## **Hopf Bifurcations - Summary**

Consider the planar system

$$\frac{dx}{dt} = f(x, y; \mu) \qquad , \tag{1}$$

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$$\frac{dy}{dt} = g(x, y; \mu) ,$$
(1)

where  $\mu$  is a parameter. Alternately, we have the notations:

$$\frac{d\mathbf{x}}{dt} = \mathbf{f}(\mathbf{x}) = \frac{d}{dt} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} f(x,y) \\ g(x,y) \end{pmatrix}$$

Further, let  $\bar{\mathbf{x}}(\mu) = (\bar{x}(\mu), \bar{y}(\mu))$  be the equilibria. The Jacobian of the vector field  $\mathbf{f}(\mathbf{x})$  at  $\bar{\mathbf{x}}$  is

$$\mathbf{Df}(\mathbf{\bar{x}}) = \left[ \begin{array}{cc} f_x(\bar{x}, \bar{y}) & f_y(\bar{x}, \bar{y}) \\ g_x(\bar{x}, \bar{y}) & g_y(\bar{x}, \bar{y}) \end{array} \right]$$

The eigenvalues of  $\mathbf{Df}(\bar{\mathbf{x}})$  are functions of the parameter  $\mu$ . In terms of the trace  $Tr\mathbf{Df}$  and determinant  $det\mathbf{Df}$ , the eigenvalues of the Jacobian are:

$$\lambda_{\pm}(\mu) = \frac{Tr\mathbf{Df} \pm \sqrt{(Tr\mathbf{Df})^2 - 4det\mathbf{Df}}}{2}$$

In this summary we consider the special case where at some parameter value  $\mu = \mu_0$ 

$$Tr\mathbf{Df}(\bar{\mathbf{x}}(\mu_0)) = 0 \tag{3}$$

$$det \mathbf{Df}(\bar{\mathbf{x}}(\mu_0)) > 0 \tag{4}$$

When these two conditions are satisfied, the eigenvalues of the Jacobian are purely imaginary. If, in addition to (3)-(4) being satisfied, the transversality condition

$$\frac{d}{d\mu} \left\{ \mathbb{R}e \left( \lambda_{+}(\mu) \right) \right\} |_{\mu = \mu_{0}} \neq 0 \tag{5}$$

is satisfied, then a *Hopf* bifurcation occurs at the bifurcation point  $(\bar{\mathbf{x}}(\mu_0)), \mu_0$ (here,  $\mathbb{R}e(z)$  is the real part of z). At such a Hopf bifurcation for some  $\mu$ near  $\mu_0$ , small amplitude oscillations (limit cycles) exist. The amplitude of these oscillations approaches zero as  $\mu$  approaches  $\mu_0$ . Though Hopf theory guarantees the existence of such periodic orbits for  $\mu \simeq \mu_0$ , it does not guarantee the existence of the oscillations for  $\mu$  further away from  $\mu_0$ . Often, however, the periodic orbits persist and grow in amplitude as  $|\mu - \mu_0|$  increases.

At  $\mu = \mu_0$  the linearized system (linearization of (1)-(2) about  $\bar{\mathbf{x}}$ )

$$\frac{dz}{dt} = \mathbf{Df}(\bar{\mathbf{x}})z. \quad , \quad z = (z_1, z_2) \in \mathbb{R}^2$$
 (6)

has a center at z=0. Therefore, solutions z(t) have the form

$$z(t) = c_1 \vec{\zeta_1} \cos \omega t + c_2 \vec{\zeta_2} \sin \omega t$$

for some real constants  $c_k$  and constant vectors  $\zeta_k$ , k=1,2. Given the assumed conditions (3)-(4),  $\lambda_{\pm} = \pm \omega i$  where  $i^2 = -1$  and

$$\omega = \sqrt{\det \mathbf{Df}} \tag{7}$$

By Hopf theory, if (3)-(5), are satisfied then for every  $\mu$  with  $|\mu - \mu_0|$  sufficiently small, there exists a T-periodic orbit (limit cycle)  $\mathbf{x}_p(t;\mu)$  which satisfy (1)-(2). The period  $T = T(\mu)$  and Hopf theory also guarantees

$$\lim_{|\mu-\mu_0|\to 0} T(\mu) = \frac{2\pi}{\omega} \tag{8}$$

In other words, for  $\mu$  very nearly equal  $\mu_0$ , the period of the (emergent) periodic orbits of (1)-(2) nearly equals the period of the concentric periodic orbits of the linearized system (6).

If the Jacobian has the very special form:

$$\mathbf{Df}(\mathbf{\bar{x}_0}) = \begin{bmatrix} \mu & -\omega \\ \omega & \mu \end{bmatrix} \quad , \quad \mathbf{\bar{x}_0} = \mathbf{\bar{x}}(\mu_0)$$

then a third-order Taylor Series expansion of (1)-(2) about  $\bar{\mathbf{x}}$  yields a system of the form:

$$\frac{dz_1}{dt} = (d\mu + a(z_1^2 + z_2^2))z_1 - (\omega + c\mu + b(z_1^2 + z_2^2))z_2$$
 (9)

$$\frac{dz_1}{dt} = (d\mu + a(z_1^2 + z_2^2))z_1 - (\omega + c\mu + b(z_1^2 + z_2^2))z_2$$
(9)
$$\frac{dz_1}{dt} = (\omega + c\mu + b(z_1^2 + z_2^2))z_1 + (d\mu + a(z_1^2 + z_2^2))z_2$$
(10)

which when expressed in polar coordinates is

$$\frac{dr}{dt} = (d\mu + ar^2)r \tag{11}$$

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$$\frac{d\theta}{dt} = (\omega + c\mu + br^2)$$
(11)

for constants  $a, b, c, d, \omega, z_1 = r \cos \theta, z_2 = r \sin \theta$ . Note the equation for r(t) is not coupled to the equation for  $\theta$ . Furthermore, depending on the signs of the constants a and d, this third-order system possesses periodic orbits along the locus

$$\mu = -ar^2/d \quad d \neq 0$$

It can be shown that

$$d = \frac{d}{d\mu} \left\{ \mathbb{R}e \left( \lambda_{+}(\mu) \right) \right\} |_{\mu = \mu_{0}}$$

so that the existence of periodic orbits local to the bifurcation point depends on  $d \neq 0$ . This is just the transversality condition (5).

The constant a has a very complicated dependence on the vector field defining the system. In Nonlinear Oscillations, Dynamical Systems and Bifurcations of Vector Fields, J. Guggenheimer, P. Holmes (1983) the stated value is:

$$a = \frac{1}{16} \left[ f_{xxx} + f_{xyy} + g_{xxy} + g_{yyy} \right] + \frac{1}{16\omega} \left[ f_{xy} (f_{xx} + f_{yy}) \right]$$
$$- \frac{1}{16\omega} \left[ g_{xy} (g_{xx} + g_{yy}) + f_{xx} g_{xx} - f_{yy} g_{yy} \right]$$

evaluated at the Hopf point  $(x^*, y^*, \mu^*)$ . Collectively, the signs of a and d determine whether the Hopf bifurcation is Supercritical (stable periodics) or Subcritical (unstable periodics). Recall the locus of periodic orbit (leading-order) radii is given by

$$\mu = -ar^2/d \quad d \neq 0$$

For this reason the branch of periodic orbits are sometimes said to have a quadratic tangency to the fixed points.