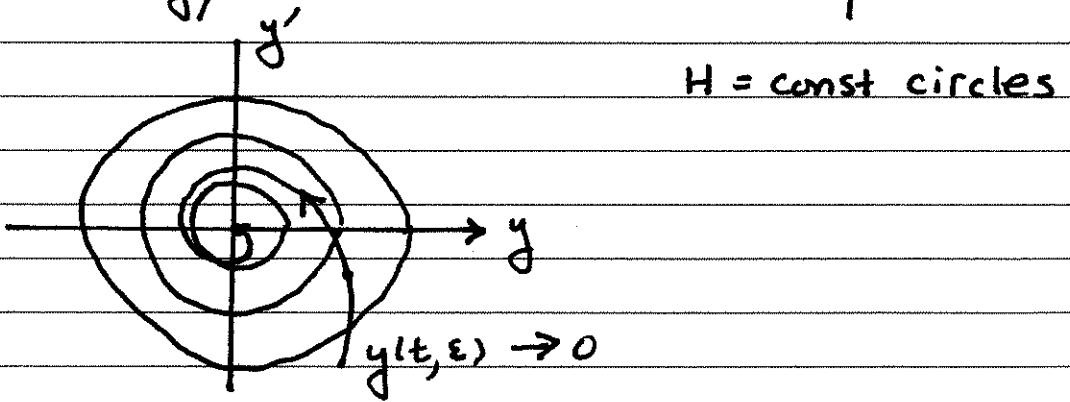
Multiply (1) by y' and integrate using I.Cnd

$$H(y, y') = H(0, 1) - \varepsilon \int_0^t [y'(i)]^2 di$$

Most importantly note that

$$\frac{dH}{dt} = -\varepsilon(y')^2 < 0$$

so that energy H is lost - hence dissipative.



But for $y_0 = \sin t$, $H=0 \Rightarrow$ conservative

Multiple Scales expansion

$$y(t, \varepsilon) = \bar{Y}(t, \tau, \varepsilon) \equiv \frac{1}{\sqrt{1 - \frac{\varepsilon^2}{4}}} e^{-\frac{1}{2}\tau} \sin\left(t\sqrt{1 - \frac{\varepsilon^2}{4}}\right)$$

Expand in ε with both t and $\tau \equiv \varepsilon t$ fixed

$$\bar{Y}(t, \tau, \varepsilon) = \bar{Y}_0(t, \tau) + \varepsilon \bar{Y}_1(t, \tau) + \dots$$

Attached Maple code

$$\bar{Y}_0(t, \tau) = \bar{Y}(t, \tau, 0)$$

and

$$\bar{Y}_k(t, \tau) = \frac{1}{k!} \frac{\partial^k \bar{Y}}{\partial \varepsilon^k}(t, \tau, 0)$$

Here $\bar{Y}_k = 0$ if k odd (code) and

$$\begin{aligned} \bar{Y}_0 &= e^{-\frac{1}{2}\tau} \sin t && \text{secular} \\ \bar{Y}_2 &= \frac{1}{8} e^{-\frac{1}{2}\tau} (\sin t - t \cos t) \end{aligned}$$

so that

$$\bar{Y} = \bar{Y}_0 + \varepsilon \bar{Y}_2 + O(\varepsilon^4) \quad t = O(\frac{1}{\varepsilon})$$

Exact solution of IVP:

```
> y:=t->1/sqrt(1-epsilon^2/4)*exp(-epsilon*t/2)*sin(t*sqrt(1-
epsilon^2/4));
```

$$y := t \mapsto \frac{e^{-\frac{1}{2} \epsilon t} \sin\left(t \sqrt{1 - \frac{1}{4} \epsilon^2}\right)}{\sqrt{1 - \frac{1}{4} \epsilon^2}} \quad (1)$$

Re-express the exact solution as an exact TWO-TIME representation: $\tau = \epsilon t$

```
> Y:=(t,tau)->1/sqrt(1-epsilon^2/4)*exp(-tau/2)*sin(t*sqrt(1-
epsilon^2/4)):Y(t,tau);
```

$$\frac{2 e^{-\frac{1}{2} \tau} \sin\left(\frac{1}{2} t \sqrt{4 - \epsilon^2}\right)}{\sqrt{4 - \epsilon^2}} \quad (2)$$

Fixing t and tau we expand in ϵ :

$$Y(t, \tau, \epsilon) = Y_0(t, \tau) + \epsilon Y_1(t, \tau) + \epsilon^2 Y_2(t, \tau) + \epsilon^3 Y_3(t, \tau) + O(\epsilon^4)$$

then find $Y_k(t, \tau)$.

```
> YM[0]:=simplify(subs(epsilon=0,Y(t,tau))):  
> for k from 1 by 1 to 3 do YM[k]:=simplify(subs(epsilon=0,diff(Y  
(t,tau),epsilon$k))/k) od:
```

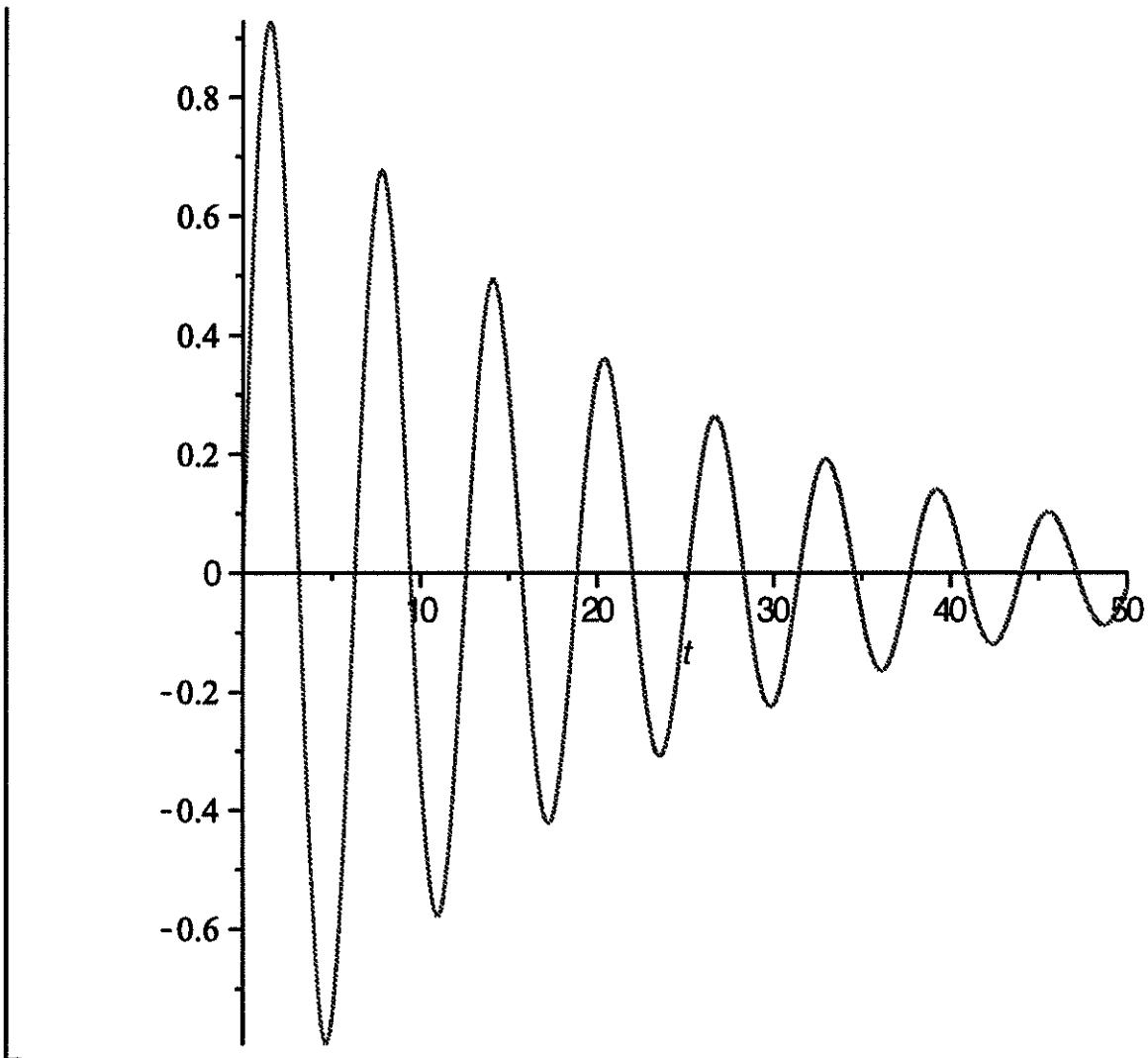
```
> for i from 0 to 3 do YM[i] od;
```

$$\begin{aligned} & e^{-\frac{1}{2} \tau} \sin(t) \\ & 0 \\ & \frac{1}{8} e^{-\frac{1}{2} \tau} (\sin(t) - \cos(t) t) \\ & 0 \end{aligned} \quad (3)$$

```
> P:=ep->plot([subs(epsilon=ep,y(t)),subs(epsilon=ep,subs(tau=-
epsilon*t,YM[0]))],t=0..50,color=[blue,red]);
```

```
P := ep->plot([subs(epsilon=ep,y(t)),subs(epsilon=ep,subs(tau=epsilon*t,YM[0]))],t=0..50,color=[blue,
red])
```

```
> P(0..1);
```



Multiple scales and strained coordinates

A strained coordinate $\tau(t, \varepsilon)$ such as

$$\tau = t$$

no straining

$$\tau = \varepsilon t$$

scaling

$$\tau = \varepsilon^2 t$$

scaling

$$\tau = (1 + \omega_1 \varepsilon + \varepsilon^2 \omega_2 + \dots) t$$

Hindstedt straining

$$\frac{d\tau}{dt} = \omega(\tilde{t}) \quad \tilde{t} = \varepsilon t$$

Straining via
differential eqns.

In a multiple scales expansion one assumes

$$(1) \quad y(t, \varepsilon) = \bar{Y}(\tau_1, \dots, \tau_K, \varepsilon)$$

and

$$(2) \quad \bar{Y} \sim \bar{Y}_0(\tau_1, \dots, \tau_K) + \nu(\varepsilon) \bar{Y}_1(\tau_1, \dots, \tau_K) + o(\nu)$$

Expansions in (2) must be consistent.
That is to say:

For all $\tau_K = O(1)$, the term $\nu_1 \bar{Y}_1 = O(\nu_1)$
when rewritten in terms of t .

EXAMPLES OF INCONSISTENT TERMS

$$y(t, \varepsilon) = \overline{I}_0(\tau, \tilde{t}) + \underbrace{\varepsilon \overline{I}_1(\tau, \tilde{t})}_{\text{+ } O(\varepsilon^2)}$$

terms in here that are $O(1)$
upon renaming are
inconsistent.

EXAMPLE $\tau = t, \tilde{t} = \varepsilon t$

$$y = \sin \tau + \underbrace{\varepsilon \tau \sin \tau}_{O(\varepsilon^2)} + O(\varepsilon^2)$$

$$y = (1 + \tilde{t}) \sin \tau + O(\varepsilon^2)$$

EXAMPLE $\tau = t, \tilde{t} = \varepsilon t$

$$y = \underbrace{\varepsilon \tau^2 \sin(\tilde{t})}_{O(\varepsilon^2)} + O(\varepsilon^2)$$

$$y = \tau \tilde{t} \sin(\tilde{t}) + O(\varepsilon^2)$$

EXAMPLE of a consistent term

$$\tau = \varepsilon \underbrace{\frac{\tau}{\tau^2 + 1}}_{\text{Bounded (uniformly)}} \sin \tau$$

Bounded (uniformly)
for $\tau \in \mathbb{R}$.

Weakly nonlinear problems

$$(1) \quad y'' + y = \varepsilon f(y, y')$$

$$(2) \quad y(0) = a \quad y'(0) = b$$

Since (1) is linear if $\varepsilon = 0$ but nonlinear otherwise, the problem is said to be weakly nonlinear

$$\tau_1 = t \quad \tau_2 = \varepsilon t$$

are fast and slow strained times. Let

$$y(t, \varepsilon) = Y(\tau_1, \tau_2, \varepsilon) = Y_0(\tau_1, \tau_2) + \varepsilon Y_1(\tau_1, \tau_2) + O(\varepsilon^2)$$

To use this multiple time scale in (1)-(2)
we must convert (1)' into partials
involving τ_1, τ_2

$$(3) \quad \frac{d}{dt} Y = \frac{\partial Y}{\partial \tau_1} + \varepsilon \frac{\partial Y}{\partial \tau_2}$$

$$(4) \quad \frac{d^2}{dt^2} Y = \frac{\partial^2 Y}{\partial \tau_1^2} + 2\varepsilon \frac{\partial^2 Y}{\partial \tau_1 \partial \tau_2} + \varepsilon^2 \frac{\partial^2 Y}{\partial \tau_2^2}$$

These must also to derive I. Cond.
for $Y_K(\tau_1, \tau_2)$

Generally

$$(5) \quad y(0, \varepsilon) = a = \bar{Y}_0(0, 0) + \varepsilon \bar{Y}_1(0, 0) + O(\varepsilon^2)$$

$$(6) \quad y'(0, \varepsilon) = b = \frac{\partial \bar{Y}_0}{\partial \tau_1}(0, 0) + \varepsilon \left(\frac{\partial \bar{Y}_1}{\partial \tau_1}(0, 0) + \frac{\partial \bar{Y}_0}{\partial \tau_2}(0, 0) \right) + O(\varepsilon^2)$$

Note the I.C. for \bar{Y}_i depend on \bar{Y}_0 !
Also

$$(7) \quad f(y, y') = f\left(\bar{Y}_0, \frac{\partial \bar{Y}_0}{\partial \tau_1}\right) + O(\varepsilon)$$

Next we define the operator

$$(8) \quad L(\bar{Y}) \equiv \frac{\partial^2 \bar{Y}}{\partial \tau_1^2} + \bar{Y}$$

Collectively (1)-(8) yield an $O(1)$ and $O(\varepsilon)$ problem.

$$L(\bar{Y}_0) = 0$$

$$L(\bar{Y}_1) = f\left(\bar{Y}_0, \frac{\partial \bar{Y}_0}{\partial \tau_1}\right) - 2 \frac{\partial^2 \bar{Y}_0}{\partial \tau_1 \partial \tau_2}$$

with I.C. conditions

$$\bar{Y}_0(0, 0) = a \quad \frac{\partial \bar{Y}_0}{\partial \tau_1}(0, 0) = b$$

$$\bar{Y}_1(0, 0) = 0 \quad \frac{\partial \bar{Y}_1}{\partial \tau_1}(0, 0) = -\frac{\partial \bar{Y}_0}{\partial \tau_2}(0, 0)$$

The general amplitude-phase solution
of O(1) problem

$$Y_0(\tau_1, \tau_2) = A(\tau_2) \cos(\tau_1 - \phi(\tau_2))$$

Initial conditions imply

$$A(0) \cos \phi(0) = a$$

$$A(0) \sin \phi(0) = b$$

From which we deduce

$$A(0) = \sqrt{a^2 + b^2} \quad \phi(0) = \arctan\left(\frac{b}{a}\right)$$

At this stage we still don't know $A(\tau_2)$, $\phi(\tau_2)$.

We require the expansion

$$Y \sim Y_0(\tau_1, \tau_2) + \varepsilon Y_1(\tau_1, \tau_2) + O(\varepsilon^2)$$

to be consistent for $0 \leq \tau_2 = O(1)$ or
for $0 \leq \varepsilon t \leq T$ with T fixed.

One way to assure this is to require
 Y_k be periodic in τ_1 and hence
uniformly bounded.

Defining

$$F_1(\tau_1, \tau_2) \equiv f(Y_0, \frac{\partial Y_0}{\partial \tau_1}) - 2 \frac{\partial^2 Y_0}{\partial \tau_1 \partial \tau_2}$$

Fredholm Alternative - periodic case

$$L[u] \equiv u'' + a(t)u' + b(t)u$$

$$L^*[v] \equiv v'' - (a(t)v)' + b(t)v$$

The problem $L[u] = f(t)$ has T -periodic solutions only if

$$\langle v, f \rangle \equiv \int_0^T v(t)f(t)dt = 0 \quad \forall v \in N(L^*)$$

Necessary conditions for $A(\tau_1)$ and $\phi(\tau_2)$

Given the F.A.T. above, \mathbf{I}_1 is 2π -periodic in \mathbf{I}_1 only if

$$(a) \int_0^{2\pi} F(\tau_1, \tau_2) \cos \tau_1 d\tau_1 = 0$$

$$(b) \int_0^{2\pi} F(\tau_1, \tau_2) \sin \tau_1 d\tau_1 = 0$$

Given how F is defined, these represent a coupled set of (nonlinear) differential equations for A, ϕ . Solving these with known I.C. completes to leading solution \mathbf{I}_0 .

EXAMPLE

$$y'' + y = -\varepsilon y^3 \quad y(0) = 0 \quad y'(0) = v > 0$$

Let $\tau_1 = t$, $\tau_2 = \varepsilon t$ and

$$y(t, \varepsilon) = Y_0(\tau_1, \tau_2) + \varepsilon Y_1(\tau_1, \tau_2) + O(\varepsilon^2)$$

The $O(1)$ and $O(\varepsilon)$ problems are

$$O(1) \quad \frac{\partial^2 Y_0}{\partial \tau_1^2} + Y_0 = 0$$

$$Y_0(0, 0) = 0 \quad \frac{\partial Y_0}{\partial \tau_1}(0, 0) = v$$

$$O(\varepsilon) \quad \frac{\partial^2 Y_1}{\partial \tau_1^2} + Y_1 = -Y_0^3 - 2 \frac{\partial^2 Y_0}{\partial \tau_1 \partial \tau_2}, \quad Y_1(0, 0) = 0 \quad \frac{\partial Y_1}{\partial \tau_1}(0, 0) = -\frac{\partial Y_0}{\partial \tau_2}$$

From the $O(1)$ problem we deduce

$$(3) \quad Y_0(\tau_1, \tau_2) = A(\tau_2) \cos(\tau_1 - \phi(\tau_2)) = A \cos \psi$$

$$(4) \quad A(0) = v$$

$$(5) \quad \phi(0) = \frac{\pi}{2}$$

Compute RHS of $O(\varepsilon)$ equation

$$F_1 = -Y_0^3 - 2 \frac{\partial^2 Y_0}{\partial \tau_1 \partial \tau_2}$$

$$F_1 = -A^3 \cos^3 \psi + 2A' \sin \psi - 2A \phi' \cos \psi$$

where $\psi = \tau_1 - \phi(\tau_2)$.

After some calculations

$$\langle F_1, \sin \psi \rangle = \int_0^{2\pi} F_1 \sin \psi \, d\psi = 2\pi A'$$

$$\langle F_1, \cos \psi \rangle = \int_0^{2\pi} F_1 \cos \psi \, d\psi = -\frac{3}{4}\pi A^3 - 2\pi A \phi'$$

For expansion to be consistent we require

$$(6) \quad A' = 0 \quad A(0) = v$$

$$(7) \quad \frac{3}{4}A^3 + 2A\phi' = 0 \quad \phi(0) = \frac{\pi}{2}$$

whose solution is

$$A(\tau_2) = v$$

$$\phi(\tau_2) = \frac{\pi}{2} - \frac{3}{8}v^2\tau_2$$

Thus, for $t = O(\frac{1}{\epsilon})$

$$y(t, \epsilon) = Y_0(\tau_1, \tau_2) = v \cos(\tau_1 - \frac{\pi}{2} + \frac{3}{8}v^2\tau_2) + O(\epsilon)$$

Stated otherwise

$$y(t, \epsilon) = v \sin((1 + \frac{3}{8}v^2\epsilon)t) + O(\epsilon)$$

Change only in period, not amplitude.

Solvability conditions, consistency

$$y'' + y = \varepsilon f(y, y')$$

$$y(0) = a \quad y'(0) = b$$

Multiple scales expansion

$$(1) \quad y(t, \varepsilon) = \mathbf{Y}(\tau_1, \tau_2, \varepsilon) = \mathbf{Y}_0(\tau_1, \tau_2) + \varepsilon \mathbf{Y}_1(\tau_1, \tau_2) + \dots$$

where $\tau_1 = t$ and $\tau_2 = \varepsilon t$.

$$O(1) \quad L(\mathbf{Y}_0) = 0$$

$$\mathbf{Y}_0(0, 0) = a \quad \frac{\partial^2 \mathbf{Y}_0}{\partial \tau_1 \partial \tau_2}(0, 0) = b$$

$$O(\varepsilon) \quad L(\mathbf{Y}_1) = F_1$$

where

$$F_1 = f(\mathbf{Y}_0, \mathbf{Y}'_0) - 2 \frac{\partial^2 \mathbf{Y}_0}{\partial \tau_1 \partial \tau_2}$$

Leading solution

$$\mathbf{Y}_0 = A(\tau_2) \cos(\tau_1 - \phi(\tau_2))$$

can alternately be written

$$(2) \quad \mathbf{Y}_0 = A_0(\tau_2) \sin \tau_1 + B_0(\tau_2) \cos \tau_1$$

Consistency of expansion assured if

- i) \mathbf{Y}_1 bounded in τ_1 ,
- ii) \mathbf{Y}_1 periodic in τ_1 ,

Some authors assure consistency by

- a) removing secular terms
- b) applying Fred. Alternative

EXAMPLE $f_1(y) = y$

Using (2) in O(E) problem

$$L(\bar{Y}_1) = \underbrace{(A_0 + 2B'_0)}_{S_1} \sin \tau_1 + \underbrace{(B_0 - 2A'_0)}_{S_2} \cos \tau_1,$$

each indicated term generates secularities

$$\bar{Y}_1 = A_1 \sin \tau_1 + B_1 \cos \tau_1 + \underbrace{2S_1 \tau_1 \sin \tau_1}_{\text{secular}} + \underbrace{2S_2 \tau_1 \cos \tau_1}_{\text{secular}},$$

Thus one must choose

$$A_0 + 2B'_0 = 0 \quad B_0 - 2A'_0 = 0$$

Alternately these are the $k=1$ Fourier coefficients of F_1 ,

$$F_1 = \frac{a_0}{2} + \sum_{k=1}^{\infty} (a_k \cos k\tau_1 + b_k \sin k\tau_1)$$

To eliminate those modes is

$$\int_0^{2\pi} F_1 \cos \tau_1 d\tau_1 = \int_0^{2\pi} F_1 \sin \tau_1 d\tau_1 = 0$$

which is the Fredholm alternative!

EXAMPLE (with dissipation)

$$y'' + y = -\varepsilon (y')^3$$

$$y(0) = 1 \quad y'(0) = 0$$

Let $\tau = t$, $\tilde{t} = \varepsilon t$ and

$$(1) \quad y(t, \varepsilon) = \Sigma(\tau, \tilde{t}, \varepsilon) = \Sigma_0(\tau, \tilde{t}) + \varepsilon \Sigma_1(\tau, \tilde{t}) + \dots$$

Define the operator

$$L(\Sigma) = \frac{\partial^2 \Sigma}{\partial \tau^2} + \Sigma$$

Derivative conversions

$$\frac{d}{dt} \Sigma = \frac{\partial \Sigma}{\partial \tau} + \varepsilon \frac{\partial \Sigma}{\partial \tilde{t}}$$

$$\frac{d^2}{dt^2} \Sigma = \frac{\partial^2 \Sigma}{\partial \tau^2} + 2\varepsilon \frac{\partial^2 \Sigma}{\partial \tau \partial \tilde{t}} + \varepsilon^2 \frac{\partial^2 \Sigma}{\partial \tilde{t}^2}$$

Use these and (1) we arrive at

$$O(1) \quad L(\Sigma_0) = 0$$

$$O(\varepsilon) \quad L(\Sigma_1) = F_1$$

$$O(\varepsilon^2) \quad L(\Sigma_2) = F_2$$

where,

$$F_1 = -2 \frac{\partial^2 Y_o}{\partial \tau \partial \tilde{\tau}} - \left(\frac{\partial Y_o}{\partial \tau} \right)^3$$

$$F_2 = -2 \frac{\partial^2 Y_o}{\partial \tau \partial \tilde{\tau}} - \frac{\partial^2 Y_o}{\partial \tilde{\tau}^2} - 3 \left(\frac{\partial Y_o}{\partial \tau} \right)^2 \frac{\partial Y_o}{\partial \tilde{\tau}} - 3 \left(\frac{\partial Y_o}{\partial \tilde{\tau}} \right)^2 \frac{\partial Y_o}{\partial \tau}$$

O(1) Problem

$$Y_o(\tau, \tilde{\tau}) = A_o(\tilde{\tau}) \cos(\tau + \phi_o(\tilde{\tau}))$$

is amplitude-phase form. Initial conditions

$$Y_o(0, 0) = A_o(0) \cos \phi_o(0) = 1$$

$$\frac{\partial Y_o}{\partial \tau}(0, 0) = -A_o(0) \sin \phi_o(0) = 0$$

from which we conclude

$$A_o(0) = 1 \quad \phi_o(0) = 0$$

At this stage we do not know $A_o(\tilde{\tau})$ and $\phi_o(\tilde{\tau})$

$$Y_o(\tau, \tilde{\tau}) = A_o(\tilde{\tau}) \cos \psi$$

where $\psi = \tau + \phi_o(\tilde{\tau})$

O(ε) problem determines A_0, ϕ_0

$$L(\bar{Y}_1) = 2A'_0 \sin \psi + 2A_0 \phi'_0 \cos \psi + A_0^3 \sin^3 \psi = F_1$$

To eliminate inconsistent terms in \bar{Y}_1 , we require it to be periodic in T .
Fredholm alternative

$$\langle F_1, \sin \psi \rangle = 0 \quad A'_0 + \frac{3}{8} A_0^3 = 0$$

$$\langle F_1, \cos \psi \rangle = 0 \quad 2A_0 \phi'_0 = 0$$

Solving the ODE system for (A_0, ϕ_0) with derived initial conditions

$$A_0(\tilde{t}) = \sqrt{\frac{2}{3\tilde{t} + 4}} \quad \phi_0(\tilde{t}) = 0$$

and

$$(2) \quad \bar{Y}_0(T, \tilde{t}) = \sqrt{\frac{2}{3\tilde{t} + 4}} \cos T$$

Simplify O(ε) problem

Using $\sin^3 x = \frac{3}{4} \sin x - \frac{1}{4} \sin 3x$ in F_1 and (2) we get

$$F_1 = -\frac{2 \sin(3\psi)}{(3t + 4)^{3/2}}$$

Note absence of $\sin \psi, \cos \psi$ Fourier components.

Solving for $\Sigma_1(\tau, \tilde{t})$:

$$(3) \quad \Sigma_1 = \underbrace{A_1(\tilde{t}) \cos(\tau + \phi_1(\tilde{t}))}_{\text{amplitude phase part}} + \frac{\sin 3\tau}{4(3\tilde{t} + 4)^{3/2}}$$

Notice Σ_1 is bounded and periodic in τ .
More over¹ $\Sigma_1 = O(1)$ for $\tilde{t} = O(1)$, i.e.
long times.

$O(\varepsilon^2)$ outline

$$\psi \equiv \tau + \phi_1$$

$$(4) \quad L(\Sigma_2) = F_2(\Sigma_0, \Sigma_1)$$

where we suppress arguments involving
the derivatives of Σ_k .

Knowing Σ_0 completely and using (3) in
(4) the resulting consistency conditions

$$\langle F_2, \sin \psi \rangle = 0$$

$$\langle F_2, \cos \psi \rangle = 0$$

yield coupled ODE's for A_1 and ϕ_1 .
Using initial cond. to complete Σ_1 ,

$$\Sigma = \Sigma_0(\tau, \tilde{t}) + \varepsilon \Sigma_1(\tau, \tilde{t}) + O(\varepsilon^2)$$

for $\tilde{t} = O(1)$ or $t = O(\frac{1}{\varepsilon})$.

Multiple Scales Linear Straining

$$(1) \quad y'' + y = \varepsilon f(y, y') \quad y(0) = A \quad y'(0) = B$$

Seek expansion

$$y \sim \sum_{n=0}^{\infty} \mathbf{Y}_n(\tau, \tilde{\tau})$$

$$\tau = \sum_{n=0}^{\infty} w_n \varepsilon^n \quad w_0 = 1 \quad (\text{linear strain})$$

$$\tilde{\tau} = \varepsilon t$$

slow time

The slight generalization in τ embodies Linsteadt's method for finding periodic orbits. Then $\tilde{\tau}$ is absent.

$$\frac{dy}{dt} = \frac{\partial \mathbf{Y}_0}{\partial \tau} + \varepsilon \left(\frac{\partial \mathbf{Y}_1}{\partial \tau} + \frac{\partial \mathbf{Y}_0}{\partial \tilde{\tau}} + w_1 \frac{\partial \mathbf{Y}_1}{\partial \tau} \right) + O(\varepsilon^2)$$

Solution of O(1) problem

$$L(\mathbf{Y}_0) = 0 \quad \mathbf{Y}_0(0, 0) = A, \quad \frac{\partial \mathbf{Y}_0}{\partial \tau}(0, 0) = B$$

is

$$\mathbf{Y}_0 = A_0(\tilde{\tau}) \cos \psi \quad \psi \equiv \tau - \phi_0(\tilde{\tau})$$

where $A_0(0)$ and $\phi_0(0)$ are known.

Inconsistent terms to $O(\epsilon)$

$$y'' = \ddot{Y}_{0\tau\tau} + \epsilon (\ddot{Y}_{1\tau\tau} + 2\omega_1 \dot{Y}_{0\tau\tau} + 2\ddot{Y}_{0\tau\tilde{\tau}}) + O(\epsilon^2)$$

The $O(\epsilon)$ equation is

$$L(Y_1) = F_1 = -2\omega_1 \ddot{Y}_{0\tau\tau} - 2\ddot{Y}_{0\tau\tilde{\tau}} + f^{(0)}$$

Given soln $\ddot{Y}_0 = A_0 \cos \psi$ one finds

$$F_1(\psi, \tilde{\tau}) = 2A'_0 \sin \psi - 2A_0(\phi'_0 - \omega_1) \cos \psi + f^{(0)}$$

Fourier expand $f^{(0)}$ to remove first harmonics.

$$\underset{\uparrow}{P_1(A_0)} = \langle f^{(0)}, \sin \psi \rangle \equiv \frac{1}{2\pi} \int_0^{2\pi} f(A_0 \cos \psi, -A_0 \sin \psi) \sin \psi d\psi$$

$$\underset{\uparrow}{Q_1(A_0)} = \langle f^{(0)}, \cos \psi \rangle$$

Hence

$$f^{(0)} = \hat{f}^{(0)} + 2P_1 \sin \psi + 2Q_1 \cos \psi$$

\uparrow
doesn't contribute
to inconsistent
terms.

Then F_1 may be written

$$F_1 = 2 \underbrace{(A'_0 + P_1)}_0 \sin \varphi + 2 \underbrace{(-A_0 \dot{\varphi}' + A_0 \omega_1 + Q_1)}_0 \cos \varphi + \hat{f}^{(o)}$$

Results in ODE's

$$\frac{dA_0}{dt} = -P_1(A_0)$$

$$A_0 \left(\frac{d\varphi}{dt} - \omega_1 \right) = Q_1(A_0)$$

Solution for amplitude given implicitly by

$$\tilde{t} = - \int_{A_0(0)}^{A_0(\tilde{t})} \frac{ds}{P_1(s)}$$

Inverted to find $A_0(\tilde{t})$ one then gets

$$\phi(\tilde{t}) = \phi(0) + \omega_1 \tilde{t} + \int_0^{\tilde{t}} \frac{Q_1(A_0(s))}{A_0(s)} ds$$

Remarks (see Kevorkian 95)

i) $\omega_1 = 0$ wlog

ii) General expressions to $O(\epsilon^2)$ possible
but $\omega_2 \neq 0$

Fixed Period Straining $\tilde{t} = \varepsilon t$ slow time

$$y'' + \omega^2(\tilde{t}) y = \varepsilon f(y, y', \tilde{t})$$

$$y(0) = A \quad y'(0) = B$$

Multiple scales

$$y(t, \varepsilon) = \mathfrak{Y}(\tau, \tilde{t}, \varepsilon) = \mathfrak{Y}_0(\tau, \tilde{t}) + \varepsilon \mathfrak{Y}_1(\tau, \tilde{t}) + \dots$$

where

$$\frac{d\tau}{dt} = \omega(\tilde{t}) \quad \tau = \int_0^t \omega(\varepsilon y) dy$$

is a strained fast time.

Derivative Conversions, etc

$$y' = \omega \frac{\partial \mathfrak{Y}}{\partial \varepsilon} + \varepsilon \frac{\partial \mathfrak{Y}}{\partial \tilde{t}}$$

$$y'' = \omega^2 \frac{\partial^2 \mathfrak{Y}}{\partial \varepsilon^2} + 2\varepsilon \omega \frac{\partial^2 \mathfrak{Y}}{\partial \varepsilon \partial \tilde{t}} + \varepsilon \omega' \frac{\partial \mathfrak{Y}}{\partial \varepsilon} + \varepsilon^2 \frac{\partial^2 \mathfrak{Y}}{\partial \tilde{t}^2}$$

$$f = f(\mathfrak{Y}_0, \omega \frac{\partial \mathfrak{Y}_0}{\partial \varepsilon}, \tilde{t}) + O(\varepsilon) \equiv f^{(0)} + O(\varepsilon)$$

Initial Conditions

$$\mathfrak{Y}_0(0, 0) = A \quad \frac{\partial \mathfrak{Y}_0}{\partial \varepsilon}(0, 0) = \frac{B}{\omega(0)}$$

$$\mathfrak{Y}_1(0, 0) = 0 \quad \frac{\partial \mathfrak{Y}_1}{\partial \varepsilon}(0, 0) = \frac{1}{\omega(0)} \frac{\partial \mathfrak{Y}_0}{\partial \tilde{t}}(0, 0)$$

O(1) and O(ϵ) problems

$$L(\ddot{\gamma}_0) = \frac{\partial^2 \ddot{\gamma}_0}{\partial t^2} + \ddot{\gamma}_0 = 0$$

has same form

$$\ddot{\gamma}_0 = A_0(\tilde{t}) \cos \psi \quad \psi = t - \phi(\tilde{t})$$

O(ϵ) problem more complex

$$L(\ddot{\gamma}_1) = -\frac{2}{\omega} \frac{\partial^2 \ddot{\gamma}_0}{\partial t \partial \tilde{t}} - \frac{\omega'}{\omega^2} \frac{\partial \ddot{\gamma}_0}{\partial \tilde{t}} + \frac{1}{\omega^2} f^{(0)} = F_1$$

As before $\langle F_1, \sin \psi \rangle = \langle F_1, \cos \psi \rangle$ assures consistency.

PENDULUM EQN: $\omega^2 \propto \frac{1}{L}$ where $L = \text{length.}$

EXAMPLE

$$y'' + \omega^2(t) y = 0 \quad y(0) = A \quad y'(0) = B$$

O(1) PROBLEM $L[\ddot{\gamma}_0] = 0 \quad \dot{\gamma}_0(0,0) = A \quad \frac{\partial \ddot{\gamma}_0}{\partial \tau}(0,0) = \frac{B}{\omega(0)}$

$$\ddot{\gamma}_0(\tau, \tilde{t}) = A_0(\tilde{t}) \cos \psi \quad \psi = \tau - \phi_0(\tilde{t})$$

$$A_0(0) = \sqrt{A^2 + \frac{B^2}{\omega(0)^2}}$$

$$\phi_0(0) = \arctan\left(\frac{B}{A\omega(0)}\right)$$

O(2) PROBLEM Straining alone induces inconsistencies

$$L[\ddot{\gamma}_1] = \frac{1}{\omega^2} (2A'_0 \omega + \omega' A_0) \sin \psi - \frac{2A_0}{\omega} \dot{\gamma}'_0 \cos \psi$$

Removal of secular terms (inconsist.)

$$\phi'_0 = 0$$

$$\phi_0(\tilde{t}) = \phi_0(0)$$

$$2A'_0 \omega + \omega' A_0 = 0$$

$$A_0(\tilde{t}) = A_0(0) \sqrt{\frac{\omega(0)}{\omega(\tilde{t})}}$$

Thus for $\omega(\tilde{t}) = 1 + \tilde{t}$ linear \uparrow in frequency

$$\tau = \int_0^t \omega(\epsilon \eta) d\eta = t + \frac{1}{2} \epsilon t^2$$

$$\ddot{\gamma}_0(\tau, \tilde{t}) = A_0(\tilde{t}) \cos(\tau - \phi_0(0))$$

$$\ddot{\gamma}_0(\tau, \tilde{t}) = A_0(0) \frac{1}{\sqrt{1+\epsilon t}} \cos(t + \frac{1}{2} \epsilon t^2 - \phi_0(0))$$

EXAMPLE

$$y'' + \omega^2(\varepsilon t) y = -\varepsilon y' \quad \omega(s) = 1+s$$

$$y(0) = a \quad y'(0) = b$$

Solving with maple code

$$A(T_2) = \frac{Ab}{\sqrt{T_2+1}} e^{\frac{1}{2}T_2}$$

$$\phi(T_2) = \phi(0)$$

Giving the solution

$$y(t, \varepsilon) \sim \frac{A(0)e^{\frac{1}{2}\varepsilon t}}{\sqrt{1+\varepsilon t}} \cos\left(t + \frac{\varepsilon t^2}{2} - \phi(0)\right)$$

The strained time

$$T_2 = \int_0^t (1+s) ds = t + \frac{\varepsilon t^2}{2}$$

EXAMPLE

$$y'' + \omega^2(\epsilon t) y = -\epsilon(y')^3$$

$$\omega > 0$$

$$y(0) = a$$

$$y'(0) = b$$

O(1) Problem

$$\bar{Y}_0(\tau_1, \tau_2) = A(\tau_2) \cos \psi \quad \psi = \tau_1 - \phi(\tau_2)$$

$$A(0) = \pm \left(a^2 + \frac{b^2}{\omega(0)^2} \right)^{1/2}$$

$$\bar{Y}_0(0, 0) = a$$

$$\phi(0) = \arctan \left(\frac{b}{a\omega(0)} \right)$$

$$\frac{\partial \bar{Y}_0}{\partial \tau_1}(0, 0) = \frac{b}{\omega(0)}$$

O(2) Problem

$$L[\bar{Y}_0] = F_1[\bar{Y}_0] = -\frac{2}{\omega} \frac{\partial^2 \bar{Y}_0}{\partial \tau_1 \partial \tau_2} - \frac{\omega'}{\omega^2} \frac{\partial \bar{Y}_0}{\partial \tau_1} - \frac{1}{\omega^2} \left(\omega \frac{\partial \bar{Y}_0}{\partial \tau_1} \right)^3$$

Fourier expand F_1 in $\psi = \tau_1 - \phi(\tau_2)$ slowly varying phase.

$$\Phi_1 = \int_0^{2\pi} F_1 \sin \psi d\psi = \frac{\pi}{4\omega^2} \left\{ 8A' \omega + 4\omega' A - 3\omega^3 A^3 \right\} = 0$$

$$\Phi_2 = \int_0^{2\pi} F_1 \cos \psi d\psi = -\frac{2\pi}{\omega} A \phi' = 0$$

Thus $\phi(\tau_2) = \phi(0)$. Integrating Φ_1 , equation gives

$$A(\tau_2) = \pm \sqrt{\frac{\omega(\tau_2)^{1/2}}{\frac{1}{\omega(0) A(0)^2} - \frac{3}{4} \int_0^{\tau_2} \omega(s) ds}}$$

Completing soln for \bar{Y}_0 .

Addendum Solution to $\ddot{\theta} = 0$ differential equation

$$2A'\omega + \omega'A - \frac{3}{4}\omega^3 A^3 = 0$$

$$(\omega A^2)' - \frac{3}{4}\omega^3 A^4 = 0$$

$$u' - \frac{3}{4}\omega u^2 = 0 \quad u \equiv \omega A^2$$

$$\frac{du}{dt_2} = \frac{3\omega u^2}{4}$$

$$\int_0^{t_2} \frac{du}{u^2} = \int_0^{t_2} \frac{3\omega}{4} dt_2$$

$$\frac{1}{u} = \left(\frac{1}{\omega_0 A_0} - \int_0^{t_2} \frac{3\omega(s)}{4} ds \right) \quad \omega_0 \equiv \omega(0), A_0 \equiv A(0)$$

Solving yields

$$A(t_2) = \sqrt{\frac{\omega(t_2)^{-1}}{\frac{1}{\omega_0^2 A_0^2} - \int_0^{t_2} \frac{3\omega(s)}{4} ds}}$$

Multiple Scales BVP

$$(1) \quad \varepsilon y'' + 2y' + 2y = 0 \quad y(0) = 0 \quad y(1) = 1$$

Expect Blayer of $O(\varepsilon)$ thickness

$$x_1 = \frac{x}{\varepsilon} \quad x_2 = x$$

are two space scales.

$$y = \bar{Y}(x_1, x_2, \varepsilon) \sim \bar{Y}_0(x_1, x_2) + \varepsilon \bar{Y}_1(x_1, x_2) + \dots$$

Derivative conversion

$$y' = \frac{1}{\varepsilon} \bar{Y}_{x_1} + \bar{Y}_{x_2} = \frac{1}{\varepsilon} \bar{Y}_{0x_1} + (\bar{Y}_{1x_1} + \bar{Y}_{0x_2}) + O(\varepsilon)$$

$$\varepsilon y'' = \frac{1}{\varepsilon} \bar{Y}_{x_1 x_1} + 2 \bar{Y}_{x_1 x_2} + \varepsilon \bar{Y}_{x_2 x_2} = \frac{1}{\varepsilon} \bar{Y}_{0x_1 x_1} + (\bar{Y}_{1x_1 x_1} + 2 \bar{Y}_{0x_2 x_2}) + O(\varepsilon)$$

Leading and $O(\varepsilon)$ problem

$$O(1) \quad \frac{\partial^2 \bar{Y}_0}{\partial x_1^2} + 2 \frac{\partial \bar{Y}_0}{\partial x_1} = 0$$

$$O(\varepsilon) \quad \frac{\partial^2 \bar{Y}_1}{\partial x_1^2} + 2 \frac{\partial \bar{Y}_1}{\partial x_1} = -2 \frac{\partial^2 \bar{Y}_0}{\partial x_1 \partial x_2} - 2 \frac{\partial \bar{Y}_0}{\partial x_2} - 2 \bar{Y}_0$$

General soln to $O(1)$ problem

$$\bar{Y}_0(x_1, x_2) = a_0(x_2) + b_0(x_2) e^{-2x_1}$$

General solution of O(ε) problem

$$I_1 = a_1(x_2) + b_1(x_2) e^{-2x_1} - (a'_0 + a_0)x_1 + (b - b'_0)x_1 e^{-2x_1}$$

\downarrow \downarrow
 $\frac{x}{\epsilon}$ $\frac{x}{\epsilon} e^{-2x/\epsilon}$
 $\brace{ }$

inconsistent terms change
order on $[0, 1]$ when reexpressed
in terms of x

Conclude

$$\begin{aligned} a'_0 + a_0 &= 0 & a_0 &= \bar{a}_0 e^{-x_2} \\ b'_0 - b_0 &= 0 & b_0 &= \bar{b}_0 e^{x_2} \end{aligned}$$

and

$$I_0(x_1, x_2) = \bar{a}_0 e^{-x_2} + \bar{b}_0 e^{x_2 - 2x_1}$$

Boundary conditions.

$$I_0(0, 0) = 0 \quad I_0(\frac{1}{\epsilon}, 1) \sim I_0(\infty, 1) = 1$$

Solution

$$I_0(x_1, x_2) = e^{1-x_2} - e^{1+x_2 - 2x_1}$$

$$y(x, \epsilon) \sim e^{1-x} + e^{1+x - \frac{2x}{\epsilon}}$$