

Math 450 (2009) – Homework 7

Due: Wed. January 27, 2010.

NAME: SOLNS

1. [7 pts] Find the extrema of

$$J(y) \equiv \int_0^1 y''(x)^2 + 240 xy(x) dx$$

over the admissible set

$$\mathcal{A} = \{y : y \in C^4[0, 1], y(0) = y(1) = y'(0) = y'(1) = 0\}$$

2. [7 pts] Find the extrema of

$$J(y) \equiv \int_1^e \frac{1}{2} x^2 y'(x)^2 - \frac{1}{8} y(x)^2 dx$$

over

$$\mathcal{A} = \{y : y \in C^2[1, e], y(1) = 1\}$$

Here the Euler-Lagrange equations are of a "Cauchy-Euler" type.

3. [7 pts] Find all the natural boundary conditions associated with extremizing

$$J(y) \equiv \frac{1}{4} y'(0)^4 + \int_0^1 y(x) + \frac{1}{2} y(x)^2 + \frac{1}{3} y''(x)^3 dx$$

over

$$\mathcal{A} = \{y : y \in C^4[0, 1], y(0) = 3, y'(1) = 2\}$$

Do not attempt to solve the Euler-Lagrange equations!

4. [7 pts] Find the extrema of

$$J(y) \equiv \int_0^1 \frac{1}{12} y'(x)^2 dx$$

over

$$\mathcal{A} = \{y \in C^2[0, 1] : y(0) = 0, y(1) = 1\}$$

subject to the constraint

$$K(y) \equiv \int_0^1 xy(x) dx = 1$$

5. [7 pts] A geodesic Γ between points P and Q on surface S is that curve (on S) connecting points P and Q having the shortest length. Great circles are geodesics on spheres (paths airplanes take to minimize distance travelled for instance). In this problem we examine the geodesics on a cone.

In cartesian coordinates the equation of a cone is $x^2 + y^2 = a^2 z^2$ for some constant a . Thus, a parametrization of a curve on the cone is given by

$$\mathbf{X}(t) = (x(t), y(t), z(t))$$

$$\mathbf{X}(t) = (r(t) \cos \theta(t), r(t) \sin \theta(t), a r(t))$$

Without loss of generality we scale t so that $P = \mathbf{X}(0)$ and $Q = \mathbf{X}(1)$. Thus, the length of such a curve is

$$J(\mathbf{X}) = \int_0^1 \|\dot{\mathbf{X}}(t)\| dt = \int_0^1 \sqrt{\dot{x}^2 + \dot{y}^2 + \dot{z}^2} dt$$

where $\dot{(\)}$ means differentiation with respect to t .

a) Show that the Lagrangian L in

$$J(r, \theta) = \int_0^1 \|\dot{\mathbf{X}}(t)\| dt = \int_0^1 L(\theta, \dot{\theta}, r, \dot{r}) dt$$

is, for $b^2 = a^2 + 1$,

$$L = \sqrt{b^2 \dot{r}^2 + r^2 \dot{\theta}^2}$$

b) Since L depends on two independent functions $r(t)$ and $\theta(t)$ there are two coupled Euler-Lagrange equations defining the geodesics on the cone. Use one of the two Euler-Lagrange equations to show that for some constant k_1

$$\frac{d\theta}{dt} = \frac{k_1 b}{r \sqrt{r^2 - k_1^2}} \frac{dr}{dt}$$

c) Assuming r is a function of θ , use the substitution $r = k_1 \sec u$ to show that

$$r = R(\theta) \equiv k_1 \sec(b^{-1}\theta + k_2)$$

on geodesics for constants k_1, k_2 (determined from endpoint constraints). The geodesic then has the parametrization:

$$\mathbf{X}(\theta) = (R(\theta) \cos \theta, R(\theta) \sin \theta, a R(\theta))$$

QUESTION ONE

$$J(y) = \int_0^1 L(x, y, y', y'') dx$$

where $L = (y'')^2 + 240xy$ is the Lagrangian.
Euler Lagrange Eqns are:

$$L_y - \frac{d}{dx} L_{y'} + \frac{d^2}{dx^2} L_{y''} = 0$$

$$240x + 0 + 2y'''' = 0$$

yields the BVP for $y \in A$.

$$(1) \quad y^{(4)}(x) = -120x$$

$$(2) \quad y(0) = y(1) = y'(0) = y'(1) = 0$$

General solution of (1) is

$$y(x) = C_1 + C_2 x + C_3 x^2 + C_4 x^3 - x^5$$

Boundary conditions yield 4 eqns for C_k as follows

$$y(0) = 0 \quad C_1 = 0$$

$$y(1) = 0 \quad C_1 + C_2 + C_3 + C_4 - 1 = 0$$

$$y'(0) = 0 \quad C_2 = 0$$

$$y'(1) = 0 \quad C_2 + 2C_3 + 3C_4 - 5 = 0$$

Solving for $C_1 = 0, C_2 = 0, C_3 = -2, C_4 = 3 \Rightarrow$

$$\bar{y}(x) = -2x^2 + 3x^3 - x^5$$

QUESTION TWO

$$J(y) = \int_1^e L(x, y, y') dx \quad , \quad L = \frac{1}{2} x^2 y'^2 - \frac{1}{8} y^2$$

Since $y(1) = 1$ is specified, need NBC at $x = e$

$$(1) \quad L_{y'} \Big|_{x=e} = x^2 y'(x) \Big|_{x=e} = e^2 y'(e)$$

must vanish, or

$$(2) \quad y'(e) = 0 \quad (\text{NBC})$$

Euler Lagrange Eqns

$$L_y = \frac{d}{dx} L_{y'}$$
$$-\frac{1}{4} y = \frac{d}{dx} (x^2 y')$$

yields

$$x^2 y'' + 2x y' + \frac{1}{4} y = 0$$

whose general solution is $(y(x) = x^r \Rightarrow r = -\frac{1}{2} \text{ root})$

$$y(x) = \frac{c_1}{\sqrt{x}} + \frac{c_2 \ln x}{\sqrt{x}}$$

Using the boundary conditions

$$y(1) = 1 \quad y'(e) = 0$$

we find $c_1 = c_2 = 1$ or

$$\bar{y}(x) = \frac{1}{\sqrt{x}} + \frac{\ln x}{\sqrt{x}}$$

QUESTION THREE

Here

$$J(y) = \frac{1}{4} y'(0)^4 + \int_0^1 L(x, y, y', y'') dx$$

where

$$(1) \quad L = y + \frac{1}{2} y'^2 + \frac{1}{3} y''^3$$

and

$$A = \{ y \in C^4[0, 1] : y(0) = 3, y'(1) = 2 \}$$

For $\delta y = y(x) + \varepsilon h(x) \in A$ must have

$$(2) \quad h(0) = 0 \quad h'(1) = 0$$

for admissible variations $h(x) \in A^*$.

Compute First variation $\delta J(y, h)$

$$\delta J = y'(0)^3 h'(0) + \int_0^1 (L_y h + \underbrace{L_{y'} h' + L_{y''} h''}_{\text{must integrate by parts}}) dx$$

must integrate by parts

Integrating by parts

$$\delta J = y'(0)^3 h'(0)$$

$$+ L_{y'} h \Big|_0^1 + L_{y''} h' \Big|_0^1 - \left(\frac{d}{dx} L_{y''} \right) h \Big|_0^1$$

$$+ \int_0^1 \underbrace{\left(L_y - \frac{d}{dx} L_{y'} + \frac{d^2}{dx^2} L_{y''} \right)}_{=0 \text{ (EL eqn)}} h(x) dx$$

= 0 (EL eqn)

For extrema, integral term vanishes (EL eqn).
 Also condition (2) implies certain boundary terms vanish, i.e.

$$h(0) = 0 \quad h'(1) = 0$$

but $h(1)$ and $h'(0)$ need not vanish.

First variation simplifies

$$(3) \quad \delta J = \underbrace{(L_{y'} - \frac{d}{dx} L_{y''}) h}_{=0} \Big|_{x=1} + \underbrace{(y'^3 - L_{y''}) h'}_{=0} \Big|_{x=0}$$

Since $L = y + \frac{1}{2}(y')^2 + \frac{1}{3}(y'')^3$ we have

$$L_{y'} = y'$$

$$L_{y''} = (y'')^2$$

$$\frac{d}{dx} L_{y''} = 2y''y'''$$

Using in (3) above

$$(4) \quad L_{y'} - \frac{d}{dx} L_{y''} = y' - 2y''y'''$$

$$(5) \quad y'^3 - L_{y''} = y'^3 - (y'')^2$$

In summary the two NBC are:

$$\begin{array}{l} \downarrow 2 \\ \boxed{\begin{array}{l} y'(1) - 2y''(1)y'''(1) = 0 \\ y'(0)^3 - y''(0)^2 = 0 \end{array}} \end{array}$$

NBC

Euler Lagrange Equations

$$L_y = 1$$

$$L_{y'} = y'$$

$$L_{y''} = (y'')^2$$

yield

$$L_y - \frac{d}{dx} L_{y'} + \frac{d^2}{dx^2} L_{y''} = 0$$

$$1 - y'' + \frac{d^2}{dx^2} (y'')^2 = 0$$

Extrema would be solutions of

$$\frac{d^2}{dx^2} (y'')^2 - y'' + 1 = 0$$

satisfying the given BC.

$$y(0) = 3$$

$$y'(1) = 2$$

and the NBC above.

QUESTION FOUR

$$J(y) = \int_0^1 \frac{1}{12} y'(x)^2 dx$$

$$K(y) = \int_0^1 x y(x) dx = 1$$

Augmented Lagrangian

$$L^*(x, y, y') = \frac{1}{12} y'^2 + \lambda x y$$

Euler Lagrange eqn

$$L_y^* = \frac{d}{dx} L_{y'}^*$$

is

$$y'' = 6\lambda x$$

whose general soln is

$$y(x) = \lambda x^3 + c_1 x + c_2$$

for constants $c_1, c_2 \in \mathbb{R}$.

Boundary Conditions

$$y(0) = c_2 = 0$$

$$y(1) = \lambda + c_1 + c_2 = 1$$

Thus $c_1 = 1 - \lambda$ and $c_2 = 0$.

$$\bar{y}(x) = \lambda x^3 + (1 - \lambda)x$$

satisfies EL eqns and B.C.

Must choose λ so that $K(\bar{y}) = 1$

$$K(\bar{y}) = \int_0^1 x \bar{y}(x) dx$$
$$= \int_0^1 \lambda x^4 + (1-\lambda)x^2 dx$$

$$= \frac{1}{5} \lambda + \frac{1}{3} (1-\lambda)$$

$$= 1$$

only if $\lambda = -5$. Thus the extrema for the isoperimetric problem is

$$\bar{y}(x) = -5x^3 + 6x$$

QUESTION FIVE

a) Finding Lagrangian

$$\dot{x} = \dot{r} \cos \theta - r \dot{\theta} \sin \theta$$

$$\dot{y} = \dot{r} \sin \theta + r \dot{\theta} \cos \theta$$

$$\dot{z} = a \dot{r}$$

Using $\sin^2 \theta + \cos^2 \theta = 1$ then direct algebra yields

$$\dot{x}^2 + \dot{y}^2 + \dot{z}^2 = \dot{r}^2 + r^2 \dot{\theta}^2 + a^2 \dot{r}^2$$

From which

$$L = \|\dot{\mathbf{X}}\| = \sqrt{b^2 \dot{r}^2 + r^2 \dot{\theta}^2} \quad b^2 = 1 + a^2$$

b) The two EL eqns are

$$L_{\theta} = \frac{d}{dt} L_{\dot{\theta}}$$

$$L_r = \frac{d}{dt} L_{\dot{r}}$$

Since L does not depend on θ explicitly, $L_{\theta} = 0$ so that $L_{\dot{\theta}}$ is a first integral,

$$(1) \quad L_{\dot{\theta}} = \frac{r^2 \dot{\theta}}{\sqrt{b^2 \dot{r}^2 + r^2 \dot{\theta}^2}} = k_1$$

for some constant k_1 .

Equation (1) can be solved for $\dot{\theta}$, i.e.

$$r^4 \dot{\theta}^2 = k_1^2 (b^2 \dot{r}^2 + r^2 \dot{\theta}^2)$$

$$(r^4 - k_1^2 r^2) \dot{\theta}^2 = k_1^2 b^2 \dot{r}^2$$

from which

$$(2) \quad \dot{\theta} = \frac{k_1 b}{r \sqrt{r^2 - k_1^2}} \dot{r}$$

(c) If $r = r(\theta)$ then (2) is separable

$$\frac{k_1 dr}{r \sqrt{r^2 - k_1^2}} = \frac{1}{b} d\theta$$

Let

$$r = k_1 \sec u$$

$$dr = k_1 \sec u \tan u$$

$$r^2 - k_1^2 = k_1^2 \tan^2 u$$

simplifies above to

$$du = \frac{1}{b} d\theta$$

$$u = \frac{1}{b} \theta + k_2, \quad k_2 \in \mathbb{R}.$$

$$\sec^{-1}\left(\frac{r}{k_1}\right) = \frac{1}{b} \theta + k_2$$

$$r = k_1 \sec(b^{-1} \theta + k_2)$$